## Lectures 9 and 10

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Today, we are going to present how to use semidefinite programming to optimize a linear function over the theta body $T H(G)$ which was discussed in last lecture.

## 1 Semidefinite programming

Let $\mathcal{S}^{n \times n}$ be the set of $n$ by $n$ real symmetric matrices.
Definition $1 A \in \mathcal{S}^{n \times n}$ is called positive semidefinite, denoted $A \succeq 0$, if $x^{T} A x \geq 0$ for any $x \in \mathbb{R}^{n}$.
There are several well-known equivalent ways to state positive semidefiniteness.
Proposition 1 The following are equivalent:
(i) $A$ is positive semidefinite.
(ii) Every eigenvalue of $A$ is nonnegative.
(iii) There is a matrix $V$ such that $A=V^{T} V$.

We define the Frobenius inner product for two matrices $A, B \in \mathcal{S}^{n \times n}$ by

$$
\langle A, B\rangle=\sum_{i, j} A_{i j} B_{i j}=\operatorname{tr}\left(A^{T} B\right)
$$

Typically, semidefinite programs are described as optimization problems of the following form:

$$
\begin{equation*}
\sup \langle C, X\rangle \quad \text { subject to } \quad\left\langle A_{i}, X\right\rangle=b_{i} \text { for } i=1, \ldots, m, X \succeq 0 \tag{1}
\end{equation*}
$$

where $C$ and $A_{i}$ are $n$ by $n$ symmetric matrices and $b_{i}$ are real numbers. Semidefinite programming generalizes linear programming because linear program is a special instance of semidefinite program that all $C, A_{i}$ and $X$ are diagonal matrices.

For the given semidefinite program (1), we define the dual program of it as

$$
\begin{equation*}
\inf \sum_{i=1}^{m} b_{i} y_{i} \quad \text { subject to } \quad \sum_{i=1}^{m} y_{i} A_{i} \succeq C \tag{2}
\end{equation*}
$$

Here we use the convention that $A \succeq B$ if $A-B$ is positive semidefinite.
Theorem 2 (Weak duality) For any feasible solution $X$ for the primal program (1) and a feasible solution $y$ for the dual (2), $\sum_{i=1}^{m} b_{i} y_{i} \geq\langle C, X\rangle$.

To prove the weak duality, we need the following useful lemma.
Lemma 3 Let $A$ and $B$ be $n$ by $n$ positive semidefinite matrices. Let $C=A \circ B$ be an $n$ by $n$ matrix such that $C_{i j}=A_{i j} B_{i j}$. Then $C$ is positive semidefinite. Moreover, $\langle A, B\rangle \geq 0$.

Proof: Note that $\langle A, B\rangle=e^{T} C e$ where $e$ is all-ones vector in $\mathbb{R}^{n}$. So $\langle A, B\rangle \geq 0$ if $C$ is positive semidefinite.

Let $A$ and $B$ be positive semidefinite matrices. By the previous proposition, $A=V^{T} V$ and $B=W^{T} W$ for some matrices $V$ and $W$. Let $v_{i}$ (and $w_{i}$ ) be the $i$-th column of $V$ ( $W$, resp.) for $i=1, \ldots, n$. Let $z_{i}=v_{i} \otimes w_{i}$, where component $(k, l)$ of $z_{i}$ is equal to component $k$ of $v_{i}$ times component $l$ of $w_{i}$. Define $Z$ be the matrix whose columns are $z_{1}, \ldots, z_{n}$. We have $z_{i}^{T} z_{j}=$ $\left(v_{i}^{T} v_{j}\right)\left(w_{i}^{T} w_{j}\right)=A_{i j} B_{i j}=C_{i j}$. Hence $C=Z^{T} Z$ and $C$ is positive semidefinite.

This lemma also implies the result that the positive semidefinite cone is self-dual, i.e. $\langle A, B\rangle \geq 0$ for all $B \succeq 0$ if and only if $A \succeq 0$. (For the only if part, if $A \nsucceq 0$ then any eigenvector $v$ corresponding to a negative eigenvalue satisfies $\left\langle A, v v^{T}\right\rangle \geq 0$.
Proof of Theorem 2: $\quad \sum_{i=1}^{m} b_{i} y_{i}-\langle C, X\rangle=\sum_{i=1}^{m} y_{i}\left\langle A_{i}, X\right\rangle-\langle C, X\rangle=\left\langle X, \sum_{i=1}^{m} y_{i} A_{i}-C\right\rangle \geq 0$ because $X \succeq 0$ and $\sum_{i=1}^{m} y_{i} A_{i}-C \succeq 0$.

In comparison to linear programming, strong duality does not always hold for semidefinite programming. Also, an optimum is not always attained by a feasible solution (which is the reason that we used inf instead of min).

Example 1 Let the primal to be

$$
\sup \left\langle\left(\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & -1
\end{array}\right), X\right\rangle \quad \text { subject to } \quad\left\langle\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{array}\right), X\right\rangle=1,\left\langle\left(\begin{array}{lll}
0 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array}\right), X\right\rangle=0, X \succeq 0
$$

Then dual is

$$
\inf y_{1} \quad \text { subject to } \quad y_{1}\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)+y_{2}\left(\begin{array}{lll}
0 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array}\right) \succeq\left(\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & -1
\end{array}\right) .
$$

This primal-dual pair doesn't satisfy strong duality since the primal has optimum value -1 but dual has the optimum value 0 (and in this case both primal and dual attain their optimum value).

Theorem 4 Strong duality If the dual (primal, resp.) is feasible and the primal (dual, resp.) has a strictly feasible solution, i.e., there is positive definite $X^{(0)}$ with $\left\langle A_{i}, X^{(0)}\right\rangle=b_{i}$ for $i=1, \ldots, m$, then there is no duality gap and dual (primal, resp.) has a feasible solution which attains the minimum.

We will prove strong duality next time.

## 2 Theta body

Let $G=(V, E)$ be a graph, and $w: V \rightarrow \mathbb{R}_{\geq 0}$ be weights for vertices. Recall that a collection of unit vectors $\left\{v_{i}\right\}_{i \in V}$ and a unit vector $c$ is called an orthonormal representation of $G$ is $v_{i}^{T} v_{j}=0$ for any $(i, j) \notin E$. The theta body of $G$ is defined as

$$
T H(G)=\left\{x \in \mathbb{R}^{|V|}: \sum_{i \in V}\left(c^{T} u_{i}\right)^{2} x_{i} \leq 1 \text { for all orthonormal rep. of } G\right\}
$$

We define the weighted theta number of $G$ as $\theta(G, w)=\max _{x \in T H(G)} w^{T} x$.

Theorem 5 Let $W \in \mathcal{S}^{n \times n}$ with $W_{i j}=\sqrt{w_{i} w_{j}}$. Then,

$$
\begin{aligned}
\theta(G, w)=\max & \langle W, X\rangle \\
\text { s.t. } & \langle I, X\rangle=1 \\
& \left\langle E_{i j}, X\right\rangle=0 \text { for }(i, j) \in E \\
& X \succeq 0,
\end{aligned}
$$

where $E_{i j}$ is $n$ by $n$ symmetric matrix such that $(i, j)$ and $(j, i)$ entries are 1 but other entries are all zero.

Proof: The dual program of this SDP is

$$
\min t \quad \text { subject to } \quad t I+\sum_{i j \in E} y_{i j} E_{i j} \succeq W
$$

Note that $X=\frac{1}{n} I$ is a strictly feasible solution for primal, and $t>\lambda_{\max }(W)$ and $y_{i j}=0$ gives a strictly feasible solution for dual, where $\lambda_{\max }(W)$ is the maximum eigenvalue of $W$. Hence strong duality holds and there are optimal solutions to both primal and dual.
$(\leq)$ We are going to prove that any feasible solution for dual gives an upper bound of $\theta(G, w)$. Let $(t, y)$ be a feasible solution for the dual. Then $M=t I+\sum_{i j \in E} y_{i j} E_{i j}-W \succeq 0$, so there are vectors $s_{i} \in \mathbb{R}^{n}$ such that $M_{i j}=s_{i}^{T} s_{j}$ for all $i, j \in[n]$. In particular, $s_{i}^{T} s_{i}=t-w_{i}$ and $s_{i}^{T} s_{j}=-\sqrt{w_{i} w_{j}}$ if $(i, j) \notin E$.

Let $c$ be a unit vector orthogonal to all of $s_{i}$ (introduce an extra dimension if needed). Let $u_{i}=\left(\sqrt{w_{i}} c+s_{i}\right) / \sqrt{t}$. Check that $u_{i}^{T} u_{i}=1$ and $u_{i}^{T} u_{j}=0$ if $(i, j) \notin E$. So $c$ and $u_{i}$ is an orthonormal representation of $G$.

For $x \in T H(G)$ such that $w^{T} x=\theta(G, w)$, we have $\sum_{i}\left(c^{T} u_{i}\right)^{2} x_{i} \leq 1$. Since $\left(c^{T} u_{i}\right)^{2}=w_{i} / t$, it implies that $\theta(G, w)=w^{T} x \leq t$.
$(\geq)$ We are going to prove that for each feasible solution $X$ for primal, we can find $x \in T H(G)$ such that $w^{T} x \geq\langle W, X\rangle$. It implies that $\theta(G, w)=\max _{x \in T H(G)} w^{T} x \geq\langle W, X\rangle$.

Let $X$ be a feasible solution for primal. Since $X$ is positive semidefinite, there is a matrix $R$ with $X=R^{T} R$. For each $i=1, \ldots, n$, let $y_{i}=R e_{i}$ where $e_{i}$ is the standard unit vector in which $i$-th coordinate is 1 . Let $v_{i}=\frac{y_{i}}{\left\|y_{i}\right\|}$ and $d=\frac{R \sqrt{w}}{\|R \sqrt{w}\|}$. Here $\sqrt{w}$ is the vector with entries $\sqrt{w_{i}}$. Clearly $v_{i}$ and $d$ are unit vectors, and $v_{i}^{T} v_{j}=\frac{e_{i}^{T} R^{T} R e_{j}}{\left\|y_{i}\right\|\left\|y_{j}\right\|}=0$ for $(i, j) \in E$ since $e_{i}^{T} R^{T} R e_{j}=X_{i j}=0$ if $(i, j) \in E$. It implies that $d$ and $v_{i}$ is an orthonormal representation of $\bar{G}$, the complement of $G$.

Claim 6 Let $d$ and $v_{i}$ be an orthonormal representation of $\bar{G}$. Let $x_{i}=\left(d^{T} v_{i}\right)^{2}$ for each $i \in V$. Then $x \in T H(G)$.

Let $c$ and $u_{i}$ be an orthonormal representation of $G$. We need to show that $\sum_{i}\left(c^{T} u_{i}\right)^{2}\left(d^{T} v_{i}\right)^{2} \leq$ 1. For, let $a_{i}=u_{i} \otimes v_{i}$. Then $a_{i}^{T} a_{i}=\left(u_{i}^{T} u_{i}\right)\left(v_{i}^{T} v_{i}\right)=1$ and $a_{i}^{T} a_{j}=\left(u_{i}^{T} u_{j}\right)\left(v_{i}^{T} v_{j}\right)=0$ since either $u_{i}^{T} u_{j}=0$ (if $(i, j) \notin E$ ) or $v_{i}^{T} v_{j}=0$ (if $(i, j) \in E$ ). Hence the $a_{i}$ 's form an orthonormal set of vectors (not necessarily a basis). On the other hand, $\left\langle c \otimes d, a_{i}\right\rangle=\left(c^{T} u_{i}\right)\left(d^{T} v_{i}\right)$. Hence,

$$
\sum_{i}\left(c^{T} u_{i}\right)^{2}\left(d^{T} v_{i}\right)^{2}=\sum_{i}\left\langle c \otimes d, a_{i}\right\rangle^{2} \leq 1
$$

since the $a_{i}$ 's are orthonormal.
By the claim, we get a point $x \in T H(G)$ from $d$ and $v_{i}$ by letting

$$
x_{i}=\left(d^{T} v_{i}\right)^{2}=\frac{\left(\sqrt{w}^{T} R^{T} R e_{i}\right)^{2}}{\left\|R e_{i}\right\|^{2}\|R \sqrt{w}\|^{2}}
$$

$$
\begin{aligned}
& \left\|R e_{i}\right\|^{2}=e_{i}^{T} R^{T} R e_{i}=X_{i i} \text { and }\|R \sqrt{w}\|^{2}=\sqrt{w}^{T} R^{T} R \sqrt{w}=\langle W, X\rangle \text { so } \\
& \qquad x_{i}=\frac{\left(\sqrt{w}^{T} X e_{i}\right)^{2}}{X_{i i}\langle W, X\rangle}=\frac{1}{X_{i i}\langle W, X\rangle}\left(\sum_{j=1}^{n} \sqrt{w_{j}} X_{i j}\right)^{2}
\end{aligned}
$$

since $W=\sqrt{w} \sqrt{w}^{T}$. Hence

$$
\begin{aligned}
w^{T} x & =\frac{1}{\langle W, X\rangle} \sum_{i=1}^{n} \frac{w_{i}}{X_{i i}}\left(\sum_{j=1}^{n} \sqrt{w_{j}} X_{i j}\right)^{2} \\
& =\frac{1}{\langle W, X\rangle} \sum_{i=1}^{n}\left(\sqrt{X_{i i}}\right)^{2} \cdot \sum_{i=1}^{n}\left(\frac{1}{\sqrt{X_{i i}}} \sum_{j=1}^{n} \sqrt{w_{i} w_{j}} X_{i j}\right)^{2} \\
& \geq \frac{1}{\langle W, X\rangle}\left(\sum_{i=1}^{n} \sum_{j=1}^{n} \sqrt{w_{i} w_{j}} X_{i j}\right)^{2}=\langle W, X\rangle
\end{aligned}
$$

Second equality comes from that $\sum_{i} X_{i i}=\langle I, X\rangle=1$ and third inequality follows from CauchySchwartz.

Now we can compute $\theta(G, w)$ by solving an equivalent semidefinite program (either primal or dual). Modulo some assumptions, semidefinite programs can be approximated within any tolerance in polynomial time. To be a bit more precise, there are interior-point algorithms for SDP that when being given an initial strictly primal feasible solution and an initial strictly dual feasible solution of duality gap $\delta$ will converge to primal and dual solutions of duality gap at most $\epsilon$ in time polynomial in $n$ and in $\log (\Delta / \epsilon)$. In our case, we can take $X_{0}=\frac{1}{n} I$ and $t_{0}>\lambda_{\text {max }}(W)$ for an initial duality gap smaller than $2 w(E) / n$. In particular, we can compute $\alpha(G)$ up to $\epsilon$ in time polynomial in the input size and $\log (1 / \epsilon)$ (and similarly for $\omega(G)=\chi(G)$ ) when $G$ is perfect. Once we can approximate $\alpha(G, w)$ for a perfect graph, we can easily find a stable set of that weight as the problem self-reduces. Indeed, for any $v \in V$, one can check whether $\alpha(G, w)=w_{v}+\alpha(G \backslash(\{v\} \cup N(v)$ and if so include $v$ in the stable set and recurse (and otherwise delete $v$ and recurse).

Finding the coloring (or the clique covering) for a perfect graph is slightly more tricky and was not covered in class.

## 3 Strong Duality for Semidefinite Programming

Strong duality does not always hold for semidefinite programming, although it typically does for combinatorial applications. We'll prove strong duality here as stated in Theorem 4, and explain when it holds and why it sometimes fails.

Suppose we would like to show that there is no primal solution of value $\geq \mu$ for some given $\mu$. This means there is no solution to

$$
\left\{\begin{array}{l}
\langle C, X\rangle+s=\mu \\
\left\langle A_{i}, X\right\rangle=b_{i} \quad \text { for all } i \\
X \succeq 0 \\
s \geq 0
\end{array}\right.
$$

Let us reformulate this differently. Let

$$
C^{\prime}=\left(\begin{array}{cc}
C & 0 \\
0 & -1
\end{array}\right),
$$

$$
A_{i}^{\prime}=\left(\begin{array}{cc}
A_{i} & 0 \\
0 & -1
\end{array}\right)
$$

and

$$
X^{\prime}=\left(\begin{array}{cc}
X & 0 \\
0 & s
\end{array}\right)
$$

Then letting

$$
S=\left\{\left(\left\langle C^{\prime}, X^{\prime}\right\rangle,\left\langle A_{1}^{\prime}, X\right\rangle, \cdots,\left\langle A_{m}^{\prime}, X^{\prime}\right\rangle\right): X^{\prime}=\left(\begin{array}{cc}
X & 0  \tag{3}\\
0 & s
\end{array}\right) \succeq 0\right\}
$$

then no primal solution of value greater or equal to $\mu$ means that $v:=\left(\mu, b_{1}, \cdots, b_{m}\right) \notin S$. At this point, we would like to use the separating hyperplane theorem (see below) to separate $v$ from $S$ since $S$ is a nonempty convex set.

Theorem 7 (Separating hyperplane theorem) Let $S \subset \mathbb{R}^{n}$ be a nonempty, closed, convex set and $v \notin S$. Then there exists $y \in \mathbb{R}^{n}: y^{T} v<y^{T} x$ for all $x \in S$.

However, and here is where the trouble is, the set $S$ given in (3) might not be a closed set. In the case of linear programming, $S$ would be a closed set as it is a linear mapping of a polyhedral set. However, for semidefinite programming, a linear map of the positive semidefinite cone might not be closed. Here is an example.

Example 2 Consider

$$
S=\left\{\left(\left\langle\left(\begin{array}{ll}
0 & 0 \\
0 & 1
\end{array}\right), X\right\rangle,\left\langle\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right), X\right\rangle\right): X \succeq 0\right\}
$$

Observe that $(\epsilon, 2) \in S$ for any $\epsilon>0$ as it corresponds to $X=\left(\begin{array}{cc}1 / \epsilon & 1 \\ 1 & \epsilon\end{array}\right) \succeq 0$. However, $(0,2) \notin S$, showing that $S$ is not closed.

So, in order to use Theorem 7, we need to consider the closure $\bar{S}$ of $S$, where $S$ is given by (3). So, there are 2 possibilities:

1. $v \notin \bar{S}$; in this case, we'll use the separating hyperplane theorem,
2. $v \in \bar{S} \backslash S$; in this case, we will need to show that we can get arbitrarily close to $\mu$ in the primal.

We first consider case 1. By the separating hyperplane theorem, we get a vector $y=\left(y_{0}, \cdots, y_{m}\right)$ such that

$$
\begin{equation*}
y_{0} \mu+\sum_{i=1}^{m} y_{i} b_{i}<y_{0}\left\langle C^{\prime}, X^{\prime}\right\rangle+\sum_{i=1}^{m} y_{i}\left\langle A_{i}^{\prime}, X^{\prime}\right\rangle \tag{4}
\end{equation*}
$$

for all $X^{\prime}=\left(\begin{array}{cc}X & 0 \\ 0 & s\end{array}\right) \succeq 0$. The left-hand-side of (4) must be $<0$ (by considering $X^{\prime}=0$ ), and the right-hand-side must be $\geq 0$ for any $X^{\prime}$ (otherwise we could tak a multiple of $X^{\prime}$ and contradict (4). Thus,

$$
\begin{equation*}
y_{0} \mu+\sum_{i=1}^{m} y_{i} b_{i}<0 \tag{5}
\end{equation*}
$$

and from $\left\langle y_{0} C^{\prime}+\sum_{i=1}^{m} y_{i} A_{i}, X^{\prime}\right\rangle \geq 0$ for all $X^{\prime}=\left(\begin{array}{cc}X & 0 \\ 0 & s\end{array}\right) \succeq 0$, we get $y_{0} \leq 0$ and

$$
\begin{equation*}
y_{0} C+\sum_{i=1}^{m} y_{i} A_{i} \succeq 0 \tag{6}
\end{equation*}
$$

If $y_{0}=0$ then we get that $b^{T} y<0$ and $\sum_{i} y_{i} A_{i} \succeq 0$ which implies that the dual is unbounded (indeed, if $\tilde{y}$ is dual feasible then $\tilde{y}+\lambda y$ is dual feasible for any $\lambda \geq 0$ ) contradicting the fact that the primal is feasible. Thus we must have that $y_{0}<0$. By dividing by $-y_{0}$, we get that $\hat{y}=\frac{1}{-y_{0}} y$ satisfies $\sum_{i} \hat{y}_{i} A_{i} \succeq C$ and $\hat{y}^{T} b<\mu$. Thus we have found a dual solution of value strictly smaller than $\mu$.

In the second case, we assume that $v \in \bar{S} \backslash S$. Thus we have a sequence $v^{(k)} \in S$ such that $v^{(k)} \rightarrow v$. This means that we have a sequence $X^{(k)} \succeq 0$ such that $\left\langle A_{i}, X^{(k)}\right\rangle \rightarrow b_{i}$ for all $i=1, \cdots, m$ and $\left\langle C, X^{(k)}\right\rangle \rightarrow \mu$. But the $A_{i}$ 's can be assumed to be linearly independent (otherwise just get rid of linearly dependent equations) and therefore, there exists $Z_{i}$ for $i=1, \cdots, m$ such that $\left\langle A_{j}, Z_{i}\right\rangle=\delta_{i j}$ (ie. 1 if $i=j$ and 0 otherwise). Now, consider

$$
\hat{X}^{(k)}=X^{(k)}+\sum_{i=1}^{m}\left(b_{i}-\left\langle A_{i}, X^{(k)}\right\rangle\right) Z_{i} .
$$

Observe that $\left\langle A_{i}, \hat{X}^{(k)}\right\rangle=b_{i}$ for all $i$, but of course $X^{(k)} \nsucceq 0$. Still it is close to be, as $X^{(k)}$ is and $b_{i}-\left\langle A_{i}, X^{(k)}\right\rangle \rightarrow 0$ as $k \rightarrow \infty$. We'll finally use the condition that there exists a strictly feasible solution $X^{(0)}$ to the primal. This means that for an appropriate $0<\alpha_{k}<1$, we have that $\bar{X}^{(k)}=\alpha_{k} X^{(0)}+\left(1-\alpha_{k}\right) \hat{X}^{(k)}$ is primal feasible and, after calculations, one can show that we can choose $\alpha_{k}$ such that $\alpha_{k} \rightarrow 0$ as $k \rightarrow \infty$. Thus $\bar{X}^{(k)}$ is primal feasible and its primal value converges to $\mu$.

Summarizing, for any $\mu$, we have one of the following:

- a primal feasible solution of value $\geq \mu$,
- a dual feasible solution of value $<\mu$, or
- a sequence of primal feasible solutions converging to $\mu$.

By choosing $\mu$ to be the infimum in the dual, we see that there is no duality gap. We haven't shown yet that the dual value is attained, but we leave this to the reader.

