

18.175: Lecture 22

Ergodic theory

Scott Sheffield

MIT

Setup

Birkhoff's ergodic theorem

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- ▶ We don't have independence. We have translation invariance instead. Is that good enough?
- ▶ More general: C_x distributed in *some* translation invariant way, $EC_0 < \infty$. Is mean of C_x (on large box) nearly constant?

Rephrasing problem

- ▶ Let θ_x be the translation of the \mathbb{Z}^2 that moves 0 to x . Each θ_x induces a measure-preserving translation of Ω . Then $C_x(\omega) = C_0(\theta_{-x}(\omega))$. So summing up the C_x values is the same as summing up the $C_0(\theta_x(\omega))$ value over a range of x .

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- ▶ Let's simplify matters still further and consider the one-dimensional problem. In this case, we have a random variable X and we study empirical averages of the form

$$N^{-1} \sum_{n=1}^N X(\phi^n \omega).$$

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- ▶ If X_0, X_1, \dots is stationary and $g : \mathbb{R}^{\{0,1,\dots\}} \rightarrow \mathbb{R}$ is measurable, then $Y_k = g(X_k, X_{k+1}, \dots)$ is stationary.

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- ▶ Can construct two-sided (\mathbb{Z} -indexed) stationary sequence from one-sided stationary sequence by Kolmogorov extension.
- ▶ What if X_j are i.i.d. tosses of a p -coin, where p is itself random?

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- ▶ Observe: class \mathcal{I} of invariant events is a σ -field.
- ▶ Measure preserving transformation is called **ergodic** if \mathcal{I} is trivial, i.e., every set $A \in \mathcal{I}$ satisfies $P(A) \in \{0, 1\}$.
- ▶ **Example:** If $\Omega = \mathbb{R}^{\{0,1,\dots\}}$ and A is invariant, then A is necessarily in tail σ -field \mathcal{T} , hence has probability zero or one by Kolmogorov's 0 – 1 law. So sequence is ergodic (the shift on sequence space $\mathbb{R}^{\{0,1,2,\dots\}}$ is ergodic..

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- ▶ Note: if sequence is ergodic, then $E(X|\mathcal{I}) = E(X)$, so the limit is just the mean.
- ▶ Proof takes a couple of pages. Shall we work through it?