

**18.155 LECTURE 8**  
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Read: Chater 3 Section 6.

I have some loose ends to tie up:

**Lemma 1.** *If  $\phi \in \mathcal{S}(\mathbb{R}^n)$  and  $\partial^\alpha \phi(0) = 0$  for all  $|\alpha| \leq N$  then for  $\chi \in \mathcal{C}_c^\infty(\mathbb{R}^n)$ ,*

$$(1) \quad \|\phi\chi(n\cdot)\|_N \rightarrow 0 \text{ as } n \rightarrow \infty, \quad \|\psi\|_N = \sup_{x, |\alpha|+|\beta| \leq N} |x^\beta \partial^\alpha \psi(x)|.$$

**Proposition 1.** *If  $u \in \mathcal{S}'(\mathbb{R}^n)$  and  $\text{supp}(u) \subset \{0\}$  then*

$$(2) \quad u = \sum_{|\alpha| \leq N} c_\alpha \partial^\alpha \delta_0$$

for some  $N$  and constants  $c_\alpha$ .

I will sneak in a discussion of linear transformations which prepares the way for later treatment of the coordinate-invariance of distributions and is useful here. Observe that if  $L \in \text{GL}(n, \mathbb{R})$  is an invertible  $n \times n$  (real) matrix, so  $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$  and for functions  $v : \mathbb{R}^n \rightarrow \mathbb{C}$  we define (as usual)  $L^*v = v \circ L$  then  $L^* : \mathcal{S}(\mathbb{R}^n) \rightarrow \mathcal{S}(\mathbb{R}^n)$  and by change-of-variable

$$(3) \quad \int (L^*\phi)(x)\psi(x)dx = \int \phi(y)(L^{-1})^*\psi(y)|\det L|^{-1}dy.$$

This means that – reverting to our formal embedding  $\mathcal{S}(\mathbb{R}^n) \ni \phi \mapsto U_\phi \in \mathcal{S}'(\mathbb{R}^n)$

$$(4) \quad U_{L^*\phi}(\psi) = \int (L^*\phi)\psi = U_\phi(|\det L|^{-1}(L^{-1})^*\psi)$$

so we are obliged by demands of consistency (and weak density) to *define*

$$(5) \quad (L^*u)(\psi) = u(|\det L|^{-1}(L^{-1})^*\psi) \quad \forall u \in \mathcal{S}'(\mathbb{R}^n) \implies \\ L^* : \mathcal{S}'(\mathbb{R}^n) \longrightarrow \mathcal{S}'(\mathbb{R}^n) \text{ is a bijection.}$$

Notice that this definition does not make sense if  $L$  is not invertible, however  $(L^{-1})^* = (L^*)^{-1}$  as one would want!

Why do I introduce this now? One reason it is very useful to think about *homogeneity* – simple behaviour under scaling of the coordinates. Let  $M_t x = tx$  for  $t > 0$ , be the corresponding linear transformation. Then from the definition above, for  $u \in \mathcal{S}'(\mathbb{R}^n)$ , becomes

$$(6) \quad (M_t^*u)(\psi) = u(t^{-n}\psi(\cdot/t))$$

and this is (the only possible definition) consistent with scaling of functions.

Observe that  $|x|^{-n+s}$ ,  $s > 0$ , is a locally integrable function on  $\mathbb{R}^n$  which defines a tempered distribution and which is indeed homogeneous of degree  $-n + s$  : If

$u = |x|^{-n+s} \in \mathcal{S}'(\mathbb{R}^n)$  then

$$(7) \quad (M_t^* u)(\psi) = t^{-n} u(\psi(\cdot/t)) = t^{-n} \int |x|^{-n+s} \psi\left(\frac{x}{t}\right) dx \\ = \int |x|^{-n+s} \psi\left(\frac{x}{t}\right) d(x/t) = \int |ty|^{-n+s} \psi(y) dy = t^{-n+s} u(\psi) \\ \text{that is } M_t^* u = t^{-n+s} u, \quad u = |x|^{-n+s}.$$

So we say an element  $u \in \mathcal{S}'(\mathbb{R}^n)$  is homogeneous of degree  $z$  for any  $z \in \mathbb{C}$  if

$$(8) \quad M_t^* u = t^z u, \text{ i.e. } u(\psi(\cdot/t)) = t^{z+n} u(\psi) \quad \forall t > 0, \quad \psi \in \mathcal{S}(\mathbb{R}^n).$$

We have shown that  $|x|^{-n+s}$  is homogeneous of degree  $-n+s$ . You might like to check that this remains meaningful, and correct, if  $s \in \mathbb{C}$ ,  $\operatorname{Re} s > 0$ . It does not make sense directly if  $\operatorname{Re} s \leq 0$  because  $|x|^{-n+s}$  is not then locally integrable across the origin.

**Lemma 2.** *If  $u \in \mathcal{S}'(\mathbb{R}^n)$  is homogeneous of degree  $z \in \mathbb{C}$  then  $x^\beta \partial^\alpha u$  is homogeneous of degree  $s + |\beta| - |\alpha|$ .*

**Lemma 3.** *The distribution  $\partial^\alpha \delta_0$  is homogeneous of degree  $-n - |\alpha|$ .*

**Proposition 2.** *For appropriate constants  $c_n$ ,  $E_n = c_n |x|^{-n+2}$  ( $n > 2$ ),  $E_2 = c_2 \log |x|$ , is a fundamental solution of  $\Delta = -\sum_i \partial_i^2$ .*

*Proof.* I leave it to you in the next homework (not due until Oct 13) to compute the constants  $c_n$ . □

Another important example of fundamental solutions is of the Cauchy-Riemann operator

$$(9) \quad \bar{\partial} = (\partial_x + i\partial_y) \text{ on } \mathbb{R}^2 = \mathbb{C}$$

where a factor of a ‘half’ is often included. Most of the elementary aspects of the theory of one complex variable can be deduced from the fact that

**Lemma 4.**  *$E = \frac{1}{2\pi}(x + iy)^{-1}$  is a fundamental solution of  $\bar{\partial}$ .*

*Proof.* You can get this in various ways. One, relating to Dirac operators (that I hope to get to a bit later) is to use the fundamental solution for  $\Delta$  when  $n = 2$  discussed above and the identity

$$(10) \quad \Delta_2 = (\partial_x + i\partial_y)(\partial_x - i\partial_y) \implies E = (\partial_x - i\partial_y)E_2$$

must be a fundamental solution for  $\bar{\partial}$ . □

Next we start to consider *ellipticity* of a differential operator with constant coefficients  $P(D)$  (remember  $D_i = \frac{1}{i}\partial_i$ ) or equivalently of its ‘characteristic polynomial’  $P(\xi)$ .

See the notes starting around Definition 6.11.