

§ 4.3 Vector fields & differential forms on mfd's.

Defⁿ Let X be a mfd. A vector field on X , written as $v \in \mathfrak{X}(X)$, is a function which assigns to each $p \in X$ an element $v(p) \in T_p X$.

A k -form ω is a function which assigns to each $p \in X$ an element $\omega(p) \in \Lambda^k(T_p^* X)$. ($C^\infty \Rightarrow \Omega^k(X)$)

Let X, Y be mfd's, $f: X \rightarrow Y$ a C^∞ -mapping.

Defⁿ (A) Given $v \in \mathfrak{X}(X), \omega \in \mathfrak{X}(Y)$, they are called f -related iff $\forall p \in X$, we have $(df)_p v(p) = \omega(f(p))$.

The vector field defined by $(f_* v)$

For f being a diffeomorphism, $\omega(q) = (df)_{f^{-1}(q)} v(f^{-1}(q))$,

we write $\omega = f_* v \Rightarrow$ push forward.

The reversed direction: $(f^*)^* \omega$ is called pullback.

(B) Given $\omega \in \Omega^k(Y)$, its pullback $f^* \omega \in \Omega^k(X)$ is defined by

$$(f^* \omega)_p := (df)_p^* (\omega_{f(p)}).$$

Propⁿ Given mfd's X, Y, Z and $X \xrightarrow{f} Y \xrightarrow{g} Z$ C^∞ -mappings,

for $\omega \in \Omega^k(Z)$, we have $(g \circ f)^* \omega = f^*(g^* \omega)$

If f, g are diffeomorphisms, then for $v \in \mathfrak{X}(X)$,

we have $(g \circ f)_* (v) = g_* (f_* (v))$.

proof Reduced to open subsets in \mathbb{R}^n . \square

Defⁿ $X \Rightarrow n$ -dim mfd, $U \subseteq X$ open is called parametrizable

if $\exists U_0 \subseteq \mathbb{R}^n$ open & $\phi_0: U_0 \xrightarrow{\cong} U$ diffeomorphism

Defⁿ A k -form ω on X is called smooth if $\phi_0^* \omega$ is smooth.

Lemma Smoothness is well-defined.

proof Given $U_0 \xrightarrow{\phi_0} U$, then map $\psi := \phi_1^{-1} \circ \phi_0$ is a diffeomorphism.

$$\begin{array}{ccc} U_0 & \xrightarrow{\phi_0} & U \\ \phi_1^{-1} \circ \phi_0 \downarrow & \nearrow \phi_1 & \\ U_1 & & \end{array} \Rightarrow \phi_0^* \omega \text{ is } C^\infty$$

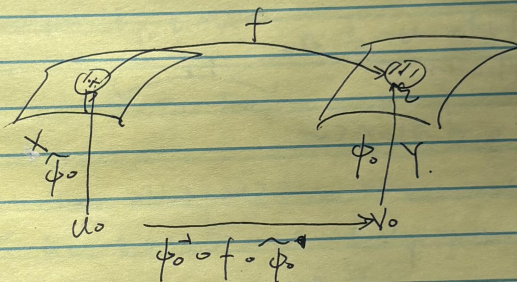
So, $\phi_0^* \omega = (\phi_1 \circ \phi_1^{-1} \circ \phi_0)^* \omega = (\phi_1^{-1} \circ \phi_0)^* \phi_1^* \omega$ iff $\phi_1^* \omega$ is C^∞ . \square

Defⁿ A vector field v on X is C^∞ iff ϕ^*v is $C^\infty \Rightarrow$ well-defined.

Defⁿ A k -form ω on X is C^∞ iff $\forall p \in X, \exists$ neighborhood of p on which ω is C^∞ . Similar for vector fields.

Propⁿ Given $\omega \in \Omega^k(Y)$, $f^*\omega$ is also C^∞ if f is smooth.

proof



Choose parametrizable open neighborhoods as above $\Rightarrow \phi_0^{-1} \circ f \circ \phi_0$ is C^∞ .

This shows that $\phi_0^* f^* \omega$

$$\begin{aligned} \phi_0^* f^* \omega &= \tilde{\phi}_0^* f^* (\phi_0^{-1})^* \phi_0^* \omega \\ &= (\phi_0^{-1} \circ f \circ \phi_0)^* \phi_0^* \omega \text{ is } C^\infty. \quad \square \end{aligned}$$

Emk If $f: X \rightarrow Y$ is a diffeomorphism, & v is a C^∞ -vector field on X , f_*v is also C^∞ . \square

The following are the analogues of statements over \mathbb{R}^n .

• support: $\left\{ \begin{array}{l} \text{for } \omega \in \Omega^k(X), \text{ supp}(\omega) := \{p \in X \mid \omega(p) \neq 0\} \\ \text{for } v \in \mathfrak{X}(X), \text{ supp}(v) := \overline{\{p \in X \mid v(p) \neq 0\}} \end{array} \right.$

• integral curve: $I \subseteq \mathbb{R}$ open interval, $\gamma: I \rightarrow X$ C^∞ curve.

Let $\vec{u} := (t_0, 1) \in T_{t_0}\mathbb{R}$ be the unit vector.

For $v \in \mathfrak{X}(X)$, \vec{v} is called an integral curve iff

$$d\gamma_{t_0}(\vec{u}) = v_{\gamma(t_0)} \in T_{\gamma(t_0)}X.$$

Propⁿ If $v \in \mathfrak{X}(X), w \in \mathfrak{X}(Y)$ are f -related, then an integral curve γ of v is mapped to an integral curve of w , $f \circ \gamma$.

proof $d(f \circ \gamma)_{t_0}(\vec{u}) = (df)_{\gamma(t_0)}(d\gamma)_{t_0}(\vec{u}) = (df)_{\gamma(t_0)}(v_{\gamma(t_0)}) = w_{f(\gamma(t_0))}$

Propⁿ Local existence: For a vector field $v \in \mathcal{X}(X)$,
 Given a parametrizable $U \subseteq X$, we have

(1) Local existence: $\forall p \in U, \exists$ an integral curve $\sigma(t)$ of v defined for $t \in (-\epsilon, \epsilon)$ for some $\epsilon > 0$, and $\sigma(0) = p$

(2) Local uniqueness:
 $\sigma_1: I_1 \rightarrow U$
 $\sigma_2: I_2 \rightarrow U$ integral curves
 $w. \sigma_1|_{I_1 \cap I_2} = \sigma_2|_{I_1 \cap I_2}$
 $\Rightarrow \sigma_1 \cup \sigma_2|_{I_1 \cup I_2}$ is also an integral curve.

(3) $\forall p \in U, \exists$ open nbhd $p \in U \subseteq U$ and $\epsilon > 0$ and $h: (-\epsilon, \epsilon) \times 0 \rightarrow U$ s.t. $\forall p \in U, \sigma_p(t) := h(t, p)$ is an integral curve s.t. $\sigma_p(0) = p$ all time.

proof Follows from the discussion in \mathbb{R}^n . \square

Recall v is called complete if $\forall p \in X \exists$ an integral curve $\sigma(t) = p$ which exists in all time.

Thm If X is compact, or more generally, $\text{supp}(v)$ is compact, then v is complete.

proof Suppose $\text{supp}(v)$ is compact.

Given $p \in X$, by local existence, $\exists \epsilon > 0$ s.t. we can find an integral curve $\sigma: (-\epsilon, \epsilon) \rightarrow X$ s.t. $\sigma(0) = p$.

Because $\text{supp}(v)$ is compact, we know that $\forall \{x_k\}_{k \in \mathbb{N}}$ s.t. $x_k \xrightarrow{k \rightarrow \infty} \pm \epsilon$, the set $\{\sigma(x_k)\}_{k \in \mathbb{N}}$ is bounded, also Cauchy in X .

By comparing arbitrarily two sequences, we can uniquely extend σ to a continuous map $\sigma: [-\epsilon, \epsilon] \rightarrow X$.

Using local existence again, at $\sigma(\pm \epsilon)$, we can extend σ to find integral curves $\sigma_1: (-\epsilon - \delta_1, \epsilon + \delta_1) \rightarrow X$
 $\sigma_2: (-\epsilon - \delta_2, \epsilon + \delta_2) \rightarrow X$.

Then the union $\sigma_1 \cup \sigma \cup \sigma_2$ is continuous, actually C^1 (thus C^∞ by ODE theory), so we have extended the solution to a bigger interval.

This implies that the solution exists for all time. \square

Thm $f \in \mathcal{X}(M) \Rightarrow 1$ parameter group of diffeomorphisms.

Def: (Exterior derivative)

$\phi_0: U_0 \rightarrow U \subseteq X$ parametrization

Given $\omega \in \Omega^k(U)$, define

$$d\omega := (\phi_0^{-1})^* d(\phi_0^* \omega)$$

Lemma: This is well-defined.

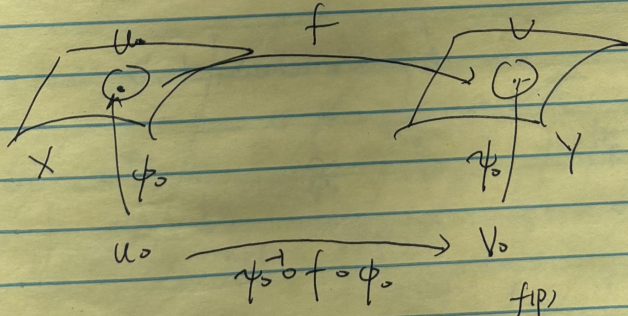
proof: For $U_0 \xrightarrow{\phi_0} U$
 $\phi_1^{-1} \phi_0 \downarrow \nearrow \phi_1$
 $U_1 \xrightarrow{\phi_1} U$

$$\begin{aligned} \text{we have } & (\phi_0^{-1})^* d(\phi_0^* \omega) \\ &= (\phi_1^{-1})^* \cdot (\phi_0^{-1} \phi_1)^* d(\phi_0^* \omega) \\ &= (\phi_1^{-1})^* d((\phi_1^* \phi_0^{-1})^* \phi_0^* \omega) \\ &= (\phi_1^{-1})^* d(\phi_1^* \omega) \quad \square \end{aligned}$$

Globally, we defined $d\omega$ on parametrizable open nbhd's of points.

Thm: Given $f: X \rightarrow Y$ (C^∞) and $\omega \in \Omega^k(Y)$, we have
 $f^*(d\omega) = d(f^*\omega)$

proof:



Choose parametrizable open nbhd's of $p \in U_0, q \in V_0$ w.l. $f(U_0) \subseteq V_0$,

$$\begin{aligned} f^*(d\omega) &= f^*((\psi_0^{-1})^* d\psi_0^* \omega) \\ &= (\phi_0^{-1})^* \phi_0^* f^* (\psi_0^{-1})^* d\psi_0^* \omega \\ &= (\phi_0^{-1})^* d\phi_0^* f^* (\psi_0^{-1})^* \psi_0^* \omega = (\phi_0^{-1})^* d\phi_0^* f^* \omega \\ &= d(f^* \omega) \quad \square \end{aligned}$$

Finally, one can define the interior product
in ω via local parametrization,
and we have:

Thm (Cartan's formula). $L_{\omega} \omega = d\iota_{\omega} \omega + \iota_{\omega} d\omega$,

where $L_{\omega} \omega = \frac{d}{dt} \Big|_{t=0} f_t^* \omega$ where f_t is the one-parameter group
associated w/ ω .