

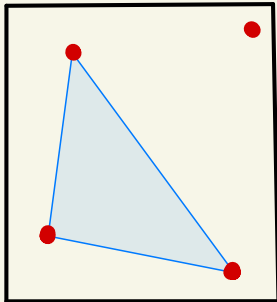
Heilbronn's triangle problem and connections to projection theory

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In any set of n points, there is a triangle of $\text{area} \leq \Delta(n)$

(and $\Delta(n)$ is the smallest number making this true)

Example:

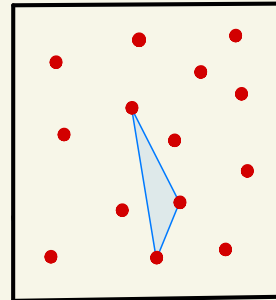


$$\Delta(4) = \frac{1}{2}$$

For any set of 4 pts,
there is a triangle with $\text{area} \leq \frac{1}{2}$

Problem: prove asymptotic upper bounds for

$$\Delta(n) \text{ as } n \rightarrow \infty$$



Find small triangles!

Lower Bounds: Finding sets with no small triangles

• Erdős: $\Delta(n) \gtrsim \frac{1}{n^2}$

- Explicit algebraic construction

• Komlós, Pintz, Szemerédi: $\Delta(n) \gtrsim \frac{\log n}{n^2}$

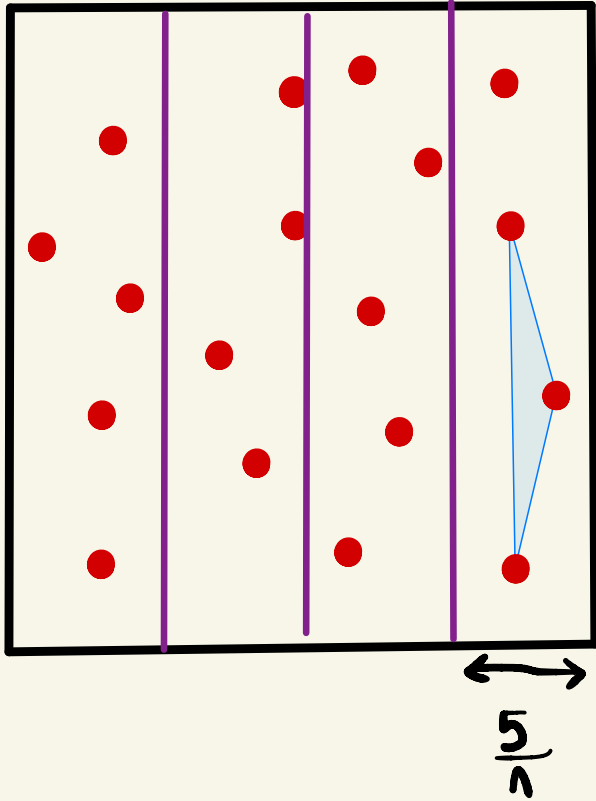
- Semi-random method

- Independence in hypergraph

- Significant combinatorial result

Now back to upper bounds

Observation 1: Trivial bound, $\Delta(n) \leq \frac{5}{n}$

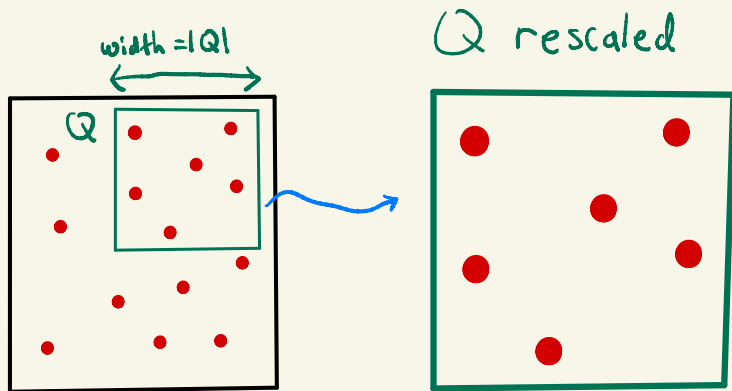


Each strip has area $\frac{5}{n}$

By the pigeonhole principle some strip has ≥ 5 points

First problem: prove $\Delta = o\left(\frac{1}{n}\right)$

Observation 2: Scaling



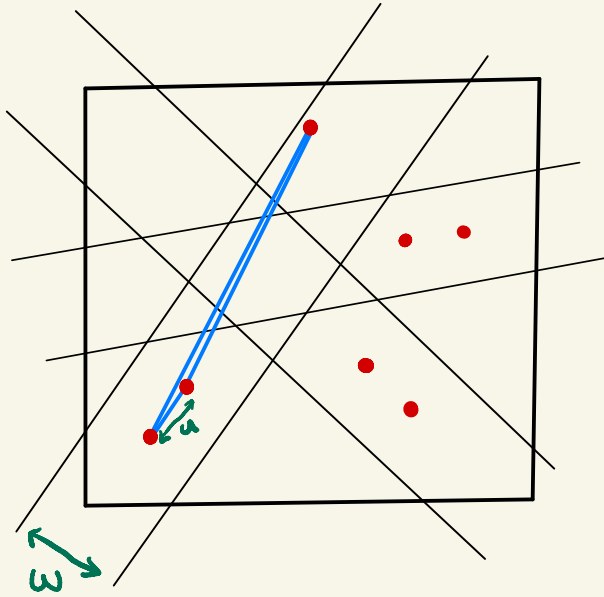
$$\Delta(P) \leq |Q|^2 \cdot \Delta(P \cap Q \text{ rescaled})$$

If points are concentrated in a subsquare, find a small triangle there

To improve on the trivial bound, we can assume P is well spaced

Otherwise, induct into a subsquare

Observation 3: Incidence setup



$$\text{Area} = \text{Base} \times \text{Height}$$

$$\Delta = u \times w$$

- Plan:
- select pairs at distance u
 - form strips of width w
 - find a third point in some strip

Base first, then height

Prior work

KPS = Komlós, Pintz, Szemerédi

- Trivial bound $\Delta \lesssim n^{-1}$
- Roth 1951 $\Delta \lesssim n^{-1} (\log \log n)^{-\frac{1}{2}}$ proof is based on density increment
- Schmidt 1972 $\Delta \lesssim n^{-1} (\log n)^{-\frac{1}{2}}$ proof considers pairs at many different scales

- Roth 1972-73 $\Delta \lesssim n^{-1.1}$ Proof has two steps: initial estimate and inductive step
- KPS 1981 $\Delta \lesssim n^{-8/7}$ Proof extends Roth's approach to its natural limit
- Us 2023 $\Delta \lesssim n^{-\frac{8}{7} - \frac{1}{2000}}$ We break the KPS barrier.

Roth's setup

$$P \subset [0,1]^2$$

$$L = \{ \text{Lines } l \text{ connecting pairs } x, y \in P \text{ with } |x-y| \leq u \}$$

$$\mathcal{T} = \{ \omega\text{-tube around } l : l \in L \} \text{ a set of tubes}$$

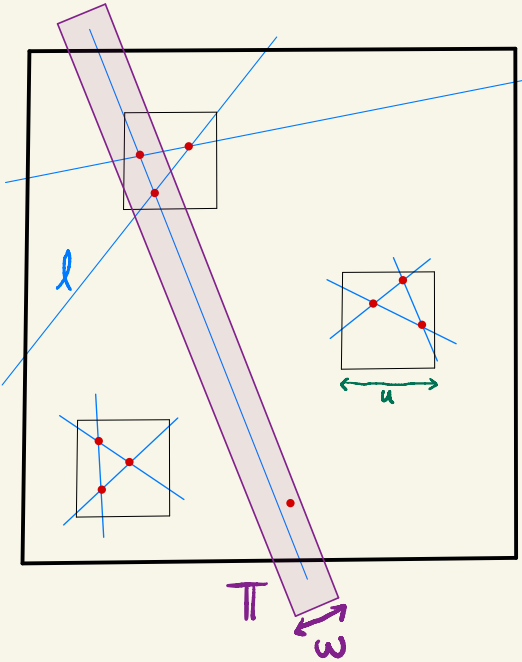
Incidences:

$$\begin{aligned} I(\omega; P, L) &= \# \{ (p, T) \in P \times \mathcal{T} : p \in T \} \\ &= \# \{ (p, l) \in P \times L : d(p, l) \leq \omega/2 \} \end{aligned}$$

$$\text{Goal: } I(\omega_f; P, L) > 2|L|$$

Then a third point in some strip, and $\Delta \leq u \cdot \omega_f$

$$\text{E.g.: } u = n^{-1/3}, \omega_f = n^{-3/4}, \Delta = n^{-13/12}$$



Roth's two steps

$$I(\omega; P, L) = \#\{(p, l) \in P \times L : d(p, l) \leq \omega/2\}$$

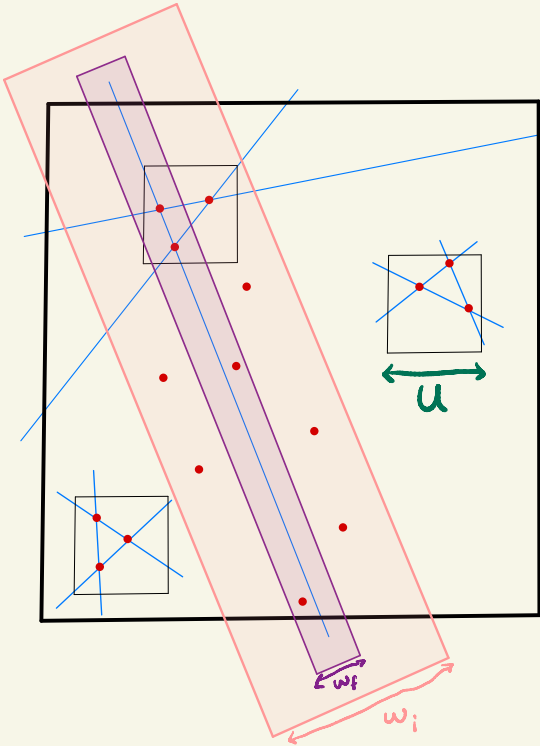
Pick $\omega_f \ll \omega_i$

• **Initial Estimate:** $I(\omega_i) \approx \omega_i |P| |L|$

• **Inductive step:** $\left| \frac{I(\omega_i)}{\omega_i |P| |L|} - \frac{I(\omega_f)}{\omega_f |P| |L|} \right| \ll 1$

Normalized # of incidences doesn't change much as the scale varies

E.g. $u = n^{-1/3}$ $\omega_i = n^{-0.1}$ $\omega_f = n^{-3/4}$ $\Delta = n^{-13/12}$



Main Theorem: $\Delta(n) \lesssim n^{-8/7 - \frac{1}{2000}}$

comes from a 2017 paper of Guth, Solomon, and Wang
Topic in incidence geometry, projection theory, and Fourier analysis

1. Recast Roth's inductive step in terms of the high-low method

- Basically the same as Roth/KPS. But a cool connection.

2. New approach to initial estimate using direction set estimates from projection theory

- Very different from Roth/KPS

- Marstrand 1954 direction set estimate recovers $\Delta \lesssim n^{-8/4}$

- Main ingredient: Use Orponen, Shmerkin, and Wang 2023 direction set estimate in place of Marstrand

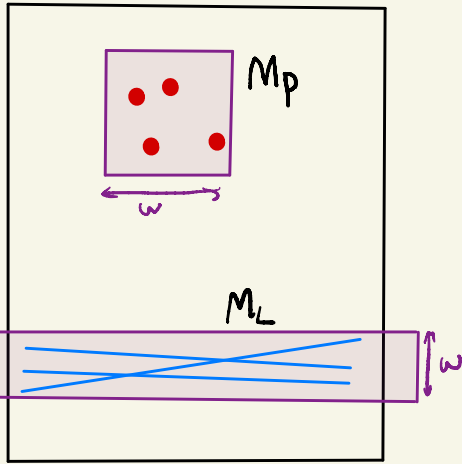
↑ This is the culmination of a line of work based on Bourgain's discretized sum-product theorem

• Roth's 3 papers and KPS use the same initial estimate and refine inductive step

• We improve initial estimate

Inductive step and the high low method

Idea: If P and L are not too concentrated, then $\frac{I(\omega)}{\omega \cdot |P| \cdot |L|} \sim \text{const.}$ as ω varies



$$M_P(\omega \times \omega) = \max |P \cap Q|, \quad Q \text{ a } \omega \times \omega \text{ square}$$

$$M_L(\omega \times 1) = \max |L \cap T|, \quad T \text{ a } \omega\text{-tube}$$

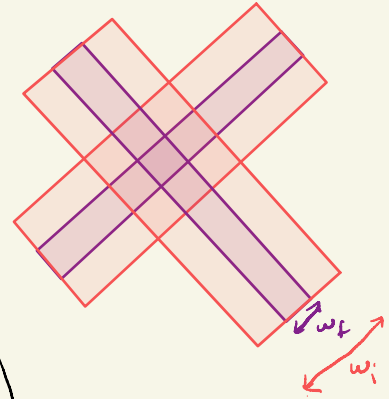
$\omega_f < \omega_i$ Scales

$$\text{Thm: } \left| \frac{I(\omega_i)}{\omega_i \cdot |P| \cdot |L|} - \frac{I(\omega_f)}{\omega_f \cdot |P| \cdot |L|} \right| \lesssim \sqrt{\frac{M_P(\omega_i \times \omega_i)}{|P|} \frac{M_L(\omega_i \times 1)}{|L|} \omega_i^{-3}}$$

GSW: Upper bounds Roth: Lower bounds

High-Low proof

The proof uses **orthogonality**.



$$g = \sum_{p \in P} w_f^2 \mathbb{1}_{B(p, w_f)}, \quad \Phi = \sum_{\ell \in L} \left(\frac{1}{w_i} \mathbb{1}_{T_{w_i}(\ell)} - \frac{1}{w_f} \mathbb{1}_{T_{w_f}(\ell)} \right)$$

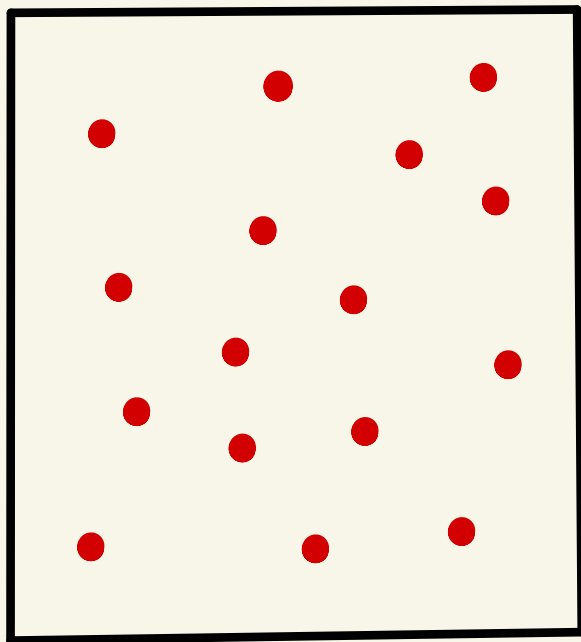
$$\left| \frac{I(w_i)}{w_i |P| |L|} - \frac{I(w_f)}{w_f |P| |L|} \right| = \frac{1}{|P| |L|} |\langle g, \Phi \rangle| \leq \frac{1}{|P| |L|} \|g\|_2 \|\Phi\|_2 \lesssim \sqrt{\frac{M_P(w_i; x_{w_i})}{|P|} \frac{M_L(w_i; x_1)}{|L|} w^{-3}}$$

Estimate $\|\Phi\|_2$ using **orthogonality** between strips

Called high-low method because of **Fourier analysis** interpretation: Split into high & low frequencies

Taking stock of inductive step

High-Low: If P and L are not too concentrated, then $\frac{I(\omega)}{\omega \cdot |P| \cdot |L|} \sim \text{const.}$ as ω varies



- If P is concentrated in a subsquare, induct and find a small triangle there
- If P is not concentrated, use high-low to find small triangles

Initial estimate intuition

• $L_Q = \{\text{lines } l \text{ connecting pairs } x, y \in P \cap Q\}$, $L = \bigcup_Q L_Q$

• Direction set $Q = \left\{ \frac{x-y}{|x-y|} : x, y \in P \cap Q \right\}$

• $\text{Bad}_Q = \{\theta : \omega_i\text{-tube in direction } \theta \text{ has } < \lambda |P \cap Q| \text{ points}\}$
 $\lambda \ll 1$

1. For most Q , $|\text{Bad}_Q| \leq \lambda$ (small)

• What is probability a random pair (Q, θ) is bad?

→ Pick Q then $\theta: \mathbb{E}|\text{Bad}_Q|$

→ Pick θ then $Q: \leq \lambda$

2. Show direction set Q is spread out

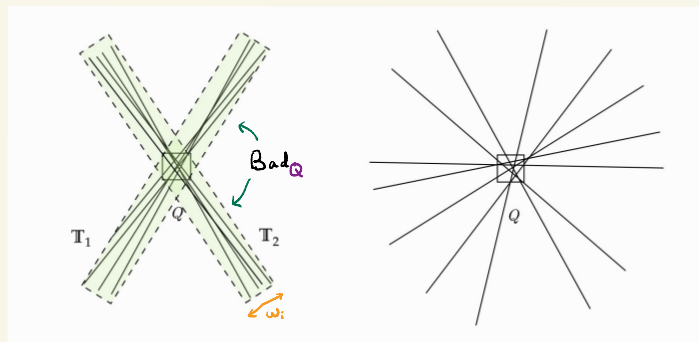
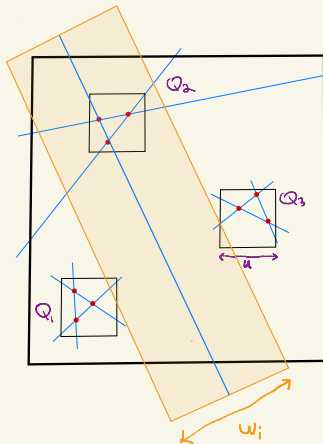
• Projection theory

3. Combine these: • $\#\{l \in L_Q : \theta(l) \in \text{Bad}_Q\} \leq \frac{1}{2} |L_Q|$

• $|T_{\omega_i}(l) \cap P| \approx \omega_i |P|$ for most $l \in L_Q$

• $I(\omega_i; P, L) = \sum_{l \in L} |T_{\omega_i}(l) \cap P| \approx \omega_i |P| |L|$ ✓

Initial Estimate: $I(\omega_i) \approx \omega_i |P| |L|$



lines are concentrated in Bad_Q

Direction set is spread out, so lines are not concentrated in Bad_Q

Direction set estimates from projection theory

Thm (Marstrand 1954): Let $X \subset [0,1]^2$ have Hausdorff dimension $s > 1$.
Then [dimension of direction set] = 1.

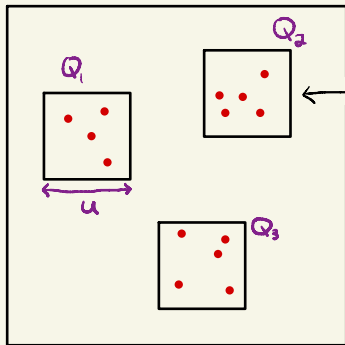
$$\text{direction set} = \left\{ \frac{x-y}{|x-y|} : x, y \in X \right\}$$

• Use discretized version to show line set is spread out

Defn: $P \subset [0,1]^2$ is s -regular above scale δ if

$$|P \cap Q| \leq C |Q|^s |P| \quad \text{for all squares } Q \text{ with } |Q| > \delta.$$

Frostman regular

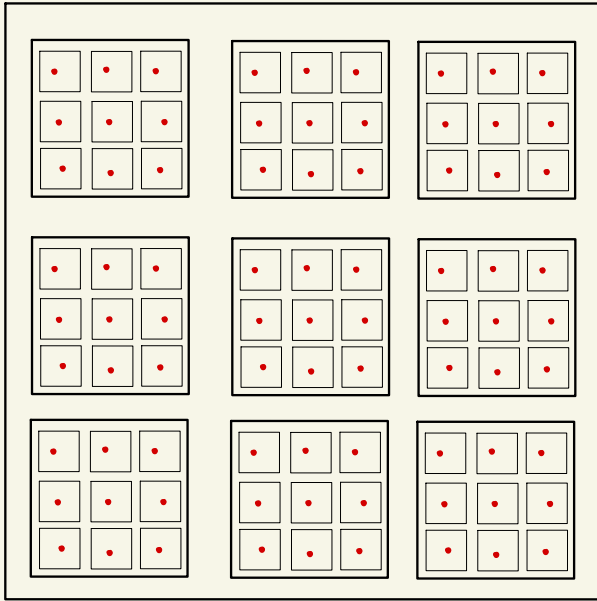


• If $P \cap Q$ is $s > 1$ regular, direction set Q is spread out

$$\#\{l \in L_Q : \theta(l) \in I\} \leq C |I| |L_Q| \quad \text{for all } I \subset S^1 \text{ with } |I| \geq \delta$$

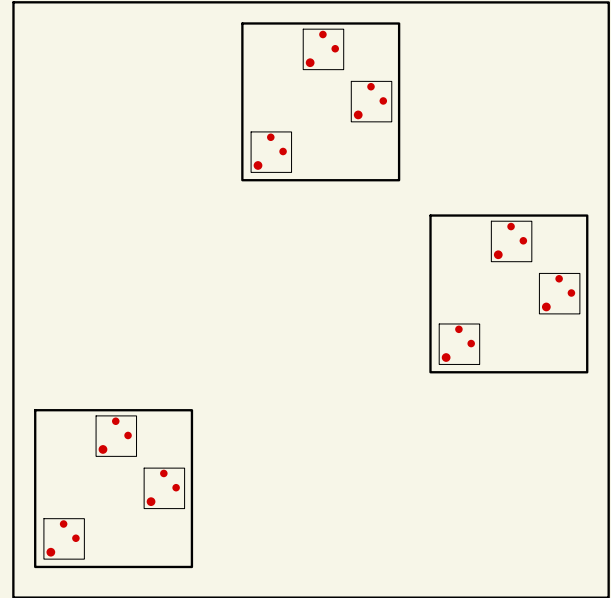
• we get initial estimate

Examples of regular sets



• P is 2-regular

• Marstrand: *direction set* is 1-dim



• P is 1-regular

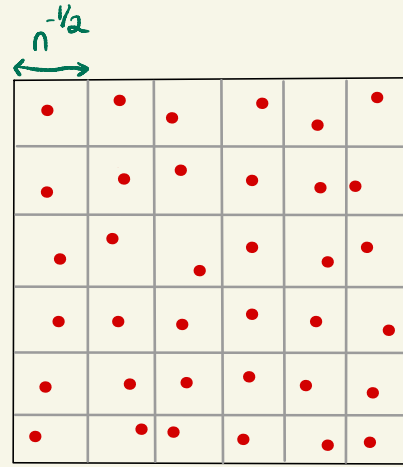
• Marstrand gives *no information* on *direction set*

Taking stock of initial estimate

- First hard case (homogenous):

P is 2-dim down to scale $\delta = n^{-1/2}$, then 1 pt

$$\Delta \approx n^{-7/6}$$

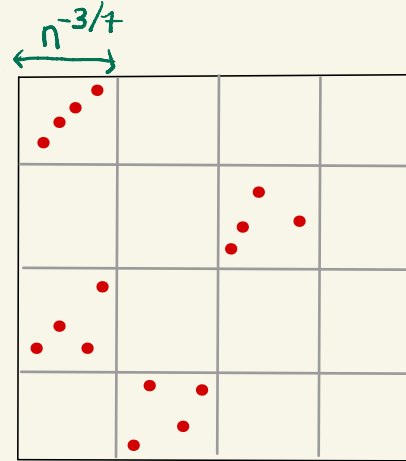


- Worst case scenario for Roth/KPS:

P is 2-dim down to scale $n^{-3/7}$

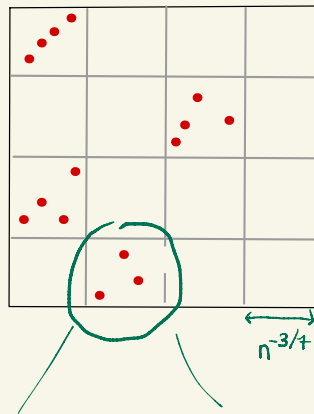
1-dim from scale $n^{-3/7} \rightarrow n^{-4/7}$

$$\Delta \approx n^{-8/7} \text{ worse bound than homogenous!}$$



Getting a better bound

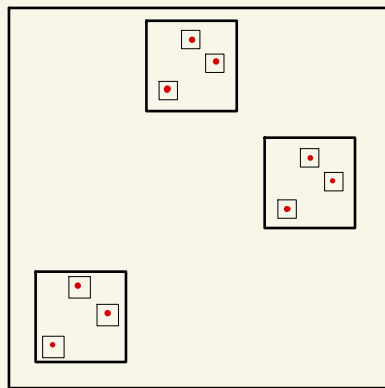
Worst case scenario: P is 2-dim down to scale $n^{-3/4}$
 1-dim from scale $n^{-3/4} \rightarrow n^{-4/7}$



Thm (Orponen-Shterkin-Wang): IF

- $X \subset [0,1]^2$ is $0 < s \ll 1$ dimensional, and
- X is not contained in a line

Then [dimension of **direction set**] $\geq s$



• Gives initial estimate in **worst case scenario**

• Pf: discretized sum-product + proj. theory + bootstrapping
 I don't understand

• $P_n \subset \mathbb{Q}$ is 1-regular

• Marstrand gives **no information** on **direction set**

• OSW: **direction set** is 1-dim

Harmonic Analysis

Incidence upper bounds

Incidence lower bounds

More to come...

Restriction & Decoupling theory

Falconer distance set

Discretized sum-product

Orponen 2017

Kakeya set

Marstrand 1954

Furstenberg set

High-Low method

OSW 2023

Geometric Measure Theory

Inductive step

Initial estimate

Projection theory

Heilbronn Triangle problem

Combinatorics

