

**18.700 - LINEAR ALGEBRA, DAY 10**  
**INVARIANT SUBSPACES AND EIGENVECTORS**

SAM SCHIAVONE

CONTENTS

I. Pre-class Planning	1
I.1. Goals for lesson	1
I.2. Methods of assessment	1
I.3. Materials to bring	1
II. Lesson Plan	2
II.1. Last time	2
II.2. Summary of Ch. 4 of Axler	5
II.3. 5A: Invariant subspaces and Eigenvectors	5

I. PRE-CLASS PLANNING

**I.1. Goals for lesson.**

- (1) Students will learn that if  $\dim(V) = n$  and  $\dim(W) = m$ , then  $\mathcal{L}(V, W) \cong M_{m \times n}(\mathbb{F})$ .
- (2) Students will learn that  $[T(v)]_{\mathcal{C}} = \mathcal{C}[T]_{\mathcal{B}}[v]_{\mathcal{B}}$ .
- (3) Students will learn the change of basis formula.
- (4) Students will learn the definition of invariant subspace, eigenvalue, and eigenvector

**I.2. Methods of assessment.**

- (1) Student responses to questions posed during lecture
- (2) Student responses to worksheet

**I.3. Materials to bring.** (1) Laptop + adapter (2) Worksheets

(0:00)

## II. LESSON PLAN

Announcements: • Exam 1: Wednesday in class. No pset this week; instead review packet. • TA review session: Tuesday, 7:00 - 9:00pm, 2-361

### II.1. Last time.

- Defined matrix multiplication.
- Gave several interpretations of matrix multiplication.
- Row rank = column rank of a matrix.
- Defined invertibility and isomorphism.
- Proved results on invertibility. (Invertible  $\iff$  bijective, case of  $\dim(V) = \dim(W)$ .)

**Definition 1.** Let  $X$  and  $Y$  be sets. A function  $f : X \rightarrow Y$  is *bijective* (or a *bijection*) if it is both injective and surjective.

**Remark 2.** Suppose  $T \in \mathcal{L}(V, W)$ . The result that, when  $\dim(V) = \dim(W)$ , then  $T$  invertible  $\iff T$  one-to-one  $\iff T$  onto is similar to a result about finite sets.

**Lemma 3.** Suppose  $X$  and  $Y$  are finite sets such that  $\#X = \#Y$ , and  $f : X \rightarrow Y$  is a function. TFAE.

- (i)  $f$  is bijective.
- (ii)  $f$  is injective.
- (iii)  $f$  is surjective.

#### II.1.1. Isomorphic vector spaces, continued.

**Theorem 4** (Dimension determines isomorphism). *Two finite-dimensional vector spaces over  $\mathbb{F}$  are isomorphic iff they have the same dimension.*

*Proof.* Suppose  $V$  and  $W$  are finite-dimensional vector spaces.

( $\Rightarrow$ ): Assume  $V$  and  $W$  are isomorphic. Then there exists an isomorphism  $T : V \rightarrow W$ . Then  $T$  is injective and surjective so

$$\ker(T) = \{0\} \quad \text{and} \quad \text{img}(T) = W.$$

By Rank-Nullity, then [ask students]

$$\dim(V) = \dim(\ker(T)) + \dim(\text{img}(T)) = \dim(W).$$

( $\Leftarrow$ ): Assume  $\dim(V) = \dim(W)$ . Let  $v_1, \dots, v_n$  be a basis for  $V$  and  $w_1, \dots, w_n$  be a basis for  $W$ . By a previous result, there is a unique linear map  $T : V \rightarrow W$  such that  $T(v_i) = w_i$  for all  $i = 1, \dots, n$ . Since  $w_1, \dots, w_n$  span  $W$ , then  $T$  is surjective. Either by Rank-Nullity, or by using the fact that  $w_1, \dots, w_n$  are linearly independent,  $T$  is injective. (Details left as exercise.) Thus  $T$  is injective and surjective, hence an isomorphism.  $\square$

**Corollary 5.** *Let  $V$  be an  $n$ -dimensional vector space. Then  $V$  is isomorphic to  $\mathbb{F}^n$ .*

*Proof.* Both have dimension  $n$ .  $\square$

**Remark 6.** We can also give an explicit isomorphism. Choose a basis  $\mathcal{B} = (v_1, \dots, v_n)$  for  $V$  and consider the coordinate vector map

$$\begin{aligned} \varphi_{\mathcal{B}} : V &\rightarrow \mathbb{F}^n \\ v &\mapsto [v]_{\mathcal{B}} \end{aligned}$$

and the linear map

$$\begin{aligned} S : \mathbb{F}^n &\rightarrow V \\ (a_1, \dots, a_n) &\mapsto a_1 v_1 + \dots + a_n v_n. \end{aligned}$$

Exercise: show these maps are mutually inverse isomorphisms.

**Example 7.**  $\mathcal{P}_m(\mathbb{F})$  has dimension [ask students]  $m + 1$ , hence is isomorphic to  $\mathbb{F}^{m+1}$ .

**Proposition 8.** Suppose  $\mathcal{B} := (v_1, \dots, v_n)$  is a basis of  $V$  and  $\mathcal{C} := (w_1, \dots, w_m)$  is a basis of  $W$  (so  $\dim(V) = n$  and  $\dim(W) = m$ ). Then the map

$$\begin{aligned} \mathcal{L}(V, W) &\rightarrow M_{m \times n}(\mathbb{F}) \\ T &\mapsto c[T]_{\mathcal{B}} \end{aligned}$$

is an isomorphism.

*Proof.* Exercise. (Similar to previous result.) □

**Corollary 9.** Suppose  $V$  and  $W$  are finite-dimensional. Then  $\dim(\mathcal{L}(V, W)) = \dim(V) \dim(W)$ .

II.1.2. Linear maps as matrices.

**Proposition 10** (Multiplication by a matrix is linear). Let  $A \in M_{m \times n}(\mathbb{F})$ . The left multiplication map

$$\begin{aligned} L_A : \mathbb{F}^n &\rightarrow \mathbb{F}^m \\ v &\mapsto Av \end{aligned}$$

is linear.

*Proof.* Considering  $v$  as an  $n \times 1$  matrix, this follows by properties of matrix multiplication. □

Let  $V$  and  $W$  be vector spaces with bases  $\mathcal{B} := (v_1, \dots, v_n)$  and  $\mathcal{C} := (w_1, \dots, w_m)$ , respectively. Recall, for  $T : V \rightarrow W$  linear, the matrix of  $T$  with respect to  $\mathcal{B}$  and  $\mathcal{C}$  is given by

$$c[T]_{\mathcal{B}} = \left( \begin{array}{ccc} | & & | \\ [T(v_1)]_{\mathcal{C}} & \cdots & [T(v_n)]_{\mathcal{C}} \\ | & & | \end{array} \right)$$

**Proposition 11.** With notation as above,

$$[T(v)]_{\mathcal{C}} = c[T]_{\mathcal{B}}[v]_{\mathcal{B}}$$

for all  $v \in V$ .

*Proof.* Given  $v \in V$ , there exist unique scalars  $a_1, \dots, a_n \in \mathbb{F}$  such that  $v = a_1v_1 + \dots + a_nv_n$ . Since  $T$  is linear, then

$$T(v) = T(a_1v_1 + \dots + a_nv_n) = a_1T(v_1) + \dots + a_nT(v_n).$$

Since the coordinate vector map is linear, then

$$\begin{aligned} [T(v)]_{\mathcal{C}} &= [a_1T(v_1) + \dots + a_nT(v_n)]_{\mathcal{C}} = a_1[T(v_1)]_{\mathcal{C}} + \dots + a_n[T(v_n)]_{\mathcal{C}} \\ &= \begin{pmatrix} | & & | \\ [T(v_1)]_{\mathcal{C}} & \cdots & [T(v_n)]_{\mathcal{C}} \\ | & & | \end{pmatrix} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = {}_{\mathcal{C}}[T]_{\mathcal{B}} [v]_{\mathcal{B}}. \end{aligned}$$

□

The equality  $[T(v)]_{\mathcal{C}} = {}_{\mathcal{C}}[T]_{\mathcal{B}} [v]_{\mathcal{B}}$  can be stated by saying the following diagram “commutes.”

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \varphi_{\mathcal{B}} \downarrow & & \downarrow \varphi_{\mathcal{C}} \\ \mathbb{F}^n & \xrightarrow{{}_{\mathcal{C}}[T]_{\mathcal{B}}} & \mathbb{F}^m \end{array}$$

[Draw image of  $v$  traveling both directions.]

**Proposition 12.** Suppose  $V$  and  $W$  are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then the rank of  $T$  (i.e.,  $\dim(\text{img}(T))$ ) is equal to the (column) rank of  $[T]$ .

*Proof.* Exercise. □

II.1.3. *Change of basis.* Q: How does the matrix  ${}_{\mathcal{C}}[T]_{\mathcal{B}}$  change if we change the bases  $\mathcal{B}$  and  $\mathcal{C}$ ?

**Definition 13.** Let  $n \in \mathbb{Z}_{\geq 0}$ . The  $n \times n$  identity matrix  $I$  is the  $n \times n$  matrix with 1s on the diagonal and 0s elsewhere:

$$I = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix}.$$

**Remark 14.** We use  $I$  for both the identity operator and the identity matrix. With respect to any basis, the matrix of the identity operator  $I_V$  is  $I$ .

**Definition 15.** An  $n \times n$  matrix  $A$  is invertible if there is a  $n \times n$  matrix  $B$  such that  $AB = BA = I$ . We call  $B$  the inverse of  $A$  and denote it  $A^{-1}$ .

**Lemma 16.** The inverse of a matrix is unique.

*Proof.* Same as for linear maps. □

**Theorem 17.** Let  $U, V$ , and  $W$  be vector spaces with bases  $\mathcal{B}, \mathcal{C}$ , and  $\mathcal{D}$ , respectively. Given  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$ , then

$${}_{\mathcal{D}}[ST]_{\mathcal{B}} = {}_{\mathcal{D}}[S]_{\mathcal{C}} {}_{\mathcal{C}}[T]_{\mathcal{B}}.$$

*Proof.* Follows by the definition of matrix multiplication. □

**Corollary 18** (Change of basis matrix). *Suppose  $\mathcal{B}$  and  $\mathcal{C}$  are both bases for  $V$ . Then*

$${}_{\mathcal{B}}[I]_{\mathcal{C}} = c[I]_{\mathcal{B}}^{-1}.$$

*Proof.*

$$I = {}_{\mathcal{B}}[I]_{\mathcal{B}} = {}_{\mathcal{B}}[I]_{\mathcal{C}} c[I]_{\mathcal{B}}.$$

□

**Proposition 19** (Change of basis formula). *Suppose  $\mathcal{B}$  and  $\mathcal{C}$  are both bases of  $V$ . Given  $T \in \mathcal{L}(V)$ , let  $A := [T]_{\mathcal{B}}$ ,  $B := [T]_{\mathcal{C}}$ , and  $C = {}_{\mathcal{B}}[I]_{\mathcal{C}}$ . Then*

$$A = CBC^{-1}.$$

*Proof.*

$${}_{\mathcal{B}}[T]_{\mathcal{B}} = {}_{\mathcal{B}}[I]_{\mathcal{C}} c[T]_{\mathcal{C}} c[I]_{\mathcal{B}} = (c[I]_{\mathcal{B}})^{-1} c[T]_{\mathcal{C}} c[I]_{\mathcal{B}}.$$

□

**Definition 20.** Two  $n \times n$  matrices  $A$  and  $B$  are *similar* or *conjugate* if there is an invertible matrix  $P$  such that  $B = PAP^{-1}$ .

**II.2. Summary of Ch. 4 of Axler.** Let  $p \in \mathcal{P}(\mathbb{F})$  be a polynomial.

- There is a division algorithm for polynomials.
- If  $p(r) = 0$  for some  $r \in \mathbb{F}$ , then there exists  $q \in \mathcal{P}(\mathbb{F})$  such that  $p(z) = (z - r)q(z)$ .
- A degree  $m$  polynomial has at most  $m$  roots in  $\mathbb{F}$ .
- The fundamental theorem of algebra: A degree  $m$  polynomial in  $\mathcal{P}(\mathbb{C})$  has exactly  $m$  roots in  $\mathbb{C}$ . Equivalently, every polynomial in  $\mathcal{P}(\mathbb{C})$  splits into linear factors:

$$p(z) = c(z - r_1) \cdots (z - r_m)$$

for some  $c, r_1, \dots, r_m \in \mathbb{C}$ .

- Every polynomial in  $\mathcal{P}(\mathbb{R})$  splits into factors of degree at most 2.

**II.3. 5A: Invariant subspaces and Eigenvectors.** Throughout this section, let  $V$  be a vector space over  $\mathbb{F}$ . Recall that a *linear operator* is a linear map  $T : V \rightarrow V$ , i.e., from a vector space to itself.

**Definition 21.** Let  $T \in \mathcal{L}(V)$ . A subspace  $U$  of  $V$  is *stable* or *invariant under  $T$*  (or  $T$ -stable or  $T$ -invariant) if  $T(u) \in U$  for all  $u \in U$ .

**Remark 22.** If  $U$  is  $T$ -invariant, then the restriction  $T|_U : U \rightarrow U$  is well-defined, and is a linear operator on  $U$ .

**Example 23.** Let  $T \in \mathcal{L}(\mathcal{P}(\mathbb{R}))$  be the differentiation operator  $T(f) = f'$ . Then  $\mathcal{P}_4(\mathbb{R})$  is  $T$ -stable: if  $\deg(f) \leq 4$ , then  $\deg(f') = \deg(f) - 1 \leq 4$ . Similarly,  $\mathcal{P}_m(\mathbb{R})$  is  $T$ -stable for every  $m \in \mathbb{Z}_{\geq 0}$ .

**Lemma 24.** Let  $T \in \mathcal{L}(V)$ . Then  $\{0\}$ ,  $V$ ,  $\ker(T)$ , and  $\text{img}(T)$  are all  $T$ -invariant.

**Remark 25.** These are not necessarily all distinct!

*Proof.* Exercise. □

Q: Does every linear operator have an invariant subspace other than  $\{0\}$  and  $V$ ?

We'll see later that the answer is yes for  $\mathbb{F} = \mathbb{C}$  if  $\dim(V) \geq 2$ , and yes for  $\mathbb{F} = \mathbb{R}$  if  $\dim(V) \geq 3$ .

Let's first consider 1-dimensional invariant subspaces. Given  $v \in V$  with  $v \neq 0$ , let [ask students]

$$U := \text{span}(v) = \{\lambda v : \lambda \in \mathbb{F}\}.$$

If  $U$  is  $T$ -invariant, then in particular,  $T(v) \in U$ , so  $T(v) = \lambda v$  for some  $\lambda \in \mathbb{F}$ . Conversely, if  $T(v) = \lambda v$  for some  $\lambda \in \mathbb{F}$ , then  $\text{span}(v)$  is  $T$ -invariant.

**Definition 26.** Let  $T \in \mathcal{L}(V)$ . A scalar  $\lambda \in \mathbb{F}$  is an *eigenvalue* of  $T$  if there exists  $v \in V$  with  $v \neq 0$  such that  $T(v) = \lambda v$ . Such a  $v$  is called an *eigenvector* corresponding to  $\lambda$ .

**Remark 27.** • "eigen-" means "self" or "own".

- We require that  $v \neq 0$  because  $T(0) = \lambda 0$  for all  $\lambda \in \mathbb{F}$ .

[Show gif depicting eigenvectors in  $\mathbb{R}^2$ .]

**Theorem 28.** Suppose  $V$  is finite-dimensional,  $T \in \mathcal{L}(V)$ , and  $\lambda \in \mathbb{F}$ . TFAE.

- $\lambda$  is an eigenvalue of  $T$ .
- $T - \lambda I$  is not injective.
- $T - \lambda I$  is not surjective.
- $T - \lambda I$  is not invertible.

*Proof.* (a)  $\implies$  (b): Assume  $\lambda$  is an eigenvalue of  $T$  with corresponding eigenvector  $v \neq 0$ , so  $T(v) = \lambda v$ . Then

$$0 = T(v) - \lambda v = (T - \lambda I)(v)$$

so  $0 \neq v \in \ker(T)$ . Thus  $T$  is not one-to-one.

(b)  $\implies$  (a): Assume  $T - \lambda I$  is not injective. Then  $\ker(T - \lambda I) \neq \{0\}$  so there exists  $0 \neq v \in \ker(T - \lambda I)$ . Then

$$0 = (T - \lambda I)(v) = T(v) - \lambda v \implies T(v) = \lambda v$$

so  $v$  is an eigenvector with eigenvalue  $\lambda$ .

We previously showed the equivalence of (b), (c), and (d). □

**Proposition 29.** Let  $T \in \mathcal{L}(V)$ . Suppose that  $\lambda_1, \dots, \lambda_k$  are distinct eigenvalues of  $T$  with corresponding eigenvectors  $v_1, \dots, v_k$ . Then  $v_1, \dots, v_k$  are linearly independent.

*Proof.* We proceed by induction on  $k$ , the number of eigenvalues.

Base case:  $k = 1$ . An eigenvector is nonzero by definition, so the list  $v_1$  is linearly independent by a previous homework problem.

Inductive step: Assume the result holds for  $k - 1$  and assume  $T$  has  $k$  distinct eigenvalues. Suppose that

$$a_1 v_1 + \dots + a_k v_k = 0 \tag{30}$$

for some  $a_1, \dots, a_k \in \mathbb{F}$ . Goal:  $a_i = 0$  for all  $i$ . Note that

$$(T - \lambda_k I)(v_i) = T(v_i) - \lambda_k v_i = \lambda_i v_i - \lambda_k v_i = (\lambda_i - \lambda_k)v_i$$

for all  $i = 1, \dots, k$ . Applying  $T - \lambda_k I$  to (30), we find

$$\begin{aligned} 0 &= (T - \lambda_k I)(a_1 v_1 + \dots + a_m v_m) \\ &= a_1(\lambda_1 - \lambda_k)v_1 + \dots + a_{k-1}(\lambda_{k-1} - \lambda_k)v_{k-1} + a_k(\lambda_k - \lambda_k)v_k. \end{aligned}$$

Since  $v_1, \dots, v_{k-1}$  are linearly independent by the inductive hypothesis, then  $a_i(\lambda_i - \lambda_k) = 0$  for all  $i = 1, \dots, k-1$ . Since the  $\lambda_i$  are distinct, then  $a_i = 0$  for all  $i = 1, \dots, k-1$ . Then (30) becomes

$$a_k v_k = 0.$$

But  $v_k$  is an eigenvector, hence is nonzero, so  $a_k = 0$  by the base case. □

**Corollary 31.** *If  $V$  is finite-dimensional, then every operator  $T \in \mathcal{L}(V)$  has at most  $\dim(V)$  distinct eigenvalues.*

*Proof.* Apply the previous result and  $\text{LI} \leq \text{span}$ . □

II.3.1. *Polynomials applied to linear operators.* Given a linear operator  $T : V \rightarrow V$ , then we can compose  $T$  with itself:  $T \circ T = T^2$ . We similarly define

$$T^m = \begin{cases} \overbrace{T \cdots T}^{m \text{ times}} & \text{if } m > 0; \\ I & \text{if } m = 0; \\ (T^{-1})^{|m|} & \text{if } m < 0 \text{ and } T \text{ is invertible.} \end{cases}$$

**Lemma 32.**

- $T^m T^n = T^{m+n}$
- $(T^m)^n = T^{mn}$

*Proof.* Exercise. □

**Definition 33.** Given  $T \in \mathcal{L}(V)$ , and  $p \in \mathcal{P}(\mathbb{F})$  with

$$p(z) = a_0 + a_1 z + \dots + a_m z^m,$$

define the operator  $p(T) \in \mathcal{L}(V)$  by

$$p(T) := a_0 I + a_1 T + \dots + a_m T^m.$$

**Definition 34.** Let  $p, q \in \mathcal{P}(\mathbb{F})$ . Their product  $pq$  is defined pointwise:

$$(pq)(z) := p(z)q(z)$$

for all  $z \in \mathbb{F}$ .

Note that multiplication of polynomials is commutative. The same is true when we apply polynomials to linear operators.

**Lemma 35.**

- (i)  $(pq)(T) = p(T)q(T)$ ;
- (ii)  $p(T)q(T) = q(T)p(T)$ .

*Proof.* Exercise. □

**Lemma 36.** *Let  $T \in \mathcal{L}(V)$  and  $p \in \mathcal{P}(\mathbb{F})$ . Then  $\ker(T)$  and  $\text{img}(T)$  are  $T$ -invariant.*

*Proof.* Exercise. □