# 18.700 - LINEAR ALGEBRA, DAY 20 SINGULAR VALUE DECOMPOSITION GENERALIZED EIGENVECTORS

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# I. PRE-CLASS PLANNING

# I.1. Goals for lesson.

- (1) Students will learn Singular Value Decomposition.
- (2) Students will learn how to compute an SVD of a matrix.
- (3) Students will learn the definition of generalized eigenvector.

### I.2. Methods of assessment.

- (1) Student responses to questions posed during lecture
- (2) Student responses to worksheet

### I.3. Materials to bring. (1) Laptop + adapter (2) Worksheets (3) Chalk

### II. LESSON PLAN

### II.1. Last time.

- Defined isometries and unitary operators.
- Proved QR Decomposition exists.
- Defined singular values of a linear map.

## II.2. 7E: Singular Value Decomposition (SVD), cont.

**Definition 1.** Let  $T \in \mathcal{L}(V, W)$ . The *singular values* of *T* are the nonnegative square roots of the eigenvalues of  $T^*T$ , listed in decreasing order, and with multiplicity.

**Theorem 2** (Singular Value Decomposition (SVD)). Suppose  $T \in \mathcal{L}(V, W)$ . Let  $s_1, \ldots, s_n$  be the singular values of T, and let  $s_1, \ldots, s_m$  be the positive ones. Then there exist orthonormal lists  $e_1, \ldots, e_m$  in V and  $f_1, \ldots, f_m$  in W such that

$$\Gamma(v) = s_1 \langle v, e_1 \rangle f_1 + \dots + s_m \langle v, e_m \rangle f_m$$

for all  $v \in V$ .

*Proof.* Since  $T^*T$  is positive, then by the Spectral Theorem there is an orthonormal basis  $e_1, \ldots, e_n$  of *V* such that

for each 
$$k = 1, ..., n$$
. Now, for each  $k = 1, ..., m$ , define  
 $f_k := \frac{T(e_k)}{s_k}$ .

We show that  $f_1, \ldots, f_m$  is orthonormal:

$$\langle f_j, f_k \rangle = \left\langle \frac{1}{s_j} T(e_j), \frac{1}{s_k} T(e_k) \right\rangle = \frac{1}{s_j s_k} \langle T(e_j), T(e_k) \rangle = \frac{1}{s_j s_k} \langle e_j, T^* T(e_k) \rangle = \frac{1}{s_j s_k} \langle e_j, s_k^2 e_k \rangle$$
$$= \frac{s_k}{s_j} \langle e_j, e_k \rangle = \begin{cases} 0 & \text{if } j \neq k, \\ 1 & \text{if } j = k \end{cases}$$

for all  $j, k \in \{1, ..., m\}$ . (Note that  $s_k \in \mathbb{R}$  for all k.)

Note that for k > m we have

$$T^*T(e_k) = s_k^2 e_k = 0 \implies e_k \in \ker(T^*T) = \ker(T) \implies T(e_k) = 0$$

by a previous result. Given  $v \in V$ , since  $e_1, \ldots, e_n$  is orthonormal, then

$$T(v) = T(\langle v, e_1 \rangle e_1 + \dots \langle v, e_n \rangle e_n = \langle v, e_1 \rangle T(e_1) + \dots \langle v, e_m T(e_m) \rangle$$
  
=  $\langle v, e_1 \rangle s_1 f_1 + \dots + \langle v, e_m \rangle s_m f_m.$ 

 $\square$ 

**Proposition 3** (SVD of adjoint). Suppose  $T \in \mathcal{L}(V, W)$  and  $s_1, \ldots, s_m, e_1, \ldots, e_m$ , and  $f_1, \ldots, f_m$  are as before, so

$$T(v) = s_1 \langle v, e_1 \rangle f_1 + \dots + s_m \langle v, e_m \rangle f_m$$

for all  $v \in V$ . Then

$$T^*(w) = s_1 \langle w, f_1 \rangle e_1 + \dots + s_m \langle v, e_m \rangle e_m$$

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**Definition 4.** Let  $A \in M_{m \times n}(\mathbb{F})$ . *A* is (generalized) diagonl if  $A_{ij} = 0$  for all  $i, j \in \{1, ..., \min(m, n)\}$  with  $i \neq j$ .

**Theorem 5** (SVD, matrix version). Let  $A \in M_{m \times n}(\mathbb{F})$  have rank r. Then there exists

- a generalized diagonal matrix  $\Sigma \in M_{\mathfrak{m} \times n}(\mathbb{F})$  whose diagonal entries are the positive singular values of A;
- a unitary matrix  $U \in M_{m \times m}(\mathbb{F})$ ; and
- a unitary matrix  $V \in M_{n \times n}(\mathbb{F})$

such that  $A = U\Sigma V^*$ .

*Proof sketch.* Let  $v_1, \ldots, v_n$  be an orthonormal basis of  $\mathbb{F}^n$  consisting of eigenvectors of  $A^*A$ . Let *V* be the matrix whose columns are  $v_1, \ldots, v_n$ .

Suppose *A* has *r* nonzero singular values. Then  $Av_1, \ldots, Av_r$  is an orthogonal basis for Col(A):

$$\langle Av_i, Av_j \rangle = \langle v_i, A^*Av_j \rangle = \langle v_i, \lambda_j v_j \rangle = \overline{\lambda_j} \langle v_i, v_j \rangle = 0.$$

Normalize this list to obtain an orthonormal basis  $u_1, \ldots, u_r$  of Col(A), where

$$u_i := \frac{1}{s_i} A v_i$$

for i = 1, ..., r. Extend this to a basis  $u_1, ..., u_m$  of  $\mathbb{F}^m$ . Let U be the matrix with columns  $u_1, ..., u_m$ . We claim that

$$A = U\Sigma V^*$$
.

II.3. Worksheet.

$$A = \begin{pmatrix} 3 & 2 \\ 2 & 3 \\ 2 & -2 \end{pmatrix} \implies A^*A = \begin{pmatrix} 17 & 8 \\ 8 & 17 \end{pmatrix}.$$

Then minpoly $(A^*A) = x^2 - 34x + 225 = (x - 9)(x - 25).$ 

$$V = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix}$$
$$Av_1 = \begin{pmatrix} 5/\sqrt{2} \\ 5/\sqrt{2} \\ 0 \end{pmatrix} \qquad Av_2 = \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \\ 2\sqrt{2} \end{pmatrix}$$
$$u_1 = \frac{1}{5}Av_1$$
$$u_2 = \frac{1}{3}Av_2$$
$$u_3 = \begin{pmatrix} -2/3 \\ 2/3 \\ 1/3 \end{pmatrix}$$

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https://sagecell.sagemath.org/?z=eJxtj0FugzAQRfdI3MFL2x0g2M2uqQQ3oBVsLLeyEpqgNqEFy-X4H vZ\_M\_MnIztyNrZrBloUoJQEAUKDEiAhElqzMMgQyWLbmUv\_2fY1xa\_-1H7TDEX-3-PZ1c3RDYOn-GF4RKYo1A6DN 5Q05IHh9qS5mnXYqoqz2k0qT\_6iwVDMgsxzh0rEPRDfWbkLt0oQXq6m9f5VJwQ18\_q5UNKxTloiBNtnzsOSaSoxI E6DdmC1Avf33Fvzf6dTrM2sNFsauaBuTP3T05v1mHsBwcyiHY=&lang=sage&interacts=eJyLjgUAARUAuQ=

Applications of SVD:

• Low-rank approximations of linear maps. Let

$$T(v) = s_1 \langle v, e_1 \rangle f_1 + \dots + s_m \langle v, e_m \rangle f_m$$

be a singular value decomposition for *T*. Define  $T_k \in \mathcal{L}(V, W)$  as the truncation

$$T_k(v) = s_1 \langle v, e_1 \rangle f_1 + \cdots + s_k \langle v, e_k \rangle f_k.$$

One can show that  $T_k$  is the "best" rank k approximation of T. This idea is used in image compression.

• Principal component analysis (PCA). Suppose that we have some multivariate data from *n* observations, stored as column vectors  $X_1, \ldots, X_n \in \mathbb{R}^m$ . Let *X* be the  $m \times n$  matrix with columns  $X_1, \ldots, X_n$ . We want to find an orthonormal basis  $v_1, \ldots, v_n$  such that most of the variation of the data occurs in the directions of  $v_1, v_2, \cdots v_n$ . This is usual done by computing a SVD  $X = U\Sigma V^*$ : the vectors  $v_1, \ldots, v_n$  that are the columns of *V* (which are also the eigenvectors of  $X^*X$ ) are the desired basis.

See section 7F for more applications of SVD.

II.4. 8A: Generalized Eigenvectors. Throughout this section, let V be a nonzero finitedimensional  $\mathbb{F}$ -vector space.

# II.4.1. Preliminaries.

**Lemma 6.** Let  $T \in \mathcal{L}(V)$ . Then we have an ascending chain

$$\{0\} = \ker(T^0) \subseteq \ker(T) \subseteq \ker(T^2) \subseteq \dots \subseteq \ker(T^k) \subseteq \ker(T^{k+1}) \subseteq \dots$$
(7)

*Proof.* [Skip, if necessary.] Suppose  $k \in \mathbb{Z}_{\geq 0}$ . Given  $v \in \ker(T^k)$ , then  $T^k(v) = 0$ . Then

$$T^{k+1}(v) = T(T^k(v)) = T(0) = 0$$

so  $v \in \ker(T^{k+1})$ .

**Proposition 8.** Suppose  $T \in \mathcal{L}(V)$ . If

$$\ker(T^m) = \ker(T^{m+1})$$

for some  $m \in \mathbb{Z}_{>0}$ , then

$$\ker(T^m) = \ker(T^{m+1}) = \ker(T^{m+2}) = \ker(T^{m+3}) = \cdots$$

*Proof.* [Skip, if necessary.] We want to show that  $\ker(T^{m+k}) = \ker(T^{m+k+1})$  for all  $k \in \mathbb{Z}_{\geq 0}$ . Suppose  $k \in \mathbb{Z}_{\geq 0}$ .

 $(\subseteq)$ : Follows from previous lemma.

(⊇): Given  $v \in \ker(T^{m+k+1})$ , then

$$T^{m+1}(T^k(v)) = T^{m+k+1}(v) = 0$$
 ,

so  $T^k(v) \in \ker(T^{m+1}) = \ker(T^m)$ . Then

$$T^{m+k}(v) = T^m(T^k(v)) = 0$$

so  $v \in \ker(T^{m+k})$ .

**Proposition 9.** Suppose  $T \in \mathcal{L}(V)$ . The chain in (7) stabilizes:

$$\operatorname{ker}(T^n) = \operatorname{ker}(T^{n+1}) = \operatorname{ker}(T^{n+2}) = \cdots,$$

where  $n := \dim(V)$ .

*Proof.* For contradiction, suppose ker $(T^n) \neq$  ker $(T^{n+1})$ . This means that no two terms in the chain are equal at or before the  $(n + 1)^{st}$  step by the previous result:

$$\{0\} = \ker(T^0) \subsetneq \ker(T) \subsetneq \cdots \subsetneq \ker(T^n) \subsetneq \ker(T^{n+1})$$

with strict containments. At each strict inclusion, the dimension must increase by at least 1, so dim $(\text{ker}(T^k)) \ge k$  for each k = 1, ..., n + 1. But then

$$\dim(\ker(T^{n+1})) \ge n+1 > n = \dim(V)$$
,

contradiction.

It's not true that  $V = \ker(T) \oplus \operatorname{img}(T)$  for every  $T \in \mathcal{L}(V)$ . (Consider  $V = \mathbb{F}^3$  and  $T := L_A$  where

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

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**Proposition 10.** Suppose  $T \in \mathcal{L}(V)$ . Letting  $n := \dim(V)$ , then

 $V = \ker(T^n) \oplus \operatorname{img}(T^n).$ 

*Proof.* [Skip, if necessary.] Given  $v \in \text{ker}(T^n) \cap \text{img}(T^n)$ , then  $T^n(v) = 0$  and  $v = T^n(u)$  for some  $u \in V$ . Then

$$T^{2n}(u) = T^n(T^n(u)) = T^n(v) = 0$$
,

so  $u \in \ker(T^{2n}) = \ker(T^n)$ . Then

$$0=T^n(u)=v.$$

Thus  $\ker(T^n) \cap \operatorname{img}(T^n) = \{0\}.$ 

By Rank-Nullity, we have

$$\dim(V) = \dim(\ker(T^n)) + \dim(\operatorname{img}(T^n)) = \dim(\ker(T^n) \oplus \operatorname{img}(T^n)),$$

hence  $V = \ker(T^n) \oplus \operatorname{img}(T^n)$ .

II.4.2. Generalized eigenvectors. Note that v is an eigenvector of  $T \in \mathcal{L}(V)$  iff span(v) is a (1-dimensional) T-invariant subspace. So T is diagonalizable iff

$$V = V_1 \oplus \dots \oplus V_n \tag{11}$$

where  $V_i = \text{span}(v_i)$  is a 1-dimensional *T*-invariant subspace for each i = 1, ..., n. But we know that not every linear operator *T* is diagonalizable: e.g.,  $V = \mathbb{F}^2$  and  $T = L_A$  for

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

But what if we allow for *T*-invariant subspaces of larger dimension in (11)? This leads to the following notion.

**Definition 12.** Suppose  $T \in \mathcal{L}(V)$  and  $\lambda$  is an eigenvalue of T. A vector  $v \in V$  is a *generalized eigenvector* of *T* associated to  $\lambda$  if  $v \neq 0$  and

$$(T - \lambda I)^k(v) = 0$$

for some  $k \in \mathbb{Z}_{>0}$ .

**Theorem 13.** Suppose  $\mathbb{F} = \mathbb{C}$  and  $T \in \mathcal{L}(V)$ . Then there is a basis of V consisting of generalized eigenvectors of T.

*Proof.* Let  $n := \dim(V)$ . By strong induction on n.

<u>Base case</u>: n = 1. Then every nonzero vector is an eigenvector of *T*.

Inductive step: Suppose  $n \ge 2$  and the result holds for all k < n. Since  $\mathbb{F} = \mathbb{C}$ , then there exists an eigenvalue  $\lambda$  of *T*. Recall then that

$$V = \ker(T - \lambda I)^n \oplus \operatorname{img}(T - \lambda I)^n$$

Case 1: ker $(T - \lambda I)^n = V$ . Then every nonzero vector in V is a generalized eigenvector of *T*, so the result holds.

<u>Case 2</u>: ker $(T - \lambda I)^n \neq V$ . Then img $(T - \lambda I)^n \neq \{0\}$ . Since  $\lambda$  is an eigenvalue of T, then dim $(\ker(T - \lambda I)^n) > 1$ . Thus

$$0 < \dim(\operatorname{img}(T - \lambda I)^n) < n.$$

Let  $U := img(T - \lambda I)^n$ . Then U is a nonzero T-invariant subspace of dimension < n. By the inductive hypothesis applied to the restriction  $T|_{U}$ , there is a basis of U consisting of generalized eigenvectors of  $T|_U$ . Adjoin this basis to a basis of ker $(T - \lambda I)^n$ . Since

$$V = \ker(T - \lambda I)^n \oplus \operatorname{img}(T - \lambda I)^n$$

then the result is a basis of V consisting of generalized eigenvectors of T.

**Lemma 14.** Suppose  $T \in \mathcal{L}(V)$ . Then each generalized eigenvector of T corresponds to a unique eigenvalue of T.

Proof. Exercise.

**Proposition 15.** Suppose  $T \in \mathcal{L}(V)$ . Then every list of generalized eigenvectors of T corresponding to distinct eigenvalues is linearly independent.

*Proof.* Exercise. Similar to the proof for eigenvectors.

II.4.3. Nilpotent operators.

**Definition 16.** An operator  $T \in \mathcal{L}(V)$  is *nilpotent* if  $T^m = 0$  for some  $m \in \mathbb{Z}_{\geq 0}$ . **Example 17.** Let  $V = \mathbb{F}^2$ . The operator  $T := L_A$  with

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

is nilpotent.

**Proposition 18.** Suppose  $T \in \mathcal{L}(V)$  is nilpotent. Then  $minpoly(T) = z^m$  for some  $m \leq \dim(V)$ .

*Proof.* Since *T* is nilpotent, then  $T^k = 0$  for some  $k \in \mathbb{Z}_{\geq 0}$ . Then minpoly(*T*) divides  $z^k$  so  $z^k = \text{minpoly}(T)f(z)$ 

for some  $f \in \mathcal{P}(\mathbb{F})$ . By unique factorization, then minpoly $(T) = z^m$  for some  $m \in \mathbb{Z}_{\geq 0}$ . Moreover, we know that deg(minpoly(T))  $\leq \dim(V)$ , so  $m \leq \dim(V)$ .

**Proposition 19.** Let  $n := \dim(V)$  and suppose  $T \in \mathcal{L}(V)$  is nilpotent. Then  $T^n = 0$ .

*Proof.* By the above, minpoly(T) =  $z^m$  for some  $m \le n$ . Then

$$T^n = T^{n-m}T^m = T^{n-m} \circ 0 = 0.$$

**Proposition 20.** Suppose  $T \in \mathcal{L}(V)$ .

- (a) If T is nilpotent, then 0 is an eigenvalue of T and T has no other eigenvalues.
- (b) If  $\mathbb{F} = \mathbb{C}$  and 0 is the only eigenvalue of *T*, then *T* is nilpotent.
- *Proof.* (a) By the previous proposition, minpoly $(T) = T^m$  for some m. The eigenvalues of T are exactly the roots of minpoly(T).
  - (b) Since  $\mathbb{F} = \mathbb{C}$ , then minpoly(*T*) splits into degree 1 factors. Then minpoly(*T*) =  $z^m$  for some  $m \in \mathbb{Z}_{>0}$ , so  $T^m = 0$ .

**Proposition 21.** Suppose  $T \in \mathcal{L}(V)$ . TFAE.

(*a*) *T* is nilpotent.

(b) minpoly(T) =  $z^m$  for some  $m \in \mathbb{Z}_{>0}$ .

(c) There is a basis  $\mathcal{B}$  of V such that

$$[T]_{\mathcal{B}} = \begin{pmatrix} 0 & & * \\ \vdots & \ddots & \\ 0 & \cdots & 0 \end{pmatrix}$$

where all entries on and below the diagonal are 0.

*Proof.* (a)  $\implies$  (b): Already done.

(b)  $\implies$  (c): Since minpoly(T) =  $z^m$  splits into degree 1 factors, then there is a basis  $\mathcal{B}$  of V such that  $[T]_{\mathcal{B}}$  is upper triangular. Its diagonal entries are exactly the eigenvalues of T, namely 0, so we obtain a matrix of the desired form.

(c)  $\implies$  (a): A direct calculation shows that  $([T]_{\mathcal{B}})^n = 0.$