

# DYNAMICAL SYSTEMS

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# Dynamical Systems

A **dynamical system** describes how different starting conditions evolve over time.

One example is interest, using the function  $F(x) = 1.1x$ .

If we put  $x$  dollars in the bank, we will have  $F^n(x) = 1.1^n x$  dollars after  $n$  years.

# The Quadratic Map

Another example is the quadratic function,  $Q_c(x) = x^2 + c$ .

This function will have different behavior for different values of the parameter,  $c$ .

# Orbits

When we iterate a function on a point  $x_0$ , we get a sequence of points, called the **orbit** of  $x_0$  under the function.

The orbit of  $x_0$  under  $F$  is the sequence  $x_0, F(x_0), F^2(x_0), \dots$

For example, the orbit of 100 under our interest function  $F(x) = 1.1x$  is 100, 110, 121, 133.1...

# Fixed Points

A **fixed point** of a function is a point for which  $F(x) = x$ .

The orbit of a fixed point  $x_0$  looks like  $x_0, x_0, x_0, \dots$

For example, 0 is a fixed point of our interest function.

## Fixed Points of $Q_c$

To find the fixed points of  $Q_c$ , we solve the equation  $Q_c(x) = x$ .  
We have:

$$Q_c(x) = x$$

$$x^2 + c = x$$

$$x^2 - x + c = 0$$

$$x = p_{\pm} = \frac{1 \pm \sqrt{1 - 4c}}{2}$$

Note that these fixed points only exist for  $c \leq \frac{1}{4}$ .

# Periodic Points

A **periodic point** (or  **$n$ -cycle**) of a function  $F$  for which  $F^n(x) = x$  for some  $n$ .

We call  $n$  the **period** of such a point.

The orbit of an  $n$ -cycle looks like  $x_0, x_1, x_2, \dots, x_n, x_0, x_1, \dots$

## The 2-Cycle of $Q_c$

To see if  $Q_c$  has a 2-cycle, we solve the equation  $Q_c^2(x) = x$ :

$$\begin{aligned}Q_c^2(x) &= (x^2 + c)^2 = x \\x^4 + 2cx^2 - x + c^2 + c &= 0\end{aligned}$$

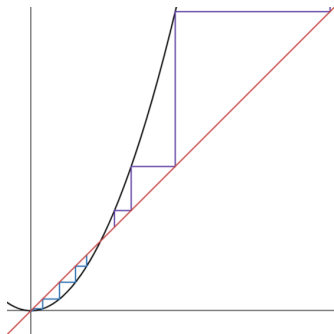
Two of the roots of this polynomial are the fixed points we already found; the other two roots are the 2-cycle

$$q_{\pm} = \frac{-1 \pm \sqrt{-4c - 3}}{2}.$$

This cycle only exists for  $c < -\frac{3}{4}$ .

## Attraction and Repulsion

A fixed point  $x$  of a function  $F$  is **attracting** if  $|F'(x)| < 1$ , **repelling** if  $|F'(x)| > 1$ , and **neutral** if  $|F'(x)| = 1$ .



The definitions are the same for  $n$ -cycles, but replace  $F$  with  $F^n$ .

## Attracting and Repelling Fixed Points of $Q_c$

To determine whether  $Q_c$ 's fixed points are attracting or repelling, we evaluate their derivatives. We have  $Q'_c(x) = 2x$ , so

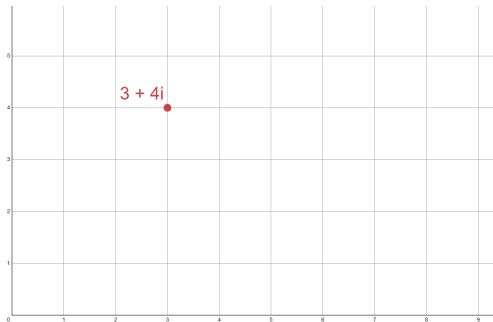
$$Q_c(p_{\pm}) = Q'_c\left(\frac{1 \pm \sqrt{1-4c}}{2}\right) = 1 \pm \sqrt{1-4c}.$$

From this, we see that:

- the larger fixed point is neutral for  $c = \frac{1}{4}$  and repelling for  $c > \frac{1}{4}$ ;
- and the smaller fixed point is neutral for  $c = \frac{1}{4}$ , attracting for  $-\frac{5}{4} < c < \frac{1}{4}$ , neutral at  $c = -\frac{5}{4}$ , and repelling for  $c < -\frac{5}{4}$ .

# The Complex Plane

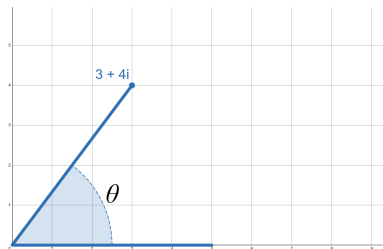
We define a **complex number** to be any number  $a + bi$  where  $a, b \in \mathbb{R}$  and  $i = \sqrt{-1}$ . We can plot a complex number  $a + bi$  on the coordinate plane at  $(a, b)$



## Modulus, Argument, and $e^{i\theta}$

The **modulus** of a complex number  $z$ ,  $|z|$ , is defined to be a complex number's distance from the origin. The **argument** of a complex number is the angle the number makes with the x-axis.

The argument and modulus can represent any complex number in a form  $re^{i\theta}$ , relying on Euler's formula  $e^{i\theta} = \cos \theta + i \sin \theta$ .



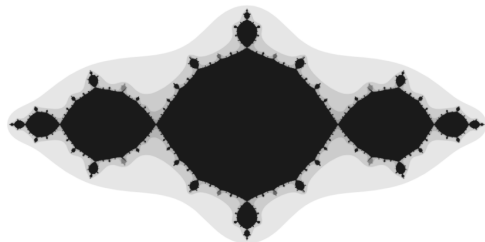
# Julia Sets

We can analyze  $Q_c$  as a complex-valued function too, letting  $c$  take any value in  $\mathbb{C}$ .

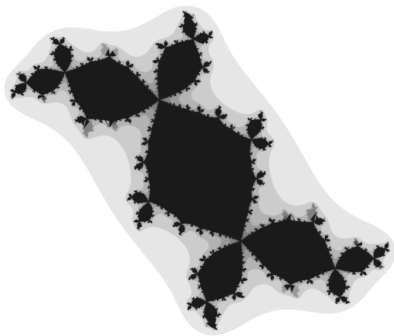
A **Julia set** for a specific  $c$  value is the set of all complex input values for  $z$  in which  $Q_c(z)$  stays bounded.

Julia sets are fractals, meaning they are shapes with infinite complexity and possibly self-similarity.

# Julia Set: $c = -1 + 0i$



Julia Set:  $c = -0.122561 + 0.744862i$



Julia Set:  $c = -0.257 + 0.7i$



Julia Set:  $c = -0.22 - 0.78i$



# The Fundamental Dichotomy: 0.25 vs. 0.251



# The Fundamental Dichotomy

The **Fundamental Dichotomy** states the following:

- 1 If the orbit of 0 under  $Q_c$  escapes to infinity then the Julia set of  $c$  contains infinitely many disjoint components.
- 2 If the orbit of 0 under  $Q_c$  stays bounded then the Julia set of  $c$  is one connected piece.

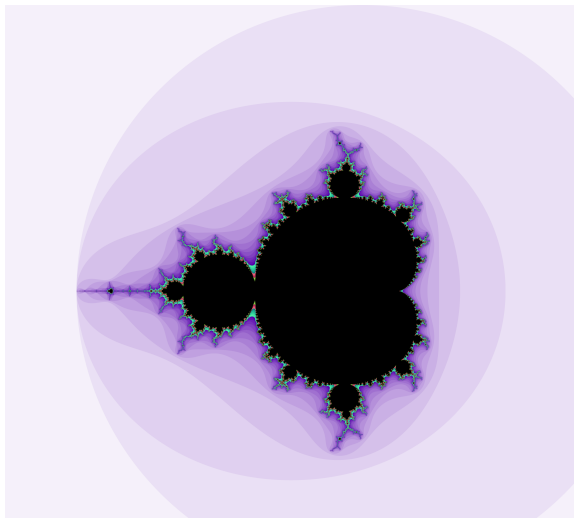
It is important to note this means there will never be a finite number of pieces other than 1 in a Julia set.

# The Mandelbrot Set

The **Mandelbrot set** is defined as the set of all  $c$ -values for which the respective Julia set is connected. Like the Julia sets, the Mandelbrot set is a fractal.

Unlike the Julia sets, which are in the input plane, the Mandelbrot set is in the parameter plane, meaning points represent values of  $c$  rather than  $z$ .

# The Mandelbrot Set





## The Main Cardioid

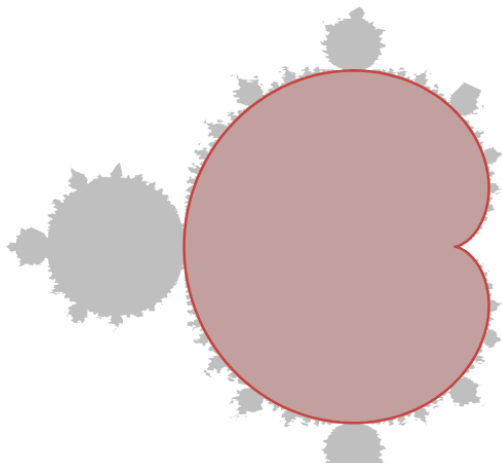
The main cardioid is the region of the Mandelbrot set for  $c$ -values where  $Q_c$  has an attracting fixed point.

Any such point  $z$  must satisfy  $z^2 + c = z$  and  $|Q'_c(z)| = |2z| < 1$ . The boundary of the inequality is given by  $z = \frac{1}{2}e^{i\theta}$  for  $\theta \in [0, 2\pi)$ .

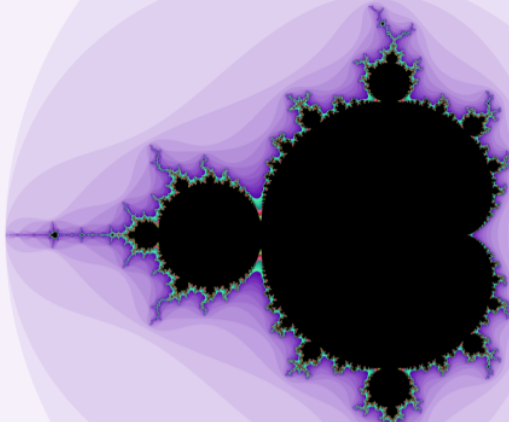
Since  $c = z - z^2$  by the first equation, the boundary of this region is given by  $c = \zeta(\theta) = \frac{1}{2}e^{2\pi i\theta} - \frac{1}{4}e^{4\pi i\theta}$ .

# The Main Cardioid

Here is the cardioid, visually:



# Any Questions?



# Sources

[1] *A First Course in Chaotic Dynamical Systems* by Robert L. Devaney