### 18.965: Homework 1

Due: Tuesday, September 24

1. (Stereographic projection) Let

$$
S^{n}:=\left\{\left(x_{1}, \ldots, x_{n+1}\right) \in \mathbb{R}^{n+1} \mid x_{1}^{2}+x_{2}^{2}+\cdots+x_{n+1}^{2}=1\right\} \subset \mathbb{R}^{n+1}
$$

be equipped with the subset topology. That is, a set $V \subset S^{n}$ is open if $V=S^{n} \cap U$ for an open set $U \subset \mathbb{R}^{n+1}$. Let $N=(0, \ldots, 0,1)$ be the North pole, and $S=(0, \ldots, 0,-1)$ be the south pole. Define $\pi_{1}: S^{n}-\{N\} \rightarrow \mathbb{R}^{n}$ (resp. $\pi_{2}: S^{n}-\{S\} \rightarrow \mathbb{R}^{n}$ ) so that $\left(\pi_{1}(p), 0\right)$ (resp. $\left.\left(\pi_{2}(p), 0\right)\right)$ is the point where the Line passing through $N$ (resp. $S$ ) and $p$ intersects the hyperplane $\left\{x_{n+1}=0\right\}$.
(a) Prove that $\Phi:=\left\{\left(S^{n}-\{N\}, \pi_{1}\right),\left(S^{n}-\{S\}, \pi_{2}\right)\right\}$ is a $C^{\infty}$ atlas on $S^{n}$.
(b) Prove that $\left(S^{n}, \Phi\right)$ is a smooth submanifold on $\mathbb{R}^{n+1}$. That is, the smooth structure defined by the $\Phi$ coincides with the smooth structure induced on $S^{n}$ as a submanifold of $\mathbb{R}^{n+1}$.
2. Suppose $X$ is a connected topological space. Assume that $X$ is Hausdorff, and locally euclidean of dimension $n$; that is, $X$ can be covered by charts ( $U_{\alpha}, \phi_{\alpha}$ ) such that

$$
\phi_{\alpha}: U_{\alpha} \rightarrow \mathbb{R}^{n}
$$

is a homeomorphism. The following three properties are equivalent
(a) $X$ is second countable. That is, there is a countable collection of open sets $\left\{U_{i}\right\}_{i \in \mathbb{N}}$ such that, for an open set $W$ we can write

$$
W=\bigcup U_{i_{k}}
$$

for some $i_{k}$. For example, $\mathbb{R}^{n}$ is second countable, where the $U_{i}$ can be taken to be open balls centered on rational points, and with rational radii.
(b) $X$ is paracompact.
(c) There exist compact sets $\left\{K_{i}\right\}_{i \in \mathbb{N}}$ such that $K_{i} \subset \operatorname{int}\left(K_{i+1}\right)$ and $X=\cup_{i} K_{i}$. That is, $X$ has a compact exhaustion.

Prove that (b) and (c) are equivalent. Here is a "hint". To prove $(b) \Rightarrow(c)$, cover $X$ by open sets which are preimages, under $\phi_{\alpha}$ of open balls (with compact closure). By paracompactness, you can take a locally finite refinement $\left\{V_{\alpha}\right\}_{\alpha \in A}$ all of which have compact closure. Use these sets to construct $K_{i}$ iteratively. To prove $(c) \Rightarrow(b)$, let $\left\{V_{\alpha}\right\}$ be any open cover. Since $X$ is Hausdorff, compact sets are closed, and so $E_{i, j}:=K_{i}-\operatorname{int}\left(K_{j}\right)$ is compact for $j<i$. Take a finite subcover of the $\left\{V_{\alpha}\right\}$ covering $E_{i+1, i}$, and set

$$
W_{\alpha, i}=V_{\alpha} \cap \operatorname{int}\left(E_{i+2, i-1}\right) .
$$

Show that the resulting collection $\left\{W_{\alpha, i}\right\}$ is a locally finite refinement. For fun, prove the equivalence of $(a) /(b)$ and $(c)$.
3. If $M, N$ are connected, smooth manifolds, then the product $M \times N$ can be made into a smooth manifold using the product manifold structure. Given patches $(U, \phi)$ on $M$ and $(V, \psi)$ on $N$ we use $(U \times V, \phi \times \psi)$ as a patch on $M \times N$. Show that this makes $M \times N$ into a smooth manifold. To show $M \times N$ is paracompact, use the preceding problem.
4. Prove the following lemma stated in class: Suppose $f: M_{1}^{m+k} \rightarrow M_{2}^{m}$ is a smooth map. Suppose $q \in M_{2}$ is a regular value of $f$. Then $f^{-1}(q)$ is a smooth submanifold of $M_{1}$ dimension $k$.
5. Let $(x, y, z)$ be coordinates on $\mathbb{R}^{3}$. Let $Y_{r}$ be the set of points in $\mathbb{R}^{3}$ at distance $r>0$ from the circle

$$
C=\left\{(x, y, z) \in \mathbb{R}^{3} \mid x^{2}+y^{2}=1, z=0\right\}
$$

(a) Let $A=\left\{r \in(0, \infty) \mid Y_{r}\right.$ is a submanifold of $\left.\mathbb{R}^{3}\right\}$. Find $A$.
(b) Let $S^{1}$ be equipped with the smooth structure given by stereographic projection (see (1)), and let $S^{1} \times S^{1}$ be equipped with the product manifold structure (see below). Prove that $Y_{r}$ is diffeomorphic to $S^{1} \times S^{1}$ for any $r \in A$.
6. Prove Hadamard's Lemma. If $F: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is smooth, then there are smooth functions $H_{1}(x), \ldots, H_{n}(x)$ so that

$$
F=F(0)+\sum_{i=1}^{n} x_{i} H_{i}(x)
$$

with $H_{i}(0)=\frac{\partial F}{\partial x_{i}}(0)$. (Hint: Use the fundamental theorem of calculus).
7. Let $M$ be a smooth manifold, and $p \in M$ a point. Let $\left(x_{1}, \ldots, x_{n}\right)$ be local coordinates near $p$. Show that every derivation $D$ at $p$ is given by

$$
D=\left.\sum_{i=1}^{n} a_{i} \frac{\partial}{\partial x_{i}}\right|_{p}
$$

for $a_{i} \in \mathbb{R}$. (Hint: Use Hadamard's lemma).
8. Let $p\left(x_{1}, \ldots, x_{k}\right)$ be a homogeneous polynomial of degree $m \geq 2$. That is,

$$
p\left(t x_{1}, \ldots, t x_{k}\right)=t^{m} p\left(x_{1}, \ldots, x_{k}\right)
$$

(a) Prove that if $a \neq 0$, and $p^{-1}(a)$ is not empty, then $X_{a}:=\{p(x)=a\}$ is a smooth, $k-1$ dimensional submanifold of $\mathbb{R}^{k}$.
(b) Prove that $X_{a}$ is diffeomorphic to $X_{1}$ if $a>0$, and $X_{a}$ is diffeomorphic to $X_{-1}$ if $a<0$, provided $a$ is in the range of $p$.
9. Let $M_{n}(\mathbb{R})$ be the space of $n \times n$ matrices with real entires. Assume $n \geq 2$, and define $f: M_{n}(\mathbb{R}) \rightarrow \mathbb{R}$ to be $f(A)=\operatorname{det}(A)$.
(a) Recall that the adjoint of $A$ has entry in the $i$-th row and $j$-th column

$$
(\operatorname{adj} A)_{i j}=(-1)^{i+j} \operatorname{det} A(j \mid i)
$$

where $A(j \mid i) \in M_{n-1}(\mathbb{R})$ is the matrix obtained by removing the $j$-th column and the $i$-th row. Show that the differential of $f$ at $A$ is given by

$$
d f_{A}: M_{n}(\mathbb{R}) \rightarrow \mathbb{R}, \quad d f_{A}(B)=\operatorname{Tr}((\operatorname{adj} A) B)
$$

(b) Use the fact that $A(\operatorname{adj} A)=(\operatorname{det} A) I$ to prove the follwing formula for the differential of $f$

$$
d f_{A}=(\operatorname{det} A) \operatorname{Tr}\left(A^{-1} B\right)
$$

whenever $\operatorname{det} A \neq 0$.
(c) Conclude that $S L(n, \mathbb{R}):=\left\{A \in M_{n}(\mathbb{R}): \operatorname{det} A=1\right\}$ is a smooth submanifold of $M_{n}(\mathbb{R})$.
10. Let $X, Y, Z$ be the vector fields on $\mathbb{R}^{3}$ defined by

$$
X=z \frac{\partial}{\partial y}-y \frac{\partial}{\partial z}, \quad Y=x \frac{\partial}{\partial z}-z \frac{\partial}{\partial x}, \quad Z=y \frac{\partial}{\partial x}-x \frac{\partial}{\partial y} .
$$

(a) Compute the flow of the vector field $X$.
(b) The map $\mathbb{R}^{3} \ni(a, b, c) \mapsto a X+b Y+c Z$ injects onto its image which is a subspace of the space of smooth vectorfields on $\mathbb{R}^{3}$. Show that, under this map, the bracket of vector fields induces the cross product on $\mathbb{R}^{3}$.

