18.600: Lecture 31 Lectures 19-30 Review

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Continuous random variables

Problems motivated by coin tossing

Random variable properties

CLE plus weak/strong laws

Markov chains

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- ▶ Probability of interval [a, b] is given by $\int_a^b f(x) dx$, the area under f between a and b.
- Probability of any single point is zero.
- Define cumulative distribution function $F(a) = F_X(a) := P\{X < a\} = P\{X \le a\} = \int_{-\infty}^a f(x) dx.$

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This formula is often useful for calculations.

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- Gamma distribution: time till *n*th event in λ Poisson point process.

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- Minimum of independent exponentials with parameters λ₁ and λ₂ is itself exponential with parameter λ₁ + λ₂.

DeMoivre-Laplace limit theorem (special case of central limit theorem):

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This is Φ(b) − Φ(a) = P{a ≤ X ≤ b} when X is a standard normal random variable.

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- Here $\sqrt{npq} = \sqrt{60000 \times \frac{1}{6} \times \frac{5}{6}} \approx 91.28$.
- And $200/91.28 \approx 2.19$. Answer is about $1 \Phi(-2.19)$.

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- Values: $\Phi(-3) \approx .0013$, $\Phi(-2) \approx .023$ and $\Phi(-1) \approx .159$.
- Rule of thumb: "two thirds of time within one SD of mean, 95 percent of time within 2 SDs of mean."

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- Formula $P\{X > a\} = e^{-\lambda a}$ is very important in practice.
- Repeated integration by parts gives $E[X^n] = n!/\lambda^n$.
- If λ = 1, then E[Xⁿ] = n!. Value Γ(n) := E[Xⁿ⁻¹] defined for real n > 0 and Γ(n) = (n − 1)!.

Say that random variable X has gamma distribution with parameters
$$(\alpha, \lambda)$$
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- Waiting time interpretation makes sense only for integer α, but distribution is defined for general positive α.

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function
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- Answer: note that $Y \le 27$ if and only if $X \le 3$. Hence $P\{Y \le 27\} = P\{X \le 3\} = F_X(3)$.

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This is a general principle. If X is a continuous random variable and g is a strictly increasing function of x and Y = g(X), then F_Y(a) = F_X(g⁻¹(a)).

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- In general, when X and Y are jointly defined discrete random variables, we write p(x, y) = p_{X,Y}(x, y) = P{X = x, Y = y}.

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• Density:
$$f(x, y) = \frac{\partial}{\partial x} \frac{\partial}{\partial y} F(x, y)$$
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$$P\{X + Y \le a\} = \int_{-\infty}^{\infty} \int_{-\infty}^{a-y} f_X(x) f_Y(y) dx dy$$
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• Differentiating both sides gives $f_{X+Y}(a) = \frac{d}{da} \int_{-\infty}^{\infty} F_X(a-y) f_Y(y) dy = \int_{-\infty}^{\infty} f_X(a-y) f_Y(y) dy.$

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- Latter formula makes some intuitive sense. We're integrating over the set of x, y pairs that add up to a.

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- This amounts to restricting f(x, y) to the line corresponding to the given y value (and dividing by the constant that makes the integral along that line equal to 1).

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• Answer:
$$F_X(a) = \begin{cases} 0 & a < 0 \\ a^n & a \in [0, 1]. \\ 1 & a > 1 \end{cases}$$

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- Answer: $f(x_1, x_2, \ldots, x_n) = n! \prod_{i=1}^n f(x_i)$ if $x_1 < x_2 \ldots < x_n$, zero otherwise.

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- So $E[X] = E[g(Y)] = \int_0^1 g(y) dy$, which is indeed the area under the graph of $1 F_X$.

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- Since $f(x, y) = f_X(x)f_Y(y)$ this factors as $\int_{-\infty}^{\infty} h(y)f_Y(y)dy \int_{-\infty}^{\infty} g(x)f_X(x)dx = E[h(Y)]E[g(X)].$

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- Converse is not true.

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Special case:

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- We do something similar when X and Y are continuous random variables. In that case we write $f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$.
- Often useful to think of sampling (X, Y) as a two-stage process. First sample Y from its marginal distribution, obtain Y = y for some particular y. Then sample X from its probability distribution given Y = y.

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- ► In continuum setting we had $f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$. So $E[X|Y = y] = \int_{-\infty}^{\infty} x \frac{f(x,y)}{f_Y(y)} dx$

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- Above fact breaks variance into two parts, corresponding to these two stages.

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- Can we check the formula Var(Z) = Var(E[Z|X]) + E[Var(Z|X)] in this case?

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- In other words, adding independent random variables corresponds to multiplying moment generating functions.

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- Turns out that $E[X] = \frac{a}{a+b}$ and the mode of X is $\frac{(a-1)}{(a-1)+(b-1)}$.

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- Central limit theorem:

$$\lim_{n\to\infty} P\{a\leq B_n\leq b\}\to \Phi(b)-\Phi(a).$$



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- Example: as n tends to infinity, the probability of seeing more than .50001n heads in n fair coin tosses tends to zero.

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- ► The strong law of large numbers states that with probability one $\lim_{n\to\infty} A_n = \mu$.
- It is called "strong" because it implies the weak law of large numbers. But it takes a bit of thought to see why this is the case.

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Precisely,

 $P\{X_{n+1}=j|X_n=i,X_{n-1}=i_{n-1},\ldots,X_1=i_1,X_0=i_0\}=P_{ij}.$

Kind of an "almost memoryless" property. Probability distribution for next state depends only on the current state (and not on the rest of the state history). ► To describe a Markov chain, we need to define P_{ij} for any $i, j \in \{0, 1, ..., M\}$.

Matrix representation

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- It is convenient to represent the collection of transition probabilities P_{ij} as a matrix:

$$A = \begin{pmatrix} P_{00} & P_{01} & \dots & P_{0M} \\ P_{10} & P_{11} & \dots & P_{1M} \\ \vdots & & & \\ \vdots & & & \\ P_{M0} & P_{M1} & \dots & P_{MM} \end{pmatrix}$$

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For this to make sense, we require $P_{ij} \ge 0$ for all i, j and $\sum_{j=0}^{M} P_{ij} = 1$ for each i. That is, the rows sum to one.

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- Turns out that if chain has this property, then π_j := lim_{n→∞} P⁽ⁿ⁾_{ij} exists and the π_j are the unique non-negative solutions of π_j = Σ^M_{k=0} π_kP_{kj} that sum to one.

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- This means that the row vector

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- One can solve the system of linear equations
 π_j = Σ^M_{k=0} π_kP_{kj} to compute the values π_j. Equivalent to
 considering A fixed and solving πA = π. Or solving
 (A − I)π = 0. This determines π up to a multiplicative
 constant, and fact that Σ π_j = 1 determines the constant.