

**18.700 - LINEAR ALGEBRA, DAY 24
BILINEAR AND MULTILINEAR FORMS
DETERMINANTS**

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I. PRE-CLASS PLANNING

I.1. Goals for lesson.

- (1) Students will learn the definitions of an inversion and the sign of a permutation.
- (2) Students will learn how permuting the entries affects the value of an alternating multilinear form.
- (3) Students will learn properties of the determinant, such as multiplicativity, interpretation as product of eigenvalues, etc.

I.2. Methods of assessment.

- (1) Student responses to questions posed during lecture
- (2) Student responses to worksheet

I.3. Materials to bring. (1) Laptop + adapter (2) Worksheets (3) Chalk

(0:00)

II. LESSON PLAN

II.1. Last time.

- Proved that every linear map has Jordan basis.
- Defined trace: $\text{tr}(A) = \sum_{i=1}^n A_{ii}$.
- Proved properties of trace. [Ask students about trace and eigenvalues.]
- Defined multilinear forms.

II.2. Worksheet.

II.3. **9B: Multilinear forms.** Notation: $V^m = \overbrace{V \times \cdots \times V}^{m \text{ times}}$. So an element of V^m is of the form (v_1, \dots, v_m) with $v_i \in V$ for all i .

- An m -linear form on V is a function $\beta : V^m \rightarrow \mathbb{F}$ that is linear in each component when the others are held fixed. I.e., for each $k \in \{1, \dots, m\}$ and $u_1, \dots, u_m \in V$, the map

$$V \rightarrow \mathbb{F}$$

$$v \mapsto \beta(u_1, \dots, u_{k-1}, v, u_{k+1}, \dots, u_m)$$

is linear.

- An m -linear form $\alpha \in V^{(m)}$ is *alternating* if $\alpha(v_1, \dots, v_m) = 0$ whenever $v_j = v_k$ for some $j, k \in \{1, \dots, m\}$ with $j \neq k$.

Lemma 1. $V^{(m)}$ is a vector space, and $V_{\text{alt}}^{(m)}$ is a subspace.

Proof. Exercise. □

Lemma 2. Let $\alpha \in V_{\text{alt}}^{(m)}$. If $v_1, \dots, v_m \in V$ is linearly dependent, then

$$\alpha(v_1, \dots, v_m) = 0.$$

Proof idea. Use the Linear Dependence Lemma to express v_k as a linear combination of the others. Then use multilinearity and alternating property. Details left as an exercise. □

Proposition 3. Let $\alpha \in V_{\text{alt}}^{(m)}$ and $v_1, \dots, v_m \in V$. Swapping the vectors in any two slots of $\alpha(v_1, \dots, v_m)$ changes the value by a factor of -1 .

Proof idea. For simplicity, suppose $m = 2$. Then

$$0 = \alpha(v+w, v+w) = \cancel{\alpha(v,v)}^0 + \alpha(v,w) + \alpha(w,v) + \cancel{\alpha(w,w)}^0.$$

The proof is virtually the same for $m \geq 2$. □

Q: What if we perform multiple swaps? For example, suppose that $\alpha \in V_{\text{alt}}^{(3)}$ and $v_1, v_2, v_3 \in V$. Then

$$\alpha(v_3, v_1, v_2) = -\alpha(v_1, v_3, v_2) = \alpha(v_1, v_2, v_3).$$

This leads us to investigate more general permutations.

Definition 4. Let $m \in \mathbb{Z}_{>0}$.

- A *permutation* of $(1, \dots, m)$ is a rearrangement of $(1, \dots, m)$, i.e., a list (j_1, \dots, j_m) that contains each of $1, \dots, m$ exactly once.
- Denote the set of all permutations of $(1, \dots, m)$ by $\text{perm}(m)$ or S_m . (The *symmetric group* on $1, \dots, m$.)

Example 5. $(2, 1, 4, 3) \in \text{perm}(4)$.

Definition 6. Suppose $(j_1, \dots, j_m) \in \text{perm}(m)$.

- An *inversion* of (j_1, \dots, j_m) is a pair of integers (k, ℓ) with $k, \ell \in \{1, \dots, m\}$ such that $k < \ell$ and k appears *after* ℓ in the list (j_1, \dots, j_m) .
- Let N be the number of inversions of (j_1, \dots, j_m) . The *sign* of (j_1, \dots, j_m) is

$$\text{sgn}(j_1, \dots, j_m) := (-1)^N.$$

Example 7.

- Consider $(2, 1, 3, 4) \in \text{perm}(4)$. It has exactly one inversion, namely $(1, 2)$, so it has $\text{sign}(-1)^1 = -1$.
- The permutation $(1, \dots, m)$ has no inversions (the numbers are all in increasing order), so it has $\text{sign}(-1)^0 = 1$.
- Consider the permutation $(2, 3, \dots, m, 1)$. Its inversions are

$$(1, 2), (1, 3), \dots, (1, m)$$

so it has $\text{sign}(-1)^{m-1}$.

Proposition 8. *Swapping two entries in a permutation multiplies the sign of the permutation by -1 .*

Proof sketch. [Shorten or skip, if necessary.] Let π be the original permutation, and π' be the permutation obtained from swapping the i^{th} and j^{th} entries of π . Denote the i^{th} entry of π by $\pi(i)$. Then $\pi(i) < \pi(j)$ iff $\pi'(i) > \pi'(j)$, so we have either added or subtracted exactly 1 inversion so far.

Consider the entries not in between the i^{th} and j^{th} spots. For these entries, there is no change in whether they were in order or not. [Draw picture.]

Now consider $\pi(k)$ with $i < k < j$.

Case 1: $\pi(k)$ was in order with respect to both $\pi(i)$ and $\pi(j)$, i.e., $\pi(i) < \pi(k) < \pi(j)$. Then

$$\pi'(i) > \pi'(k) > \pi'(j)$$

so we have 2 more inversions, multiplying the sign by $(-1)^2 = 1$.

Case 2: $\pi(i) > \pi(k) > \pi(j)$. Similar.

Case 3: $\pi(i) < \pi(k)$ and $\pi(k) > \pi(j)$. Then

$$\pi'(i) = \pi(j) < \pi(k) = \pi'(k)$$

$$\pi'(k) = \pi(k) > \pi(i) = \pi'(j)$$

so we have the same number of inversions that we started with, and the sign is unchanged.

Case 4: $\pi(i) > \pi(k)$ and $\pi(k) < \pi(j)$. Similar.

Thus in all cases we have an odd number of inversions, so $\text{sign}(\pi') = -\text{sign}(\pi)$. \square

Proposition 9. Suppose $m \in \mathbb{Z}_{>0}$ and $\alpha \in V_{\text{alt}}^{(m)}$. Then

$$\alpha(v_{j_1}, \dots, v_{j_m}) = \text{sign}(j_1, \dots, j_m) \alpha(v_1, \dots, v_m)$$

Proof idea. We can get from (j_1, \dots, j_m) to $(1, \dots, m)$ by a series of swaps. Each swap changes the sign of α by a factor of -1 , and also changes the sign of the remaining permutation by a factor of -1 . \square

Theorem 10. Let $n := \dim(V)$. Suppose e_1, \dots, e_n is a basis of V . Suppose $v_1, \dots, v_n \in V$. For each k , write

$$v_k = \sum_{j=1}^n b_{j,k} e_j$$

for some $b_{1,k}, \dots, b_{n,k} \in \mathbb{F}$. Then

$$\alpha(v_1, \dots, v_n) = \alpha(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) b_{j_1,1} \cdots b_{j_n,n}$$

for all $\alpha \in V_{\text{alt}}^{(n)}$.

Proof.

$$\begin{aligned} \alpha(v_1, \dots, v_n) &= \alpha \left(\sum_{j_1=1}^n b_{j_1,1} e_{j_1}, \dots, \sum_{j_n=1}^n b_{j_n,n} e_{j_n} \right) = \sum_{j_1=1}^n \cdots \sum_{j_n=1}^n b_{j_1,1} \cdots b_{j_n,n} \alpha(e_{j_1}, \dots, e_{j_n}) \\ &= \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} b_{j_1,1} \cdots b_{j_n,n} \alpha(e_{j_1}, \dots, e_{j_n}) \\ &= \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} b_{j_1,1} \cdots b_{j_n,n} \text{sign}(j_1, \dots, j_n) \alpha(e_1, \dots, e_n) \\ &= \alpha(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) b_{j_1,1} \cdots b_{j_n,n}, \end{aligned}$$

where the third equality holds because $\alpha(e_{j_1}, \dots, e_{j_n}) = 0$ if j_1, \dots, j_n are not distinct. \square

Corollary 11. $\dim(V_{\text{alt}}^{(n)}) = 1$.

Proof. Let $n := \dim(V)$. Suppose $\alpha, \alpha' \in V_{\text{alt}}^{(n)}$ with $\alpha \neq 0$. Then $\alpha(e_1, \dots, e_n) \neq 0$ for some $e_1, \dots, e_n \in V$. Then e_1, \dots, e_n is linearly independent (contrapositive of earlier result). Let

$$c := \frac{\alpha'(e_1, \dots, e_n)}{\alpha(e_1, \dots, e_n)}.$$

Letting $b_{j,k}$ be as above, then

$$\begin{aligned} \alpha'(v_1, \dots, v_n) &= \alpha'(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) b_{j_1,1} \cdots b_{j_n,n} \\ &= c \alpha(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) b_{j_1,1} \cdots b_{j_n,n} \\ &= c \alpha(v_1, \dots, v_n). \end{aligned}$$

Thus $\alpha' = c\alpha$. Thus $\dim(V_{\text{alt}}^{(n)}) \leq 1$.

It remains to show that $\dim(V_{\text{alt}}^{(n)}) = 1$. For details, see 9.37 in the text book. (Uses the concept of the dual basis of a basis.) \square

[Skip if necessary.] To prove that $\dim(V_{\text{alt}}^{(n)}) = 1$, we will need some more results on linear functionals. Recall that V^\vee , the dual space, is

$$V^\vee = \mathcal{L}(V, \mathbb{F}) = \{\varphi : V \rightarrow \mathbb{F} \mid \varphi \text{ is linear}\}.$$

Fix $j \in \{1, \dots, n\}$. Define

$$\begin{aligned} \varphi_j : \mathbb{F}^n &\rightarrow \mathbb{F} \\ (x_1, \dots, x_n) &\mapsto x_j, \end{aligned}$$

i.e., projection onto the j^{th} coordinate. Then φ_j is linear and

$$\varphi_j(e_k) = \begin{cases} 1 & \text{if } k = j; \\ 0 & \text{otherwise.} \end{cases}$$

We can define a similar notion in general.

Definition 12. Let $\mathcal{B} := (v_1, \dots, v_n)$ be a basis of V . The *dual basis of \mathcal{B}* is the list $\mathcal{B}^\vee := (\varphi_1, \dots, \varphi_n)$ in V^\vee , where φ_j is defined by

$$\varphi_j(v_k) = \begin{cases} 1 & \text{if } k = j; \\ 0 & \text{otherwise.} \end{cases}$$

Lemma 13. Suppose V is finite-dimensional. Then \mathcal{B}^\vee is a basis of V^\vee .

Remark 14. φ_j is sometimes denoted v_j^\vee .

Proof, completed. Let $e_1, \dots, e_n \in V$ be a basis and let $\varphi_1, \dots, \varphi_n \in V^\vee$ be its dual basis. Define

$$\alpha(v_1, \dots, v_n) = \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) \varphi_{j_1}(v_1) \cdots \varphi_{j_n}(v_n).$$

One can show that α is n -linear, alternating, and nonzero. Indeed,

$$\alpha(e_1, \dots, e_n) = 1$$

since only the term corresponding to the permutation $(1, \dots, n)$ is nonzero. \square

Proposition 15. Let $n := \dim(V)$. Suppose $\alpha \in V_{\text{alt}}^{(n)}$ is nonzero and $e_1, \dots, e_n \in V$. Then e_1, \dots, e_n is linearly independent iff

$$\alpha(e_1, \dots, e_n) \neq 0.$$

Proof. (\Leftarrow): Assume $\alpha(e_1, \dots, e_n) \neq 0$. Then e_1, \dots, e_n is linearly independent: this is the converse of an earlier result.

(\Rightarrow): Assume e_1, \dots, e_n is linearly independent. Since $n = \dim(V)$, then it is a basis of V . Since $\alpha \neq 0$ then there exist $v_1, \dots, v_n \in V$ such that $\alpha(v_1, \dots, v_n) \neq 0$. Since e_1, \dots, e_n is a basis, then for each k ,

$$v_k = \sum_{j=1}^n b_{j,k} e_j$$

for some $b_{1,k}, \dots, b_{n,k} \in \mathbb{F}$. By an earlier result,

$$0 \neq \alpha(v_1, \dots, v_n) = \alpha(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) b_{j_1,1} \cdots b_{j_n,n}.$$

Thus $\alpha(e_1, \dots, e_n) \neq 0$. □

II.4. 9C: Determinants. [Show 3Blue1Brown video: <https://www.youtube.com/watch?v=Ip3X9L0h2dk> beginning until about 5:30 or so.]

Definition 16 (“Moral” definition). Suppose $T \in \mathcal{L}(V)$. Consider the unit hypercube C formed by the standard basis e_1, \dots, e_n . Then the image of C under T is a parallelotope P . The determinant of T is the signed volume of P , where the sign keeps track of the orientation of $T(e_1), \dots, T(e_n)$.

Definition 17. Suppose $m \in \mathbb{Z}_{>0}$ and $T \in \mathcal{L}(V)$. Define the map

$$\begin{aligned} T^\# : V_{\text{alt}}^{(m)} &\rightarrow V_{\text{alt}}^{(m)} \\ \alpha &\mapsto T^\#(\alpha) \end{aligned}$$

where

$$T^\#(\alpha)(v_1, \dots, v_m) := \alpha(T(v_1), \dots, T(v_m)).$$

Remark 18. The textbook instead denotes $T^\#(\alpha)$ by α_T .

Let $n := \dim(V)$. Recall that $V_{\text{alt}}^{(n)}$ has dimension 1. Any linear map from a 1-dimensional space to itself is multiplication by a scalar.

Definition 19.

- Let $n := \dim(V)$. Suppose $T \in \mathcal{L}(V)$. The *determinant* of T , denoted $\det(T)$, is the unique scalar in \mathbb{F} such that

$$T^\#(\alpha) = \det(T)\alpha$$

for all $\alpha \in V_{\text{alt}}^{(n)}$.

- Suppose $A \in M_{n \times n}(\mathbb{F})$. Define $\det(A) := \det(L_A)$ where L_A is the left multiplication map

$$\begin{aligned} L_A : \mathbb{F}^n &\rightarrow \mathbb{F}^n \\ v &\mapsto Av. \end{aligned}$$

Example 20.

- Consider the identity operator I .

$$I^\#(\alpha)(v_1, \dots, v_n) = \alpha(Iv_1, \dots, Iv_n) = \alpha(v_1, \dots, v_n),$$

so $I^\#(\alpha) = \alpha$. Thus [ask students] $\det(I) = 1$.

- Suppose T is diagonalizable with a basis of eigenvectors v_1, \dots, v_n with eigenvalues $\lambda_1, \dots, \lambda_n$. Given $0 \neq \alpha \in V_{\text{alt}}^{(n)}$, then

$$T^\#(\alpha)(v_1, \dots, v_n) = \alpha(T(v_1), \dots, T(v_n)) = \alpha(\lambda_1 v_1, \dots, \lambda_n v_n) = \lambda_1 \cdots \lambda_n \alpha(v_1, \dots, v_n).$$

Thus $\det(T) = \lambda_1 \cdots \lambda_n$, the product of the eigenvalues of T .

Theorem 21. Suppose $n \in \mathbb{Z}_{>0}$. The map

$$\varphi : \overbrace{\mathbb{F}^n \times \cdots \times \mathbb{F}^n}^{n \text{ times}} \rightarrow \mathbb{F}$$

$$(v_1, \dots, v_n) \mapsto \det \begin{pmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{pmatrix}$$

is an alternating n -linear form on \mathbb{F}^n .

Proof. Let $\mathcal{E} := (e_1, \dots, e_n)$ be the standard basis of \mathbb{F}^n . Suppose $v_1, \dots, v_n \in \mathbb{F}^n$. Define

$$T : \mathbb{F}^n \rightarrow \mathbb{F}^n$$

$$e_i \mapsto v_i$$

for each $i = 1, \dots, n$. Then

$$[T]_{\mathcal{E}} = \begin{pmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{pmatrix}.$$

Let α be an alternating n -linear form on \mathbb{F}^n such that $\alpha(e_1, \dots, e_n) = 1$. Then

$$\begin{aligned} \psi(v_1, \dots, v_n) &= \det \begin{pmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{pmatrix} = \det(T) = \det(T)\alpha(e_1, \dots, e_n) \\ &= \alpha(T(e_1), \dots, T(e_n)) = \alpha(v_1, \dots, v_n). \end{aligned}$$

Thus $\psi = \alpha$, so the map ψ is an alternating n -linear form. □

Remark 22. One often considers the determinant of a square matrix A as a multilinear form on the columns of A .

Corollary 23. Suppose $n \in \mathbb{Z}_{>0}$ and $A \in M_{n \times n}(\mathbb{F})$. Then

$$\det(A) = \sum_{(j_1, \dots, j_n) \in \text{perm}(n)} \text{sign}(j_1, \dots, j_n) A_{j_1, 1} \cdots A_{j_n, n}.$$

Proof. Letting e_1, \dots, e_n be the standard basis for \mathbb{F}^n , note that

$$\det \begin{pmatrix} | & & | \\ e_1 & \cdots & e_n \\ | & & | \end{pmatrix} = \det(I) = 1.$$

The result follows from an earlier result on alternating n -linear forms on an n -dimensional vector space. □

Example 24. If A is 2×2 , then $\text{perm}(2) = \{(1, 2), (2, 1)\}$, so [ask students]

$$\det(A) = A_{1,1}A_{2,2} + (-1)A_{2,1}A_{1,2}.$$

Remark 25. While this formula can be used for small matrices, the sum contains $n!$ terms, which grows rapidly as n increases.

Proposition 26 (The determinant is multiplicative).

- $\det(ST) = \det(S) \det(T)$ for all $S, T \in \mathcal{L}(V)$.

- $\det(AB) = \det(A) \det(B)$ for all $A, B \in M_{n \times n}(\mathbb{F})$.

Proposition 27. $T \in \mathcal{L}(V)$ is invertible iff $\det(T) \neq 0$. In this case, $\det(T^{-1}) = \frac{1}{\det(T)}$.

Proof. (\Rightarrow): Assume T is invertible. Then

$$1 = \det(I) = \det(TT^{-1}) = \det(T) \det(T^{-1})$$

Thus $\det(T) \neq 0$.

(\Leftarrow): Exercise. (Usually proved using Cramer's rule.) □

Proposition 28. Suppose $T \in \mathcal{L}(V)$ and $\lambda \in \mathbb{F}$. Then λ is an eigenvalue of T iff $\det(\lambda I - T) = 0$.

Proof. λ is an eigenvalue of T iff $T - \lambda I$ is not invertible iff $\lambda I - T = -(T - \lambda I)$ is not invertible iff $\det(\lambda I - T) = 0$ by the previous result. □

Proposition 29. Suppose $T \in \mathcal{L}(V)$ and $S : W \rightarrow V$ is an invertible linear map. Then

$$\det(S^{-1}TS) = \det(T).$$

Proof. [Skip if necessary. See 9.52 in the textbook.] Since S is an isomorphism, then $\dim(W) = \dim(V)$; call this common value n . Given $\tau \in W_{\text{alt}}^{(n)}$, let $\alpha := (S^{-1})^{\#}(\tau)$, so

$$\alpha(v_1, \dots, v_n) = \tau(S^{-1}v_1, \dots, S^{-1}v_n)$$

for all $v_1, \dots, v_n \in V$. Given $w_1, \dots, w_n \in W$, then

$$\begin{aligned} (S^{-1}TS)^{\#}(\tau)(w_1, \dots, w_n) &= \tau(S^{-1}TSw_1, \dots, S^{-1}TSw_n) = \overbrace{(S^{-1})^{\#}(\tau)}^{\alpha}(TSw_1, \dots, TSw_n) \\ &= T^{\#}(\alpha)(Sw_1, \dots, Sw_n) = \det(T)\alpha(Sw_1, \dots, Sw_n) \\ &= \det(T)S^{\#}(\alpha)(w_1, \dots, w_n) = \det(T)\tau(w_1, \dots, w_n). \end{aligned}$$

□

Proposition 30. Suppose $T \in \mathcal{L}(V)$ and $\mathcal{B} := (v_1, \dots, v_n)$ a basis of V . Then

$$\det(T) = \det([T]_{\mathcal{B}}).$$

Proof. Let $\mathcal{E} = (e_1, \dots, e_n)$ be the standard basis of \mathbb{F}^n , and let $S : \mathbb{F}^n \rightarrow V$ be the isomorphism that takes $S(v_i) = e_i$ for each i . Then $_{\mathcal{B}}[S]_{\mathcal{E}} = I$, so

$$_{\mathcal{E}}[S^{-1}TS]_{\mathcal{B}} = _{\mathcal{E}}[S^{-1}]_{\mathcal{E}} [T]_{\mathcal{B}} _{\mathcal{B}}[S]_{\mathcal{E}} = I[T]_{\mathcal{B}}I = [T]_{\mathcal{B}}.$$

Then

$$\det(T) = \det(S^{-1}TS) = \det\left([S^{-1}TS]_{\mathcal{E}}\right) = \det([T]_{\mathcal{B}}).$$

□

Theorem 31 (Determinant is product of eigenvalues). Suppose $\mathbb{F} = \mathbb{C}$ and $T \in \mathcal{L}(V)$. Let $\lambda_1, \dots, \lambda_n$ be the eigenvalues of T , repeated with algebraic multiplicity. Then

$$\det(T) = \lambda_1 \cdots \lambda_n.$$

Proof. By a previous result, there exists a basis \mathcal{B} of V such that $[T]_{\mathcal{B}}$ is upper triangular with the eigenvalues of T on its diagonal. Then

$$\det(T) = \det([T]_{\mathcal{B}}) = \lambda_1 \cdots \lambda_n$$

□

Corollary 32. Suppose $\mathbb{F} = \mathbb{C}$ and $T = \mathcal{L}(V)$. Then

$$\det(zI - T) = \text{charpoly}(T)$$

considered as polynomial functions of $z \in \mathbb{C}$.

We now use this to redefine the notion of characteristic polynomial, extending the definition to operators on \mathbb{R} -vector spaces.

Definition 33. Let V be a finite-dimensional \mathbb{F} -vector space and $T \in \mathcal{L}(V)$. Then polynomial defined by

$$z \mapsto \det(zI - T)$$

is the *characteristic polynomial* of T .

Proposition 34.

(a) Suppose A is a square matrix. Then $\det(A^t) = \det(A)$.

(b) Suppose V is an inner product space and $T \in \mathcal{L}(V)$. Then

$$\det(T^*) = \overline{\det(T)}.$$

Proof. (a) Let $n \in \mathbb{Z}_{>0}$. Define

$$\alpha : (\mathbb{F}^n)^n \rightarrow \mathbb{F}$$

$$(v_1, \dots, v_n) \mapsto \det \begin{pmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{pmatrix}.$$

From the permutation formula for the determinant, then α is an n -linear form on \mathbb{F}^n .

Claim: α is alternating. Suppose $v_1, \dots, v_n \in \mathbb{F}^n$ with $v_j = v_k$ for some $j \neq k$. Then the matrix

$$B := \begin{pmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{pmatrix}$$

has rank $< n$. Since row rank = column rank, then B^t has rank $< n$, so B^t is not invertible. Then the columns of B^t are linearly dependent, hence

$$\alpha(v_1, \dots, v_n) = \det(B^t) = 0.$$

Thus α is alternating.

Since $\alpha, \det \in V_{\text{alt}}^{(n)}$ and this space is 1-dimensional, then $\alpha = c \det$ for some $c \in \mathbb{F}$. Applying α to the standard basis, we have

$$\alpha(e_1, \dots, e_n) = \det(I^t) = \det(I) = 1,$$

so $c = 1$ and $\alpha = \det$ (thought of as a function of the columns).

(b) Exercise. □

Proposition 35. *Let A be a square matrix.*

- (a) *If any two columns of A are equal, then $\det(A) = 0$.*
- (b) *Let B be the matrix obtained by swapping two rows of A . Then $\det(B) = -\det(A)$.*
- (c) *If B is obtained by multiplying a column of A by a scalar c , then $\det(B) = c \det(A)$.*
- (d) *If B is obtained by adding a scalar multiple of one column of A to another, then $\det(B) = \det(A)$.*
- (e) *In all the above, the word “column” may be replaced by the word “row”.*

Proof. Straightforward. Last statement holds because $\det(A^t) = \det(A)$ by the previous result. For instance,

$$\det(v_1 + cv_2, v_2, \dots, v_n) = \det(v_1, v_2, \dots, v_n) + c \det(v_2, v_2, \dots, v_n) = \det(v_1, \dots, v_n).$$

□

Remark 36. This provides a strategy for evaluating the determinant of a matrix A :

- (1) Perform row operations on A to obtain an upper triangular matrix, keeping track of any swaps or rescalings of rows.
- (2) The determinant of the resulting upper triangular matrix is simply the product of the diagonal entries. Multiply this by the factors from swaps and rescalings.

Example 37. Let

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{pmatrix}.$$

Then $\det(A) = \dots = 2$. [Row reduce matrix.]