

MODEL ANSWERS TO HWK #5

1 (i) By the chain rule,

$$\begin{aligned}w_r &= w_x x_r + w_y y_r = w_x \cos \theta + w_y \sin \theta \\w_\theta &= w_x x_\theta + w_y y_\theta = w_x (-r \sin \theta) + w_y (r \cos \theta).\end{aligned}$$

Rewriting these equations in terms of matrices,

$$\begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} w_x \\ w_y \end{pmatrix} = \begin{pmatrix} w_r \\ w_\theta \end{pmatrix}.$$

(ii) By the chain rule,

$$\begin{aligned}w_x &= w_r r_x + w_\theta \theta_x = w_r \left(\frac{x}{\sqrt{x^2 + y^2}} \right) + w_\theta \left(-\frac{y}{x^2 + y^2} \right) \\w_y &= w_r r_y + w_\theta \theta_y = w_r \left(\frac{y}{\sqrt{x^2 + y^2}} \right) + w_\theta \left(\frac{x}{x^2 + y^2} \right).\end{aligned}$$

Rewriting these equations in terms of matrices,

$$\begin{pmatrix} \frac{x}{\sqrt{x^2 + y^2}} & -\frac{y}{x^2 + y^2} \\ \frac{y}{\sqrt{x^2 + y^2}} & \frac{x}{x^2 + y^2} \end{pmatrix} \begin{pmatrix} w_r \\ w_\theta \end{pmatrix} = \begin{pmatrix} w_x \\ w_y \end{pmatrix}.$$

(iii) First we change variables in B from x, y to θ, r . So,

$$B = \begin{pmatrix} \frac{x}{\sqrt{x^2 + y^2}} & -\frac{y}{x^2 + y^2} \\ \frac{y}{\sqrt{x^2 + y^2}} & \frac{x}{x^2 + y^2} \end{pmatrix} = \begin{pmatrix} \frac{r \cos \theta}{r} & -\frac{r \sin \theta}{r^2} \\ \frac{r \sin \theta}{r} & \frac{r \cos \theta}{r^2} \end{pmatrix} = \begin{pmatrix} \cos \theta & -\frac{\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix}.$$

Then we compute,

$$AB = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\frac{\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Since $AB = I$ we know that $B = A^{-1}$.

(iv) We know from the above calculations that

$$B \begin{pmatrix} w_r \\ w_\theta \end{pmatrix} = \begin{pmatrix} \cos \theta & -\frac{\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix} \begin{pmatrix} w_r \\ w_\theta \end{pmatrix} = \begin{pmatrix} w_x \\ w_y \end{pmatrix}.$$

Plugging the values $w_r = 2$, $w_\theta = 10$, $r = 5$, and $\theta = \pi/2$ into the above equation yields

$$\begin{pmatrix} w_x \\ w_y \end{pmatrix} = \begin{pmatrix} 0 & -1/5 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 10 \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \end{pmatrix}.$$

2. Let $\hat{u} = \langle a, b \rangle$ and $\vec{r}(s) = \langle 1/2, 1 \rangle + s\langle a, b \rangle$. Then

$$\left. \frac{df}{ds} \right|_{\hat{u}} = \frac{d}{ds}(f(\vec{r}(s))) = \frac{d}{ds}\left(f\left(\frac{1}{2} + sa, 1 + sb\right)\right) = \nabla f\left(\frac{1}{2}, 1\right) \cdot \langle a, b \rangle.$$

Since $\nabla f(x, y) = \langle 3x^2 - y^2 - 8x + 3 + 2xy, -2xy + x^2 \rangle$, we have

$$\nabla f\left(\frac{1}{2}, 1\right) = \left\langle -\frac{1}{4}, -\frac{3}{4} \right\rangle.$$

Thus,

$$\left. \frac{df}{ds} \right|_{\hat{u}} = \left\langle \frac{-1}{4}, \frac{-3}{4} \right\rangle \cdot \langle a, b \rangle = \left| \left\langle \frac{-1}{4}, \frac{-3}{4} \right\rangle \right| \cos \theta = \frac{\sqrt{5}}{2\sqrt{2}} \cos \theta,$$

where θ is the angle between \hat{u} and $\langle 1/2, 1 \rangle$, and so

$$-\frac{\sqrt{5}}{2\sqrt{2}} \leq \left. \frac{df}{ds} \right|_{\hat{u}} \leq \frac{\sqrt{5}}{2\sqrt{2}}.$$

(i) and (ii) The right inequality is attained if the direction of \hat{u} is the same as $\langle \frac{-1}{4}, \frac{-3}{4} \rangle$, that is, the maximum is achieved in the direction

$$\hat{u}_{\max} = \frac{\sqrt{2}}{\sqrt{5}} \left\langle \frac{-1}{2}, \frac{-3}{2} \right\rangle,$$

in which case the maximum value of the directional derivative $\left. \frac{df}{ds} \right|_{\hat{u}}$ is

$$\left. \frac{df}{ds} \right|_{\hat{u}_{\max}} = \frac{\sqrt{5}}{2\sqrt{2}}.$$

Similarly the minimum value is achieved in the direction

$$\hat{u}_{\min} = -\hat{u}_{\max} = \frac{\sqrt{2}}{\sqrt{5}} \left\langle \frac{1}{2}, \frac{3}{2} \right\rangle,$$

and the minimum value of the directional derivative $\left. \frac{df}{ds} \right|_{\hat{u}}$ is

$$\left. \frac{df}{ds} \right|_{\hat{u}_{\min}} = -\frac{\sqrt{5}}{2\sqrt{2}}.$$

(iii) The directional derivative is 0 in the two directions orthogonal to \hat{u}_{\max} ,

$$\pm \frac{\sqrt{2}}{\sqrt{5}} \left\langle -\frac{3}{2}, \frac{1}{2} \right\rangle$$

3. (i) $\nabla g = \langle 2x, z, y \rangle$ so that at $(2-1, 1)$ we have $\langle 4, 1, -1 \rangle$ and so we want the direction $\hat{u} = -\frac{1}{3\sqrt{2}} \langle 4, 1, -1 \rangle$.

(ii) Let

$$\vec{r}(s) = \langle 2, -1, 1 \rangle + \frac{s}{3\sqrt{2}} \langle -4, -1, 1 \rangle.$$

The magnitude of $\langle 4, 1, -1 \rangle$ is $3\sqrt{2}$. The value of g at $(2, -1, 1)$ is $g(2, -1, 1) = 3$. We want to decrease g by 1, so we want to move a distance $s = \frac{1}{3\sqrt{2}}$, that is, we want the point

$$\vec{r}\left(\frac{1}{3\sqrt{2}}\right) = \langle 2, -1, 1 \rangle + \frac{1}{18} \langle -4, -1, 1 \rangle = \langle 16/9, -19/18, 19/18 \rangle.$$

Note that

$$g\left(\frac{16}{9}, -\frac{19}{18}, \frac{19}{18}\right) = \frac{221}{108} \approx 2.046.$$