

**Accurate and Efficient Matrix Computations
with Generalized Vandermonde Matrices
using Schur Functions**

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Vandermonde Matrices

- TP Vandermonde Matrix:

$$V = \begin{bmatrix} 1 & x_1 & \dots & x_1^{n-1} \\ 1 & x_2 & \dots & x_2^{n-1} \\ & & \ddots & \\ 1 & x_n & \dots & x_n^{n-1} \end{bmatrix},$$

where $x_1 > x_2 > \dots > x_n > 0$.

- TP Generalized Vandermonde Matrix:

$$G_\lambda = \begin{bmatrix} x_1^{\lambda_1} & x_1^{1+\lambda_2} & \dots & x_1^{n-1+\lambda_n} \\ x_2^{\lambda_1} & x_2^{1+\lambda_2} & \dots & x_2^{n-1+\lambda_n} \\ & & \ddots & \\ x_n^{\lambda_1} & x_n^{1+\lambda_2} & \dots & x_n^{n-1+\lambda_n} \end{bmatrix},$$

where

- $x_1 > x_2 > \dots > x_n > 0$
- $\lambda_n \geq \lambda_{n-1} \geq \dots \geq \lambda_0$

- Notoriously illconditioned

GOALS

Given a matrix A , compute to high relative accuracy in poly time:

- $\det(A)$
 - not trivial even for tridiagonals
- A^{-1}
- Solve $Ax = b$
- LU from GENP, GEPP, GECP
- SVD

Model of Arithmetic: $1 + \delta$

- $\text{fl}(a \otimes b) = (a \otimes b)(1 + \delta)$
- **Unbounded Exponents**
- **Expressions we can compute without losing relative accuracy:**
 - Products and quotients
 - Sums of positive quantities
 - $x_i \pm x_j$, where x_i and x_j are initial data
- **Proof:** $1 + \delta$ factors can be factored out
- We will compute everything using allowable expressions

Statement of Results

- Can compute G^{-1} accurately for certain generalized Vandermondes in $O(n^3)$ time
- $\det(G)$ in $O(n^2)$ time
- LU of G from GENP, GEPP in $O(n^3)$ time, but who cares...
- Can solve $Gx = b$ with “Björck-Pereyra accuracy”, but speed $O(n^3)$, not $O(n^2)$

Type of Matrix	$\det(A)$	A^{-1}	Any minor	GENP / GENP	GECP	SVD
Cauchy	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n^3)$	$O(n^3)$	$O(n^3)$
Vandermonde	$O(n^2)$	NONE	NONE	NONE	NONE	$O(n^3)$
Totally Positive (TP) Vandermonde	$O(n^2)$	$O(n^3)$	EXP	$O(n^3)$	EXP	$O(n^3)$
TP Generalized Vandermonde, $ \lambda = \lambda_1 + O(1)$	$O(\lambda_1 n^2)$	$O(\lambda_1 n^3)$	EXP	$O(\lambda_1 n^3)$	EXP	EXP
TP Generalized Vandermonde, any λ	$f(n, \lambda)$	EXP	EXP	EXP	EXP	EXP

$$f(n, \lambda) = O(n^{1+\log \lambda_1+\log \lambda_2+\dots+\log \lambda_n}) \text{ vs. } O(n^{|\lambda|}) = O(n^{\lambda_1+\lambda_2+\dots+\lambda_n})$$

(Symmetrica)

Known Results - Björck-Pereyra Methods

$$V^{-1} = \begin{bmatrix} 1 & x_1 & \dots & x_1^{n-1} \\ 1 & x_2 & \dots & x_2^{n-1} \\ & & \ddots & \\ 1 & x_n & \dots & x_n^{n-1} \end{bmatrix}^{-1} = \begin{bmatrix} 1 & -x_1 & & \\ & 1 & -x_1 & \\ & & 1 & -x_1 \\ & & & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & & & \\ & 1 & -x_2 & \\ & & 1 & -x_2 \\ & & & 1 \end{bmatrix} \cdots \begin{bmatrix} 1 & & & \\ & 1 & -x_{n-1} & \\ & & 1 & -x_{n-1} \\ & & & 1 \end{bmatrix} \\
 \cdot \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & -\frac{1}{x_n-x_1} & \frac{1}{x_n-x_1} \end{bmatrix} \cdots \begin{bmatrix} 1 & & & \\ & -\frac{1}{x_2-x_1} & \frac{1}{x_2-x_1} & \\ & & -\frac{1}{x_3-x_2} & \frac{1}{x_3-x_2} \\ & & & -\frac{1}{x_n-x_{n-1}} & \frac{1}{x_n-x_{n-1}} \end{bmatrix}$$

- Solving $Vz = b$ extremely accurate if b has “checkerboard pattern”
- Sign pattern result of Total Positivity, so only question is accuracy
- For SOLVING we could assemble V^{-1} and then form $V^{-1}b$ and the accuracy will be the same, but not speed
- Sign pattern of V^{-1} also alternating
- We will use Cramer’s rule to compute inverses of generalized Vandermondes G , to which BP does not apply

- Then we can solve with BP accuracy by forming $G^{-1}b$
- Interesting: Even for V : Cramer's rule for V^{-1} : $5/12n^3$, BP: $2n^3$

TP Vandermonde and Generalized Vandermonde Matrices

$$V = \begin{bmatrix} 1 & x_1 & \dots & x_1^{n-1} \\ 1 & x_2 & \dots & x_2^{n-1} \\ & & \ddots & \\ 1 & x_n & \dots & x_n^{n-1} \end{bmatrix}, \quad G_\lambda = \begin{bmatrix} x_1^{\lambda_1} & x_1^{1+\lambda_2} & \dots & x_1^{n-1+\lambda_n} \\ x_2^{\lambda_1} & x_2^{1+\lambda_2} & \dots & x_2^{n-1+\lambda_n} \\ & & \ddots & \\ x_n^{\lambda_1} & x_n^{1+\lambda_2} & \dots & x_n^{n-1+\lambda_n} \end{bmatrix},$$

where $x_1 > x_2 > \dots > x_n > 0$, $\lambda_n \geq \lambda_{n-1} \geq \dots \geq \lambda_0$

- Def: $\lambda = (\lambda_n, \lambda_{n-1}, \dots, \lambda_0)$ is **partition** of $|\lambda| = \lambda_n + \dots + \lambda_0$
- Def: **Young Diagrams** \equiv partitions:

$$\lambda = (4, 2, 1) = \begin{array}{|c|c|c|c|} \hline & & & \\ \hline & & & \\ \hline & & & \\ \hline \end{array}$$

- Def: **Schur Function** $s_\lambda(x_1, \dots, x_n) = \det(G_\lambda) / \det(V)$.
- Thm: s_λ is a polynomial with positive integer coefficients depending only on λ (MacDonald)

Facts about TP Generalized Vandermonde Matrices

● **Recall:** $\det(G) = \det(V) \cdot s_\lambda(x_1, \dots, x_n)$

● **Example:**

$$\det \begin{pmatrix} 1 & x_1^2 & x_1^4 \\ 1 & x_2^2 & x_2^4 \\ 1 & x_3^2 & x_3^4 \end{pmatrix} = \det \begin{pmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{pmatrix} \cdot (2x_1x_2x_3 + x_1^2x_2 + x_1x_2^2 + x_1^2x_3 + x_1x_3^2 + x_2^2x_3 + x_2x_3^2)$$

● $\det(V) = \prod_{i>j}(x_i - x_j)$ is computable accurately and efficiently

● s_λ computable accurately ($x_i > 0$), question is cost.

● **Theorem:**

$$s_\lambda(x_1, \dots, x_n, y_1, \dots, y_m) = \sum_{\mu < \lambda} s_\mu(x_1, \dots, x_n) s_{\lambda/\mu}(y_1, \dots, y_m)$$

Allows recursive computation and Divide-and-Conquer approach.

- **Example:**

$$s_{(1,1)}(x_1, \dots, x_n) = \sum_{i < j} x_i x_j = (x_1 + \dots + x_n)x_2 + (x_2 + \dots + x_n)x_3 + \dots + x_{n-1}x_n$$

cost: $O(n)$, although $s_{(1,1)}$ has $O(n^2)$ terms.

- **Some s_λ 's are computable accurately and efficiently:**

$$\lambda = (1, 1, 1, \dots, 1) = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \quad \text{and} \quad \lambda = (m, 1, 1, \dots, 1) = \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & & & & \\ \hline \square & & & & \\ \hline \square & & & & \\ \hline \square & & & & \\ \hline \square & & & & \\ \hline \square & & & & \\ \hline \end{array}$$

- **For Cramer's rule on a Vandermonde Matrix we need $(n - 1) \times (n - 1)$ minors:**

$$W_{ij} = \begin{bmatrix} 1 & x_1 & \dots & x_1^{j-2} & x_1^j & \dots & x_1^{n-1} \\ 1 & x_2 & \dots & x_2^{j-2} & x_2^j & \dots & x_2^{n-1} \\ & & \dots & & & \dots & \\ 1 & x_{i-1} & \dots & x_{i-1}^{j-2} & x_{i-1}^j & \dots & x_{i-1}^{n-1} \\ 1 & x_{i+1} & \dots & x_{i+1}^{j-2} & x_{i+1}^j & \dots & x_{i+1}^{n-1} \\ & & \dots & & & \dots & \\ 1 & x_n & \dots & x_n^{j-2} & x_n^j & \dots & x_n^{n-1} \end{bmatrix}$$

- The partition that corresponds to W_{ij} is

$$\lambda = (n-1-(n-2), n-2-(n-3), \dots, j-(j-1), j-2-(j-2), \dots, 1-1, 0) = (1, 1, \dots, 1) = (1^{n-j}).$$

- The same trick applies to some generalized Vandermondes, e.g.

$$G = \begin{bmatrix} 1 & x_1 & x_1^2 & & x_1^{n-2} & x_1^{n-1+m} \\ 1 & x_2 & x_2^2 & \dots & x_2^{n-2} & x_2^{n-1+m} \\ & & & \ddots & & \\ 1 & x_n & x_n^2 & & x_n^{n-2} & x_n^{n-1+m} \end{bmatrix}$$

- Partition of G is $\lambda = (m)$
- Partitions of $(n-1) \times (n-1)$ minors $\lambda = (m, 1, 1, 1, \dots, 1)$
- Cost of inversion: $O(mn^3)$
- Extends to $\lambda = (\lambda_1, \lambda_2, \dots)$ as long as $\lambda_2 + \lambda_3 + \dots$ is small ($O(1)$).
- G^{-1} will have “checkerboard” sign pattern
- Finally, with accurate inverses we can solve accurately

Conclusions

- Can compute accurate determinants and inverses of some Generalized Vandermonde Matrices in $O(n^3)$ time
- Can solve linear systems with these systems to high accuracy

Open Problems

- Inverting Any Generalized Vandermonde
- Accurate bidiagonal decomposition of G^{-1} like BP?
- Totally Positive Matrices in General
- Subtraction-free complexity of evaluating the Schur Function