Knot crossings counter

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Yulia's Dream program

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What is NN?

A typical model architecture consists of a composition of functions, say $f_1, f_2, \ldots, f_N$. This composition is applied to the input data, and the result is processed to optimize the model parameters.

$$f_N \circ f_{N-1} \circ \cdots \circ f_1(input) = output$$

$$f(\mathbf{x}; \boldsymbol{\theta}) = f_N \circ f_{N-1} \circ \cdots \circ f_1(\mathbf{x}),$$

where $\mathbf{x}$ is the input and $\boldsymbol{\theta}$ is the vector of all model parameters.

How do we train it?

Loss function L measures the discrepancy between predictions and ground truth:

$$L = L(\mathit{predictions}, \mathit{truths}) = L(f(\mathit{truths}), \mathit{truths}) = \mathit{discrepancy}$$

$$\min_{\boldsymbol{\theta} \in \mathrm{dom}\ L} L \quad \Rightarrow \quad \boldsymbol{\theta}^{(l+1)} = \boldsymbol{\theta}^{(l)} - \eta \nabla L(\boldsymbol{\theta}^{(l)}), \tag{1}$$

where the superscript (l) denotes the l-th iteration, η is the *learning rate*, and ∇L is the *gradient* of the loss function with respect to the parameters.

Gradient Descent Algorithm

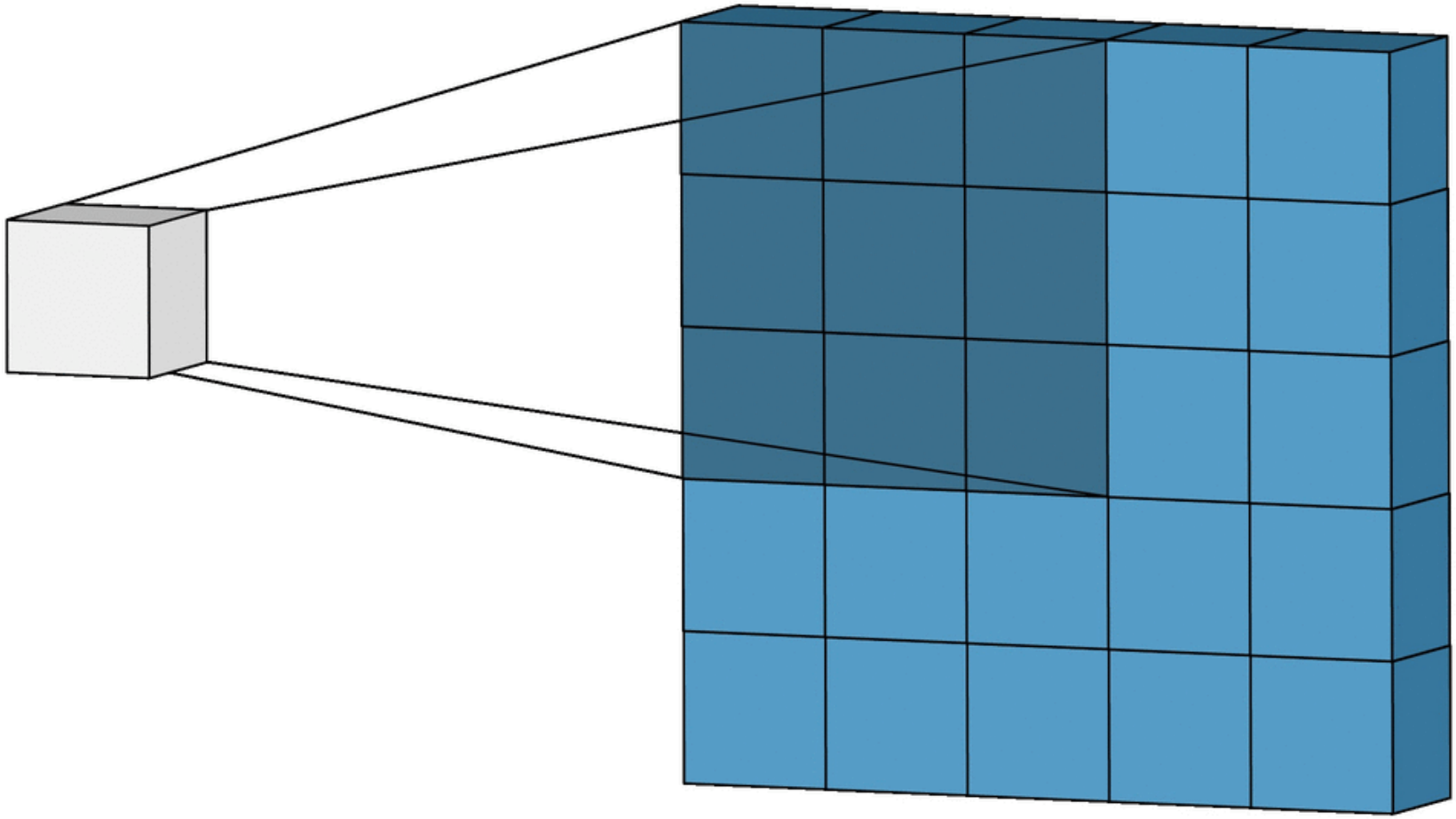
Algorithm 1: Gradient Descent

Input : Training set of data points indexed by $n \in \{1, \ldots, N\}$
Number of training steps N
Loss function $L(\boldsymbol{\theta})$
Learning rate η
Initial parameter vector $\boldsymbol{\theta}$

Output: Final parameter vector $\boldsymbol{\theta}$

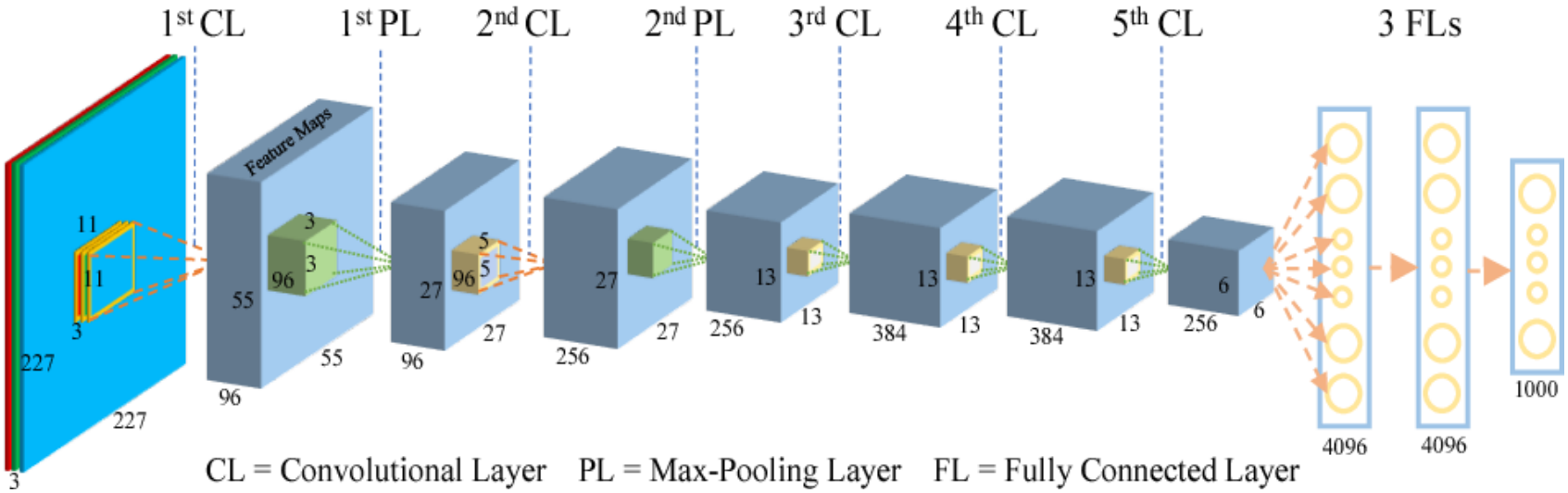
$n \leftarrow 1$;
repeat
  $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \eta \nabla L(\boldsymbol{\theta})$;
  $n \leftarrow n + 1$;
until $n > N$;
return $\boldsymbol{\theta}$

What is a convolution in ML?



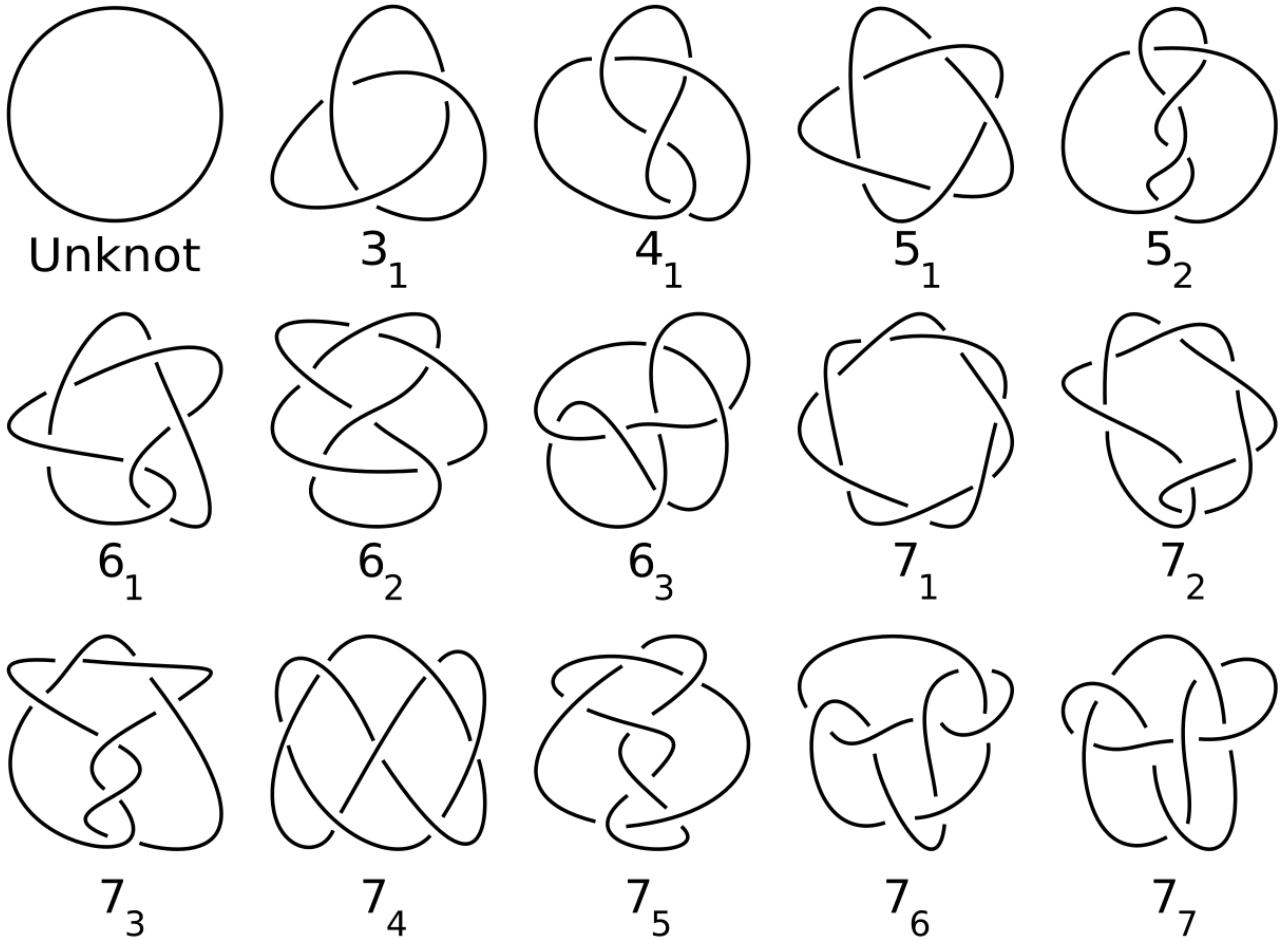
Source

Standart architecture



Source

Motivation



Source

State of the art results

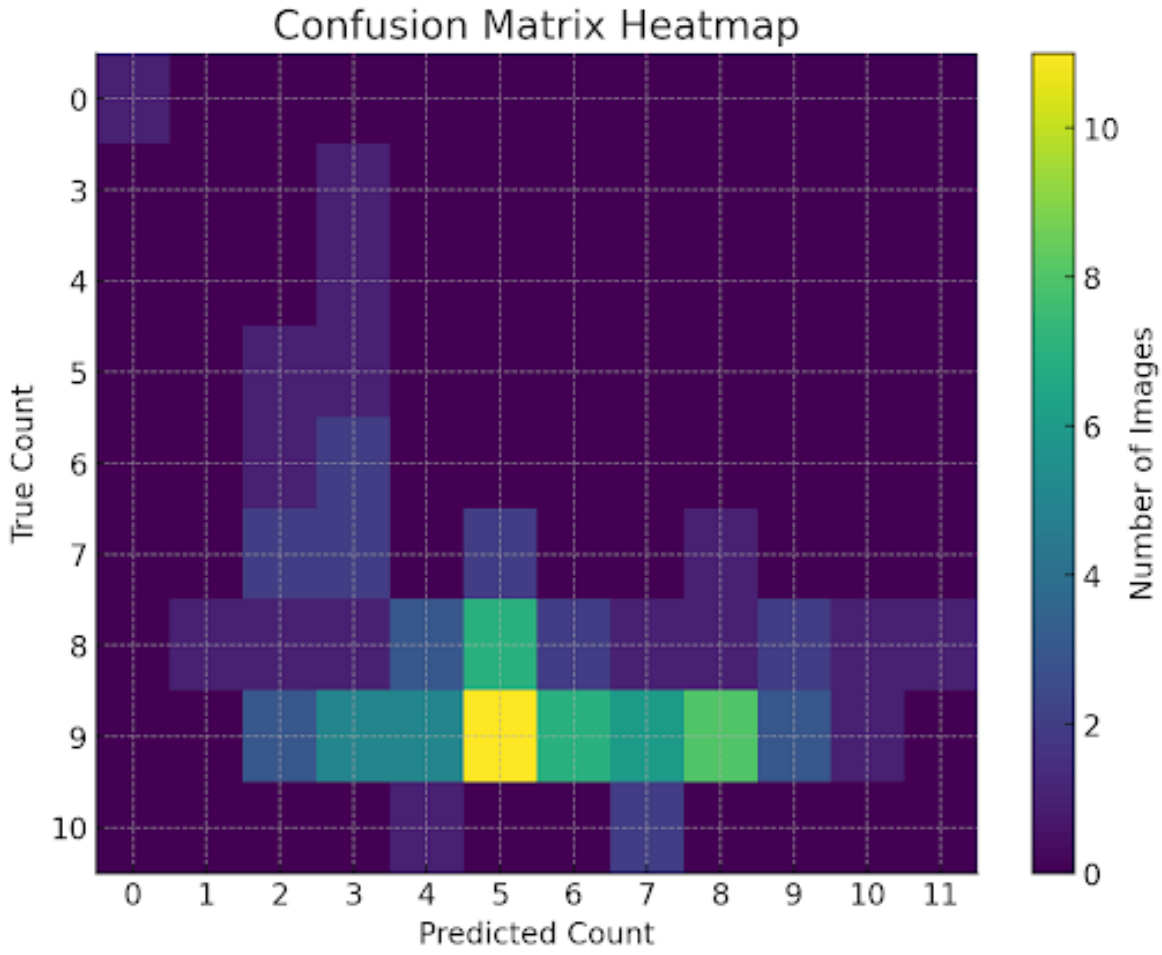
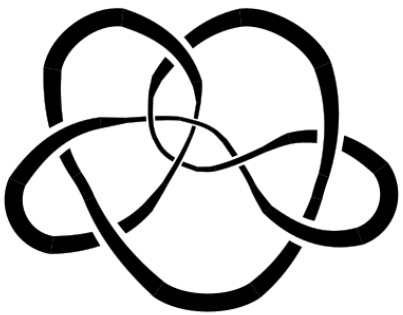


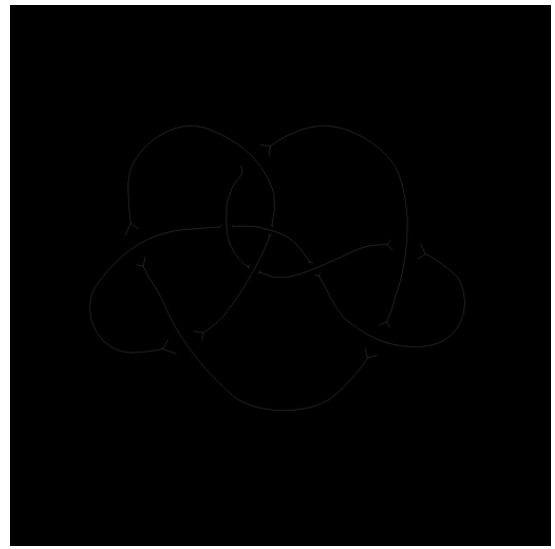
Figure: Confusion matrix of o4-mini results. Average accuracy is 5.65%

Data preparation



(a) Original knot

(b) Skeletonized



(c) Inverted

Figure: Steps of image preprocessing

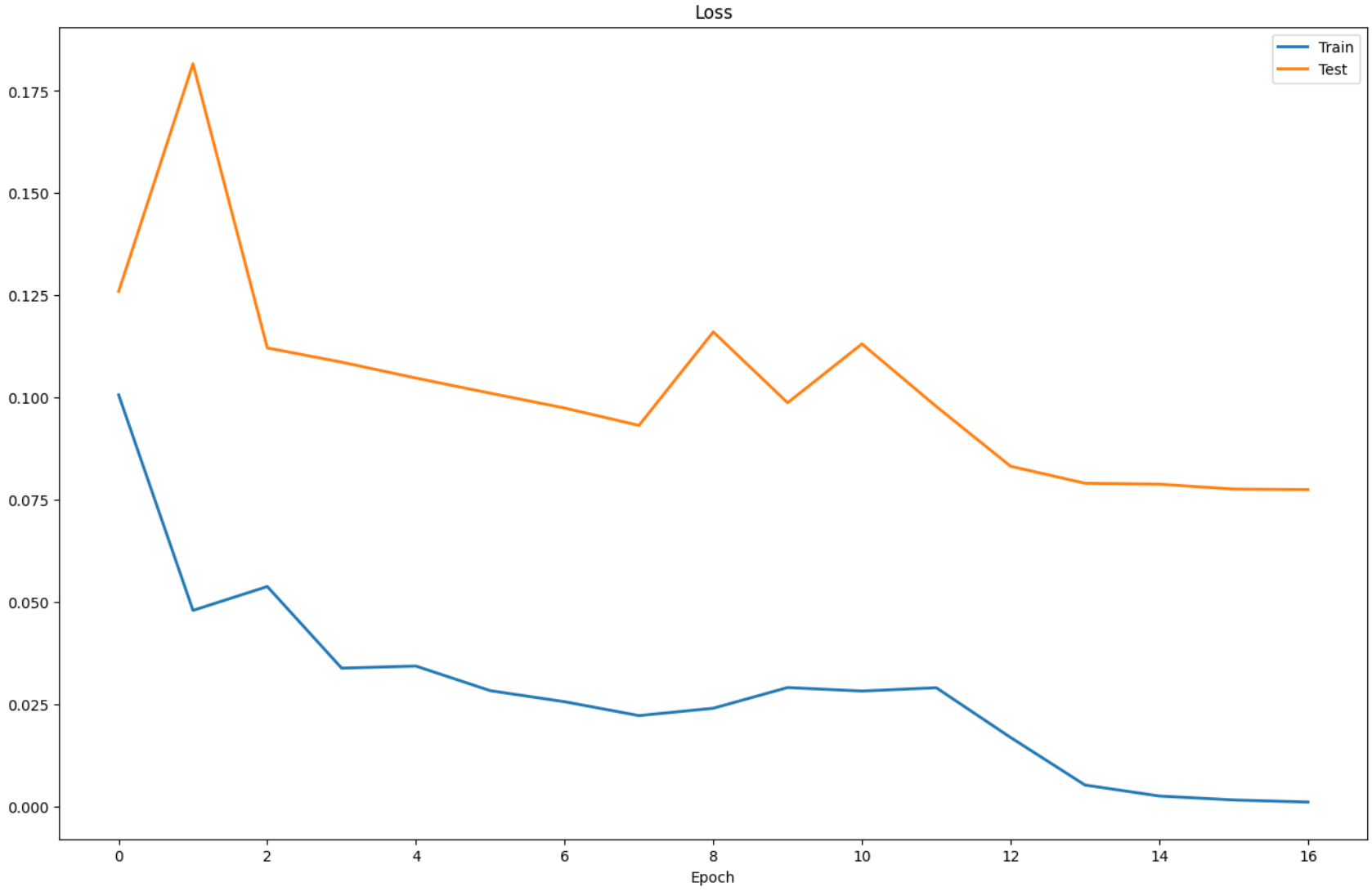
Vanilla

Easiest architecture is linear layer. But since composition of linears is also linear, one should insert non=linear function (in our case - ELU) between linear.

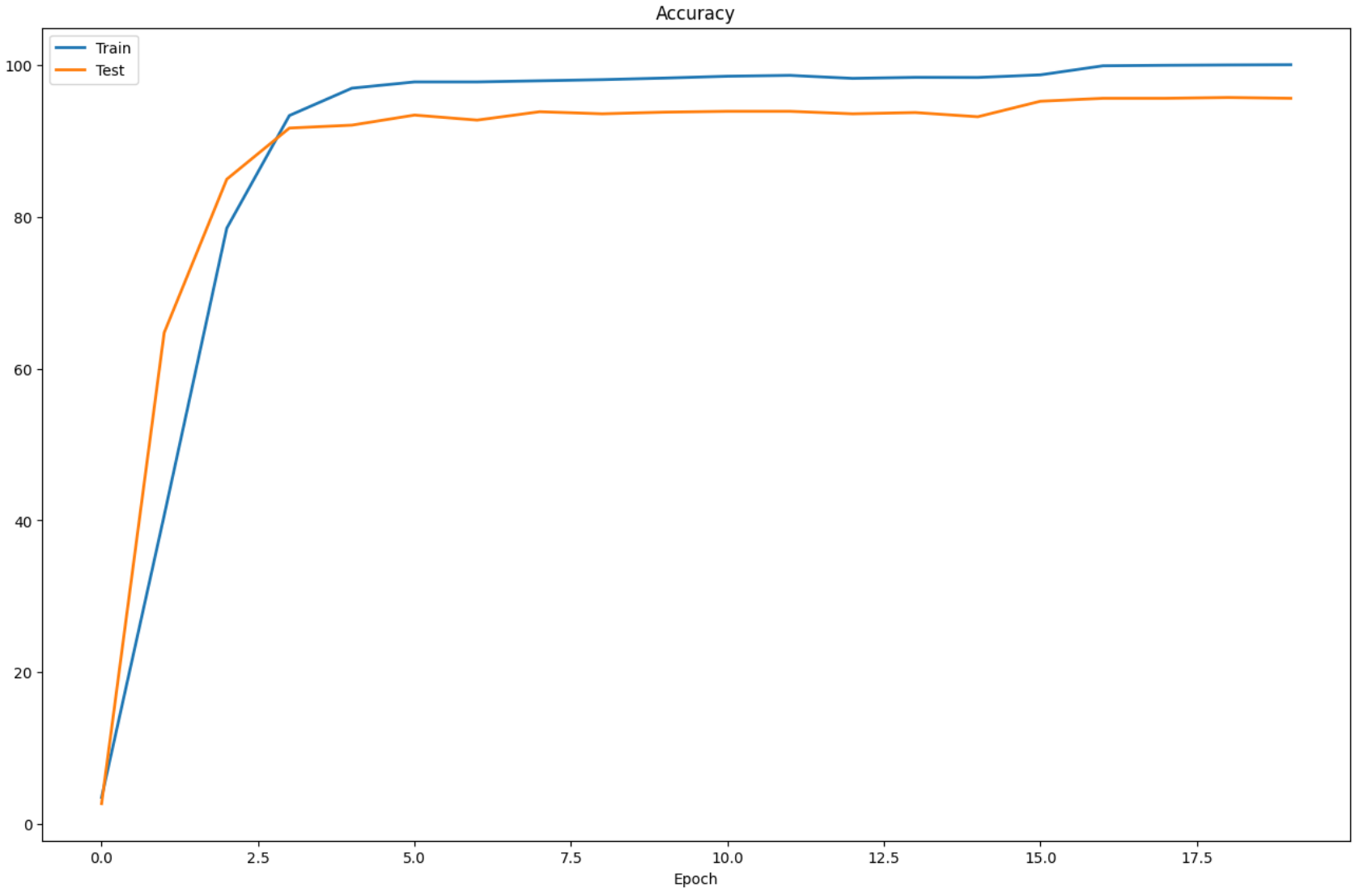
$$FC(\mathbf{x}) = ELU(\mathbf{W}\mathbf{x} + \mathbf{b})$$

$$Vanilla = FC^k,\ k \in \mathbb{N}$$

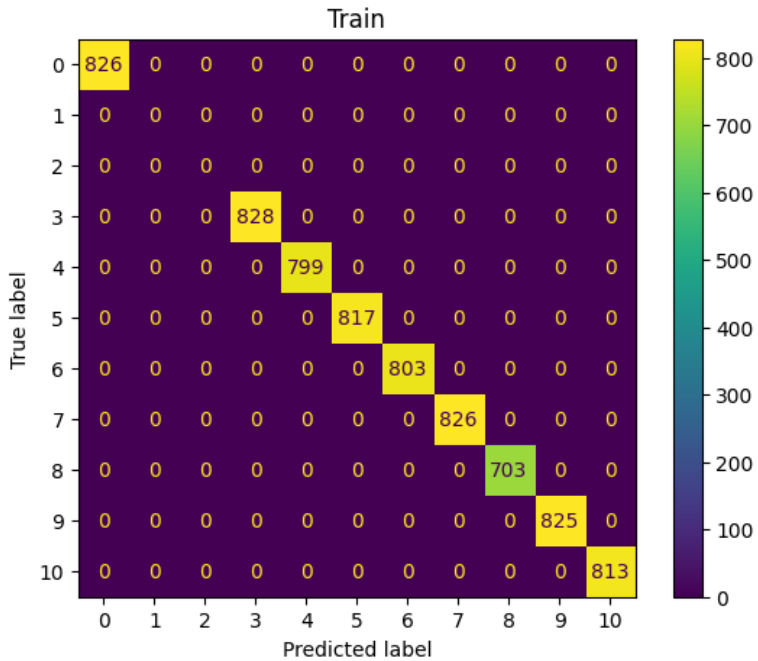
Vanilla, loss

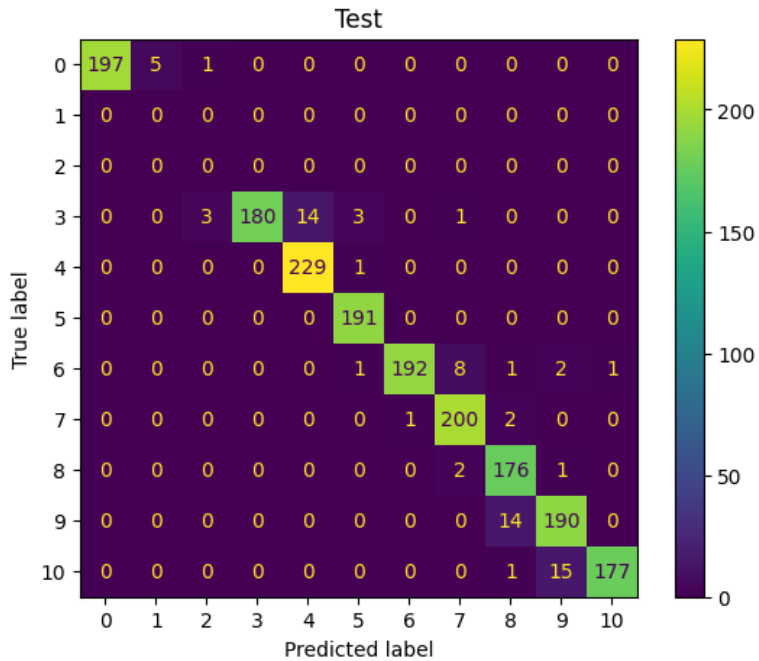


Vanilla, accuracy

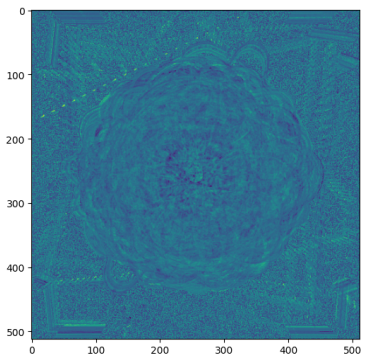


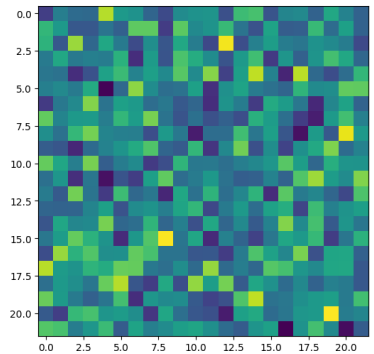
Vanilla, confusion matrices

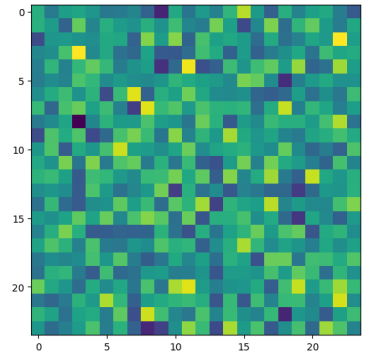


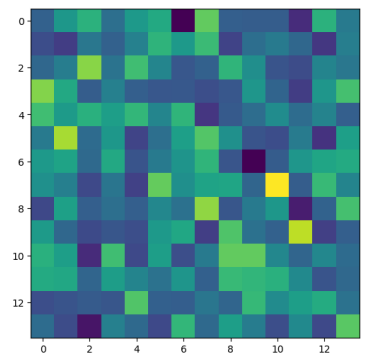


Vanilla, weights









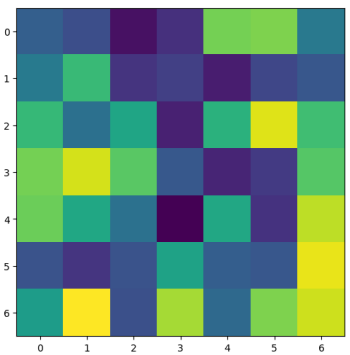
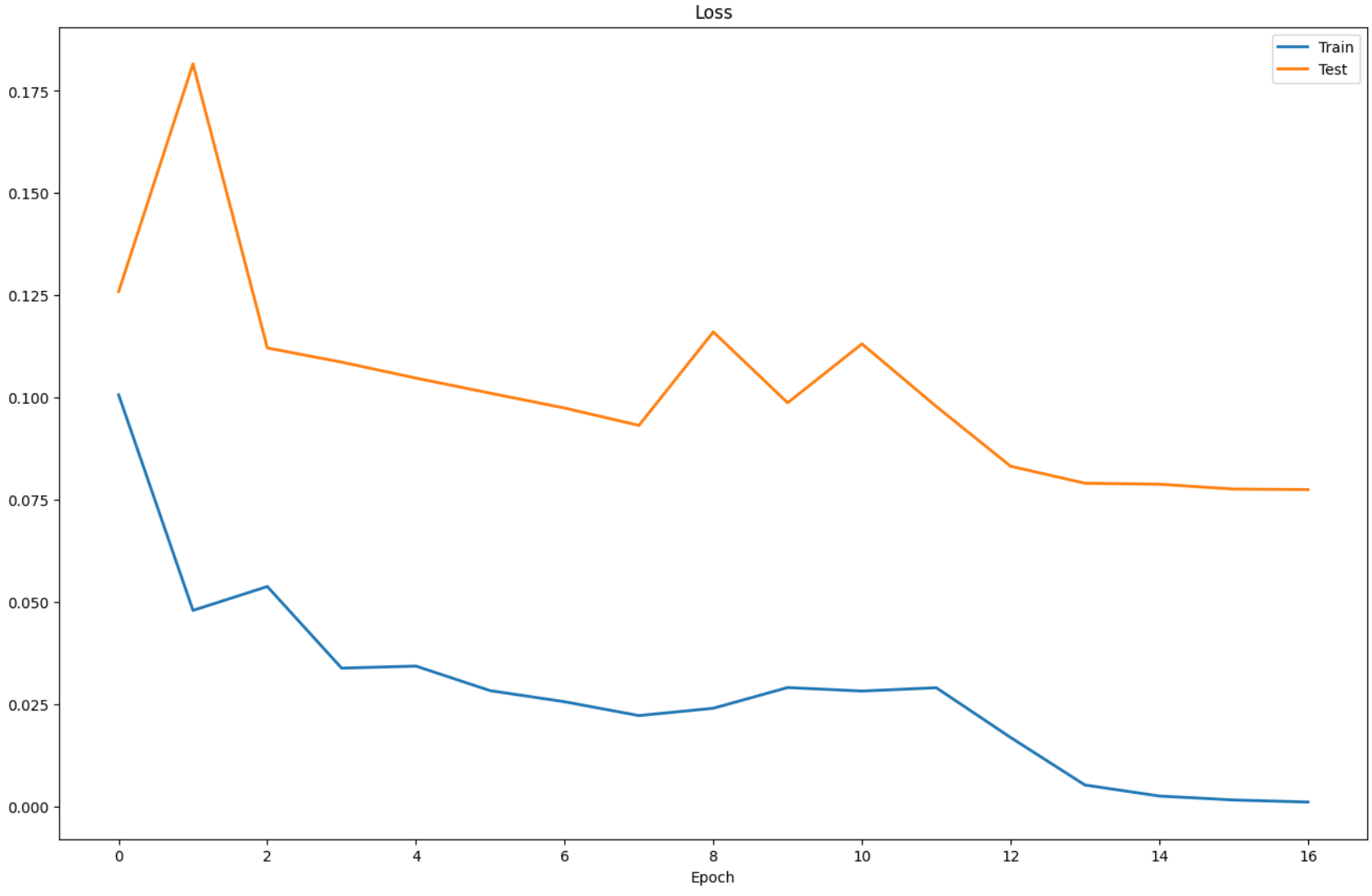
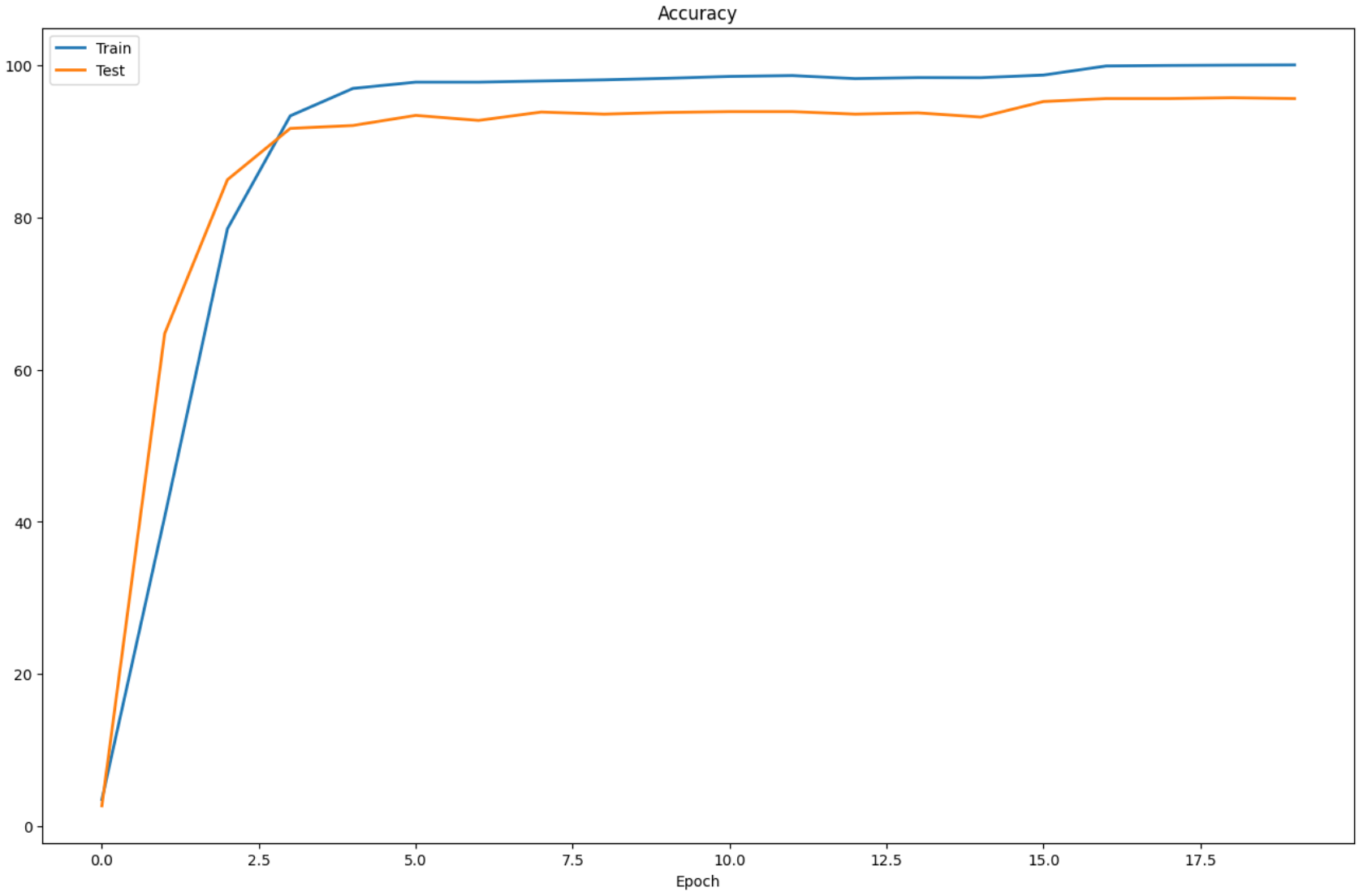


Figure: Weights of different Vanilla's layers

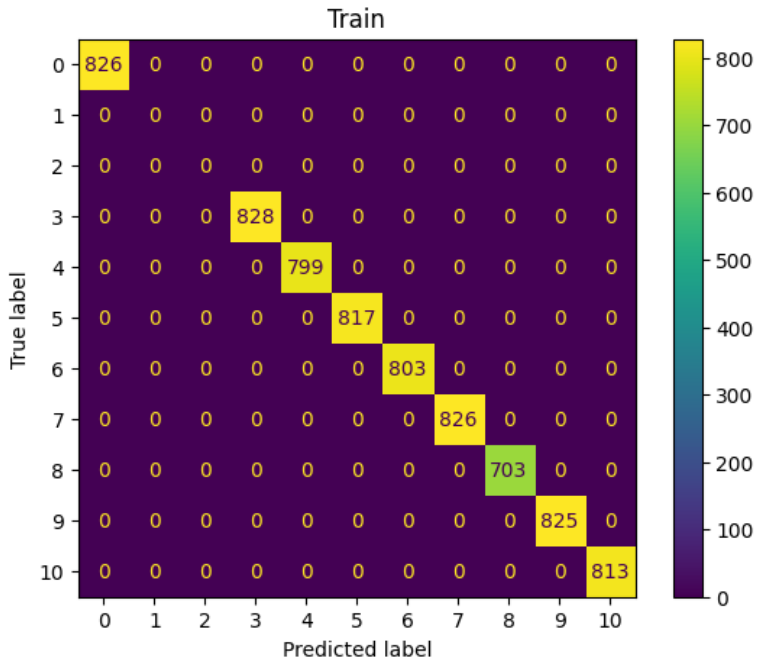
CNN, loss

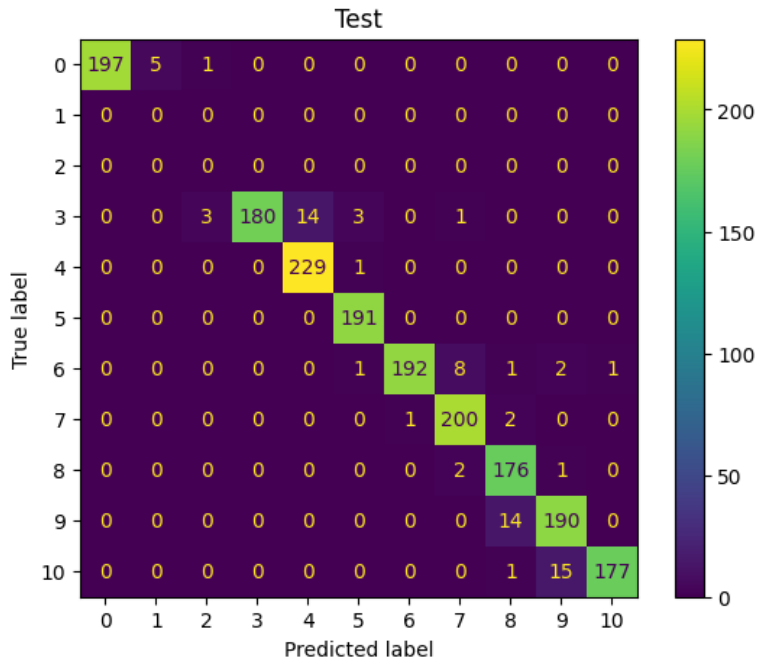

Loss
Train
Test
0.175
0.150
0.125
0.100
0.075
0.050
0.025
0.000
0
2
4
6
8
10
12
14
16
Epoch

CNN, accuracy



CNN, confusion matrices





CNN, weights

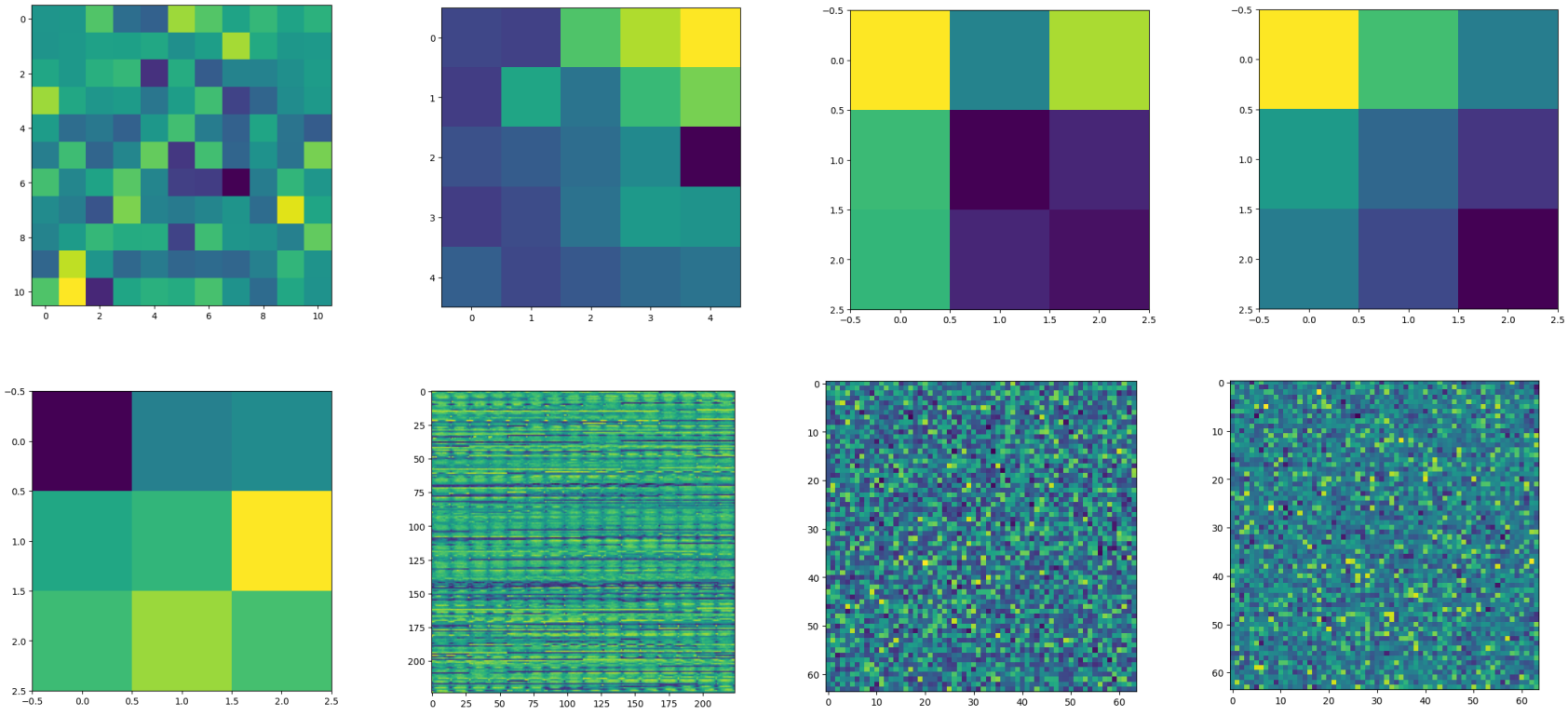
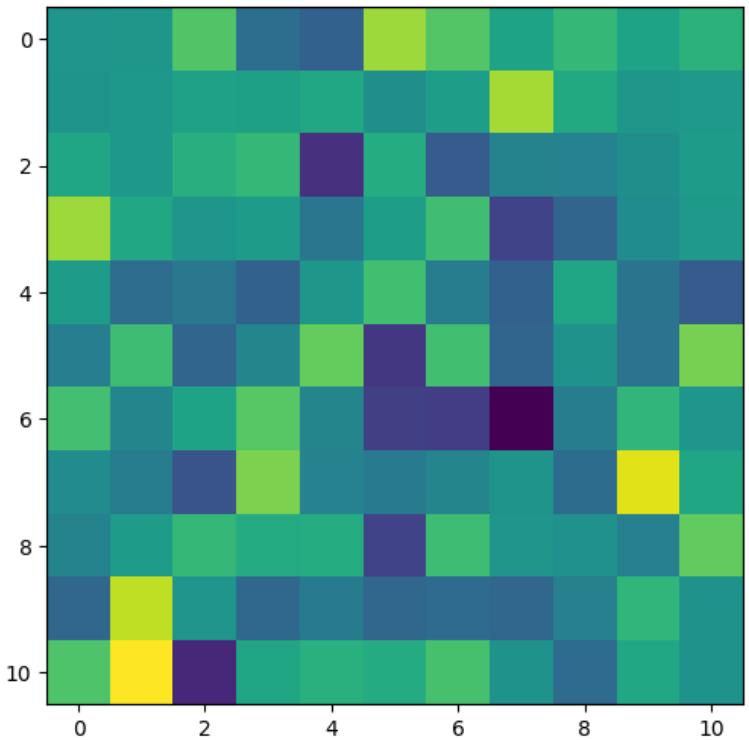
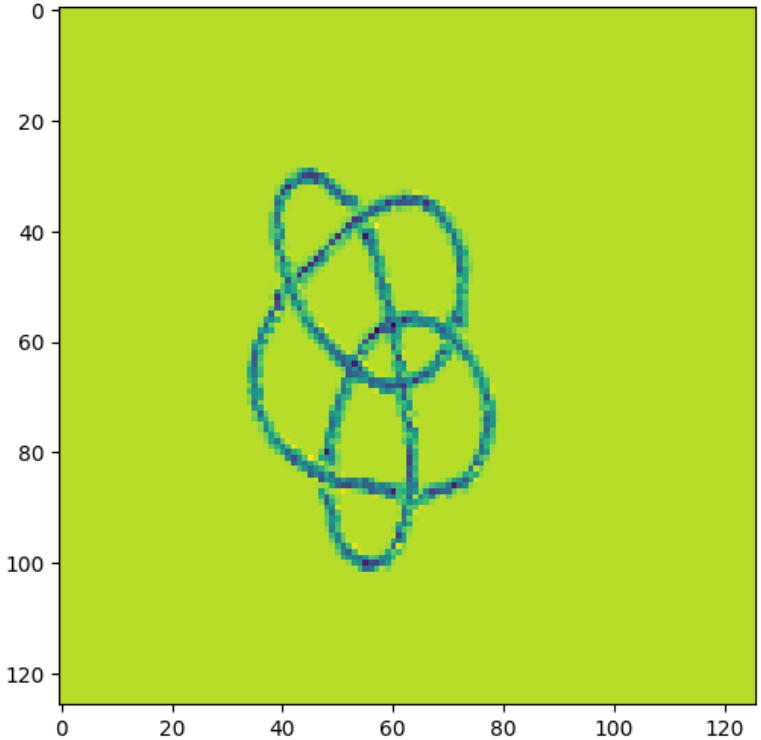


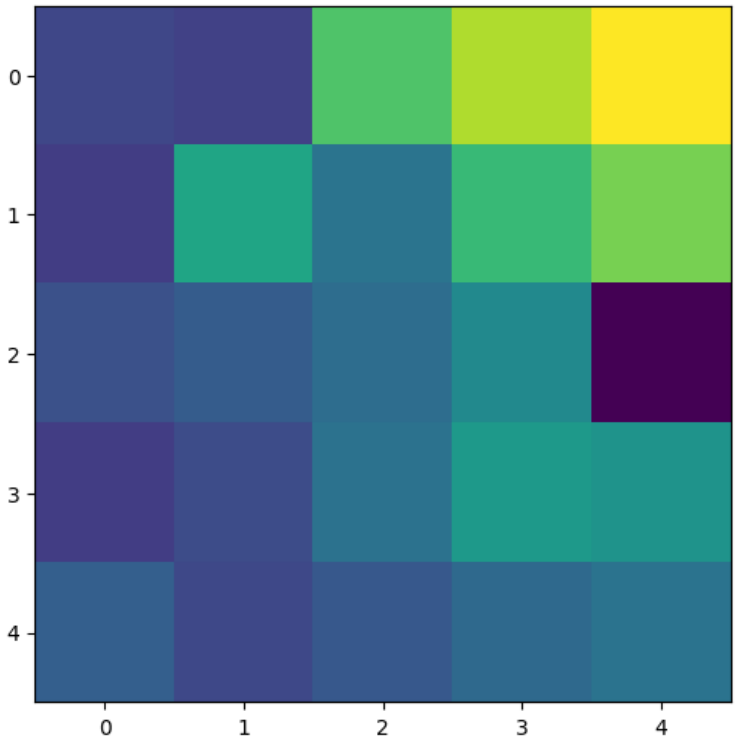
Figure: Weights of different CNN's layers

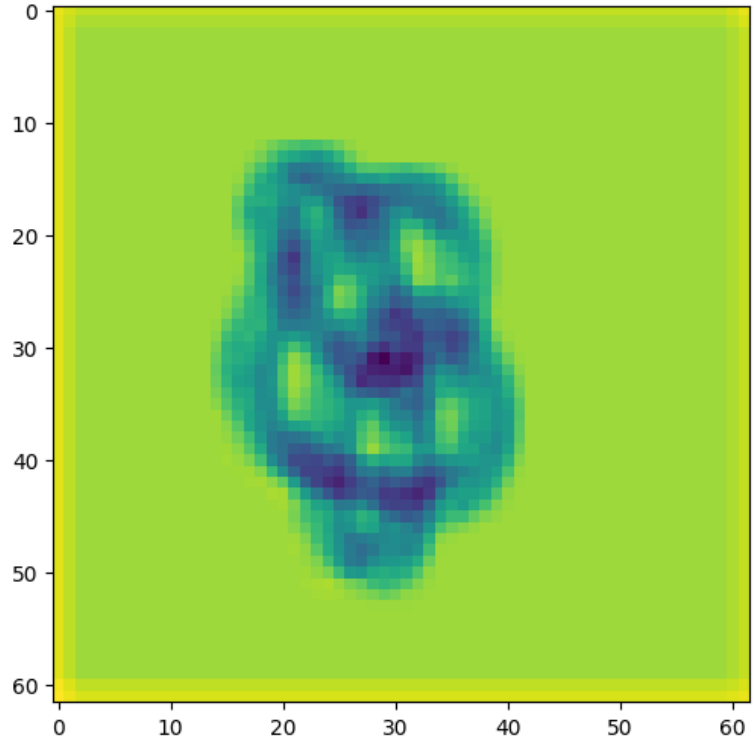
What does CNN actually do? 1



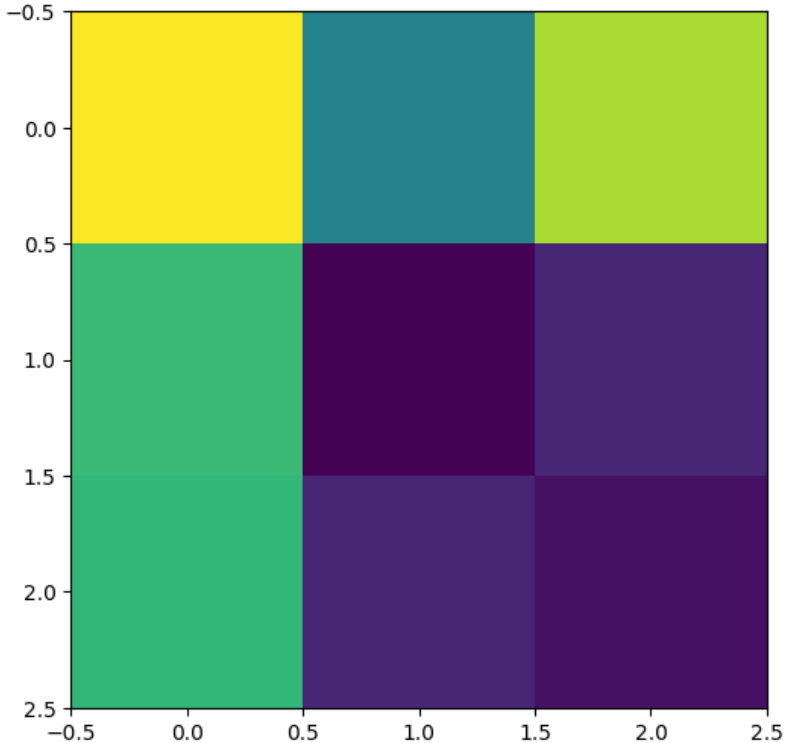


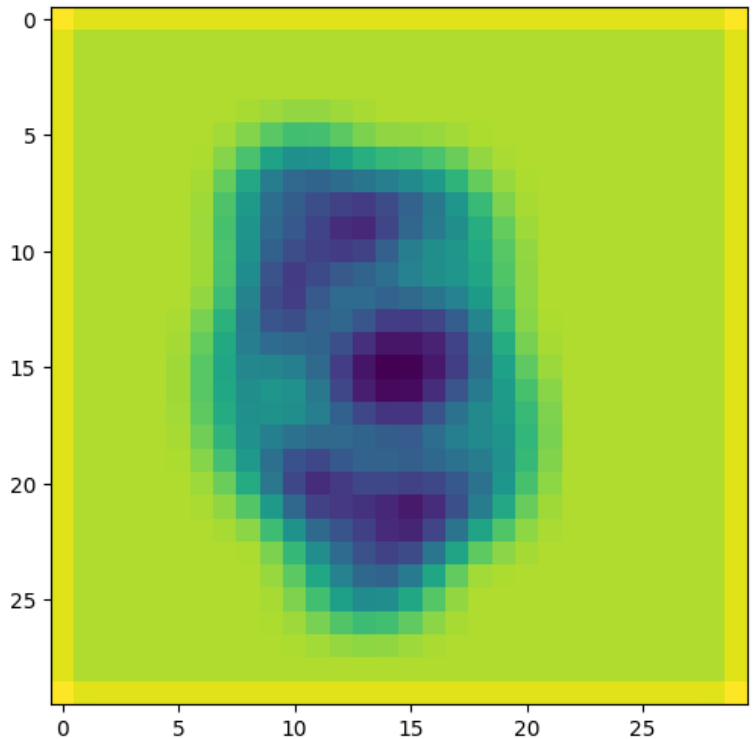
What does CNN actually do? 2



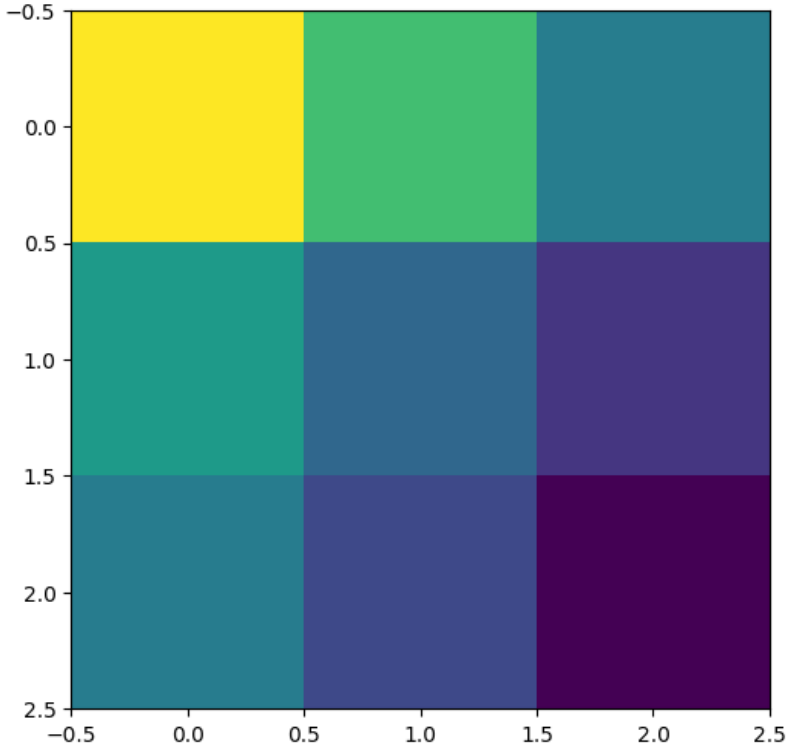


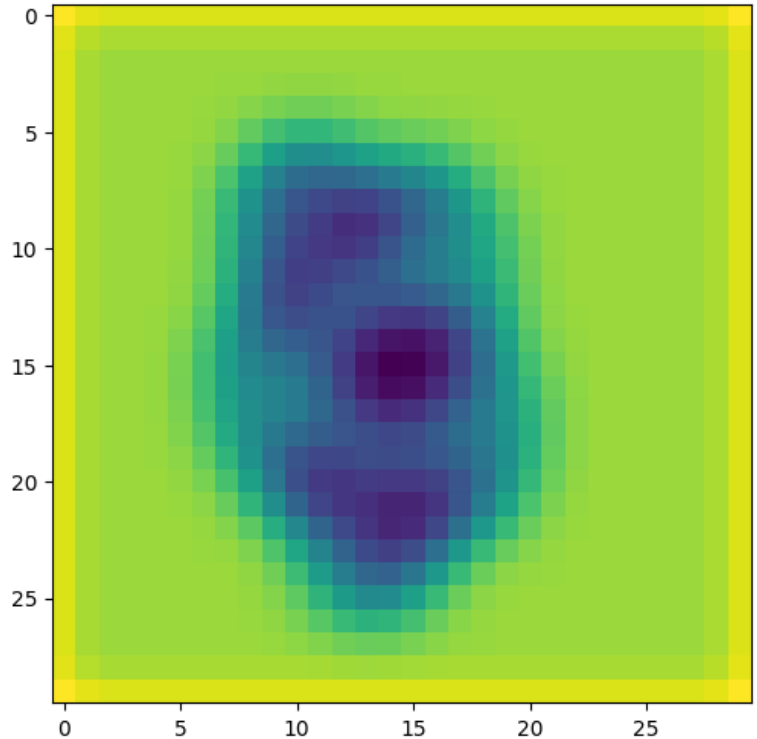
What does CNN actually do? 3



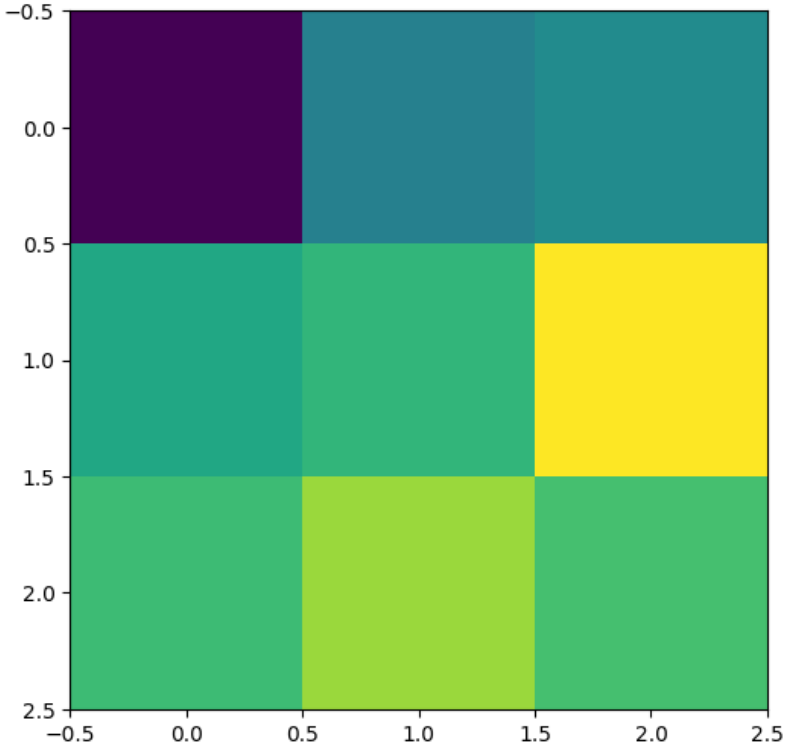


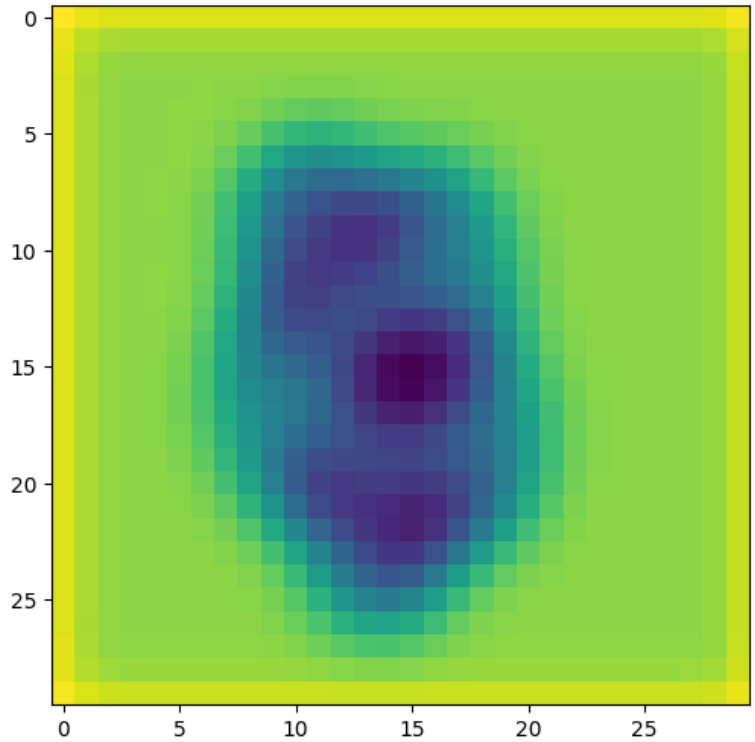
What does CNN actually do? 4



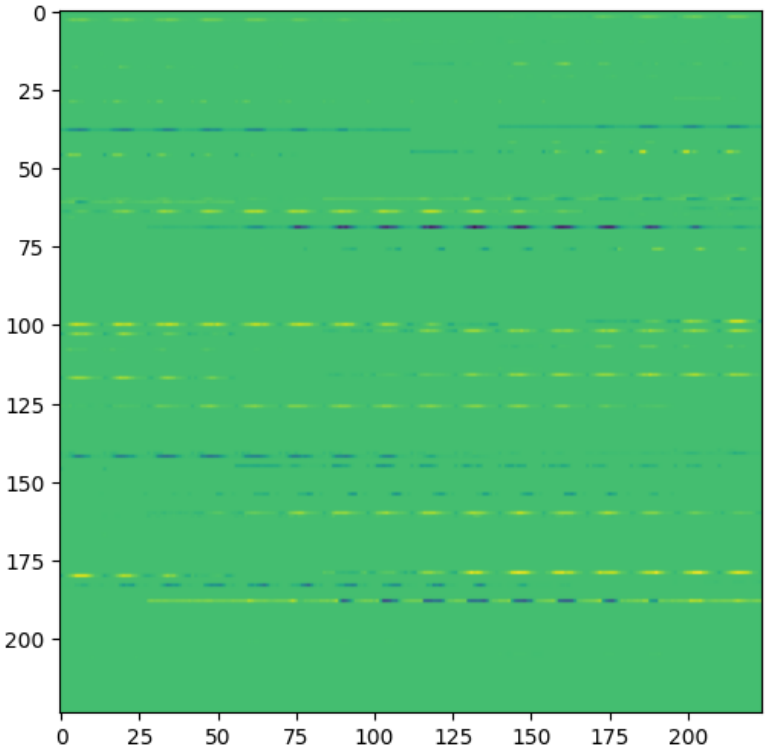


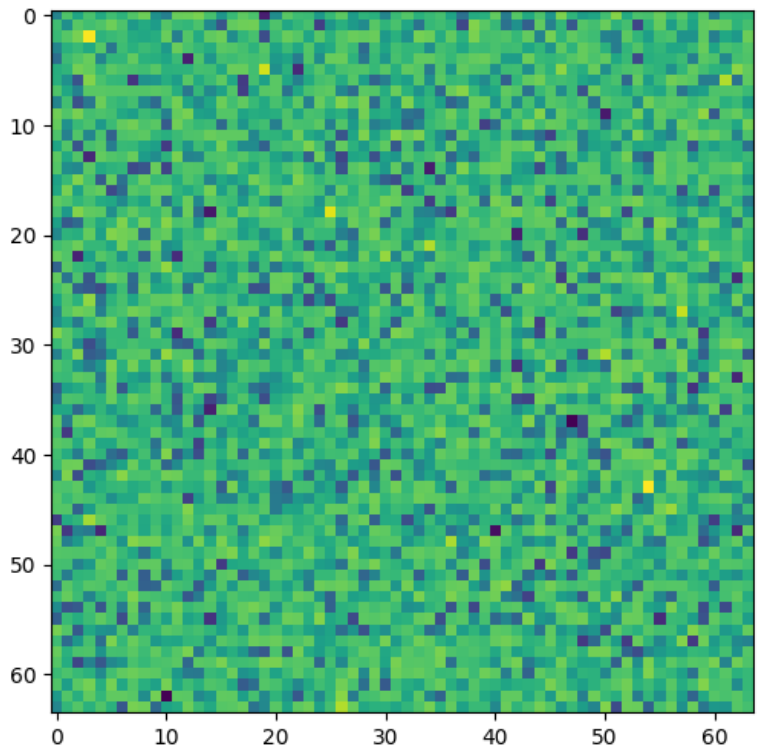
What does CNN actually do? 5



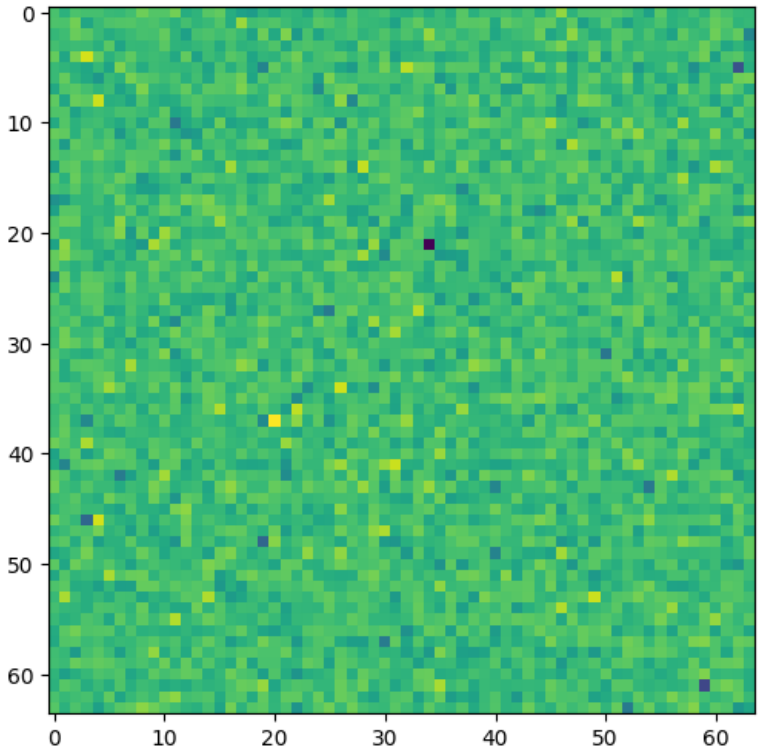


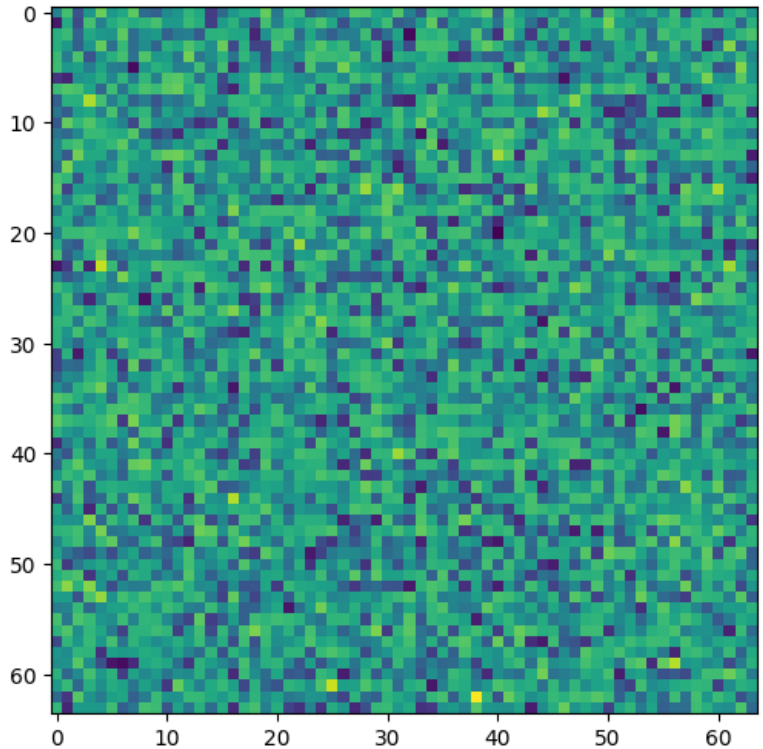
What does CNN actually do? 6



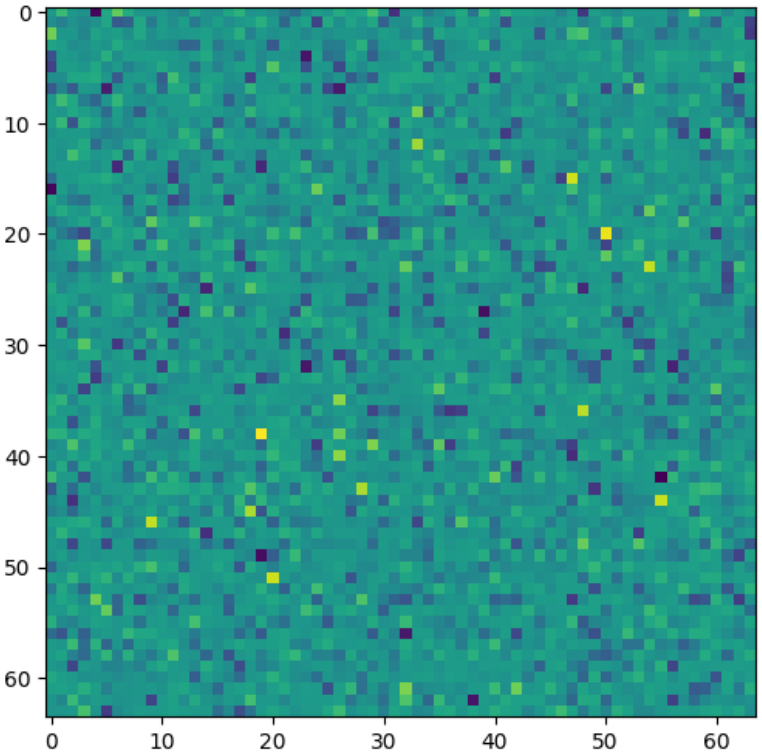


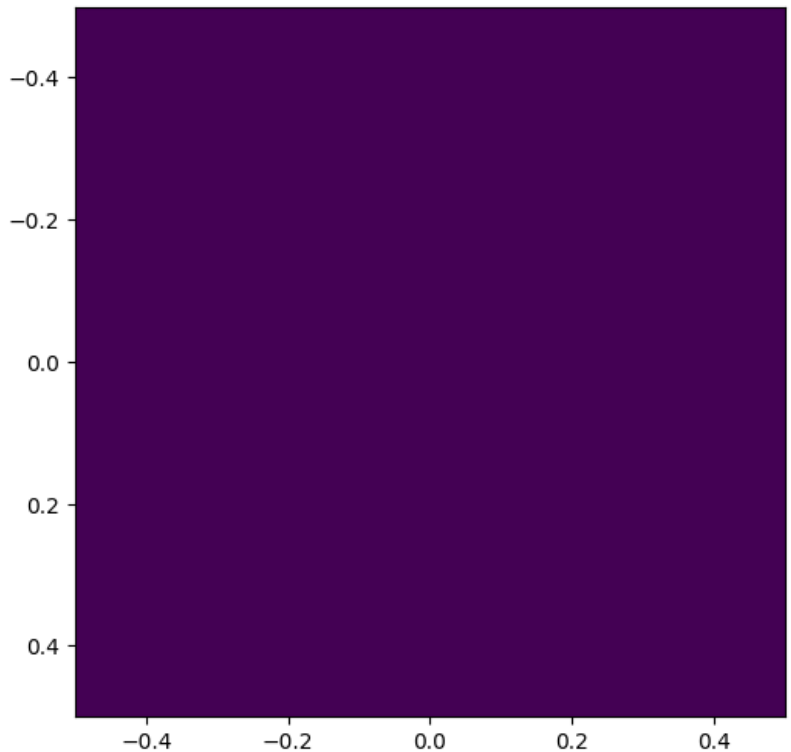
What does CNN actually do? 7



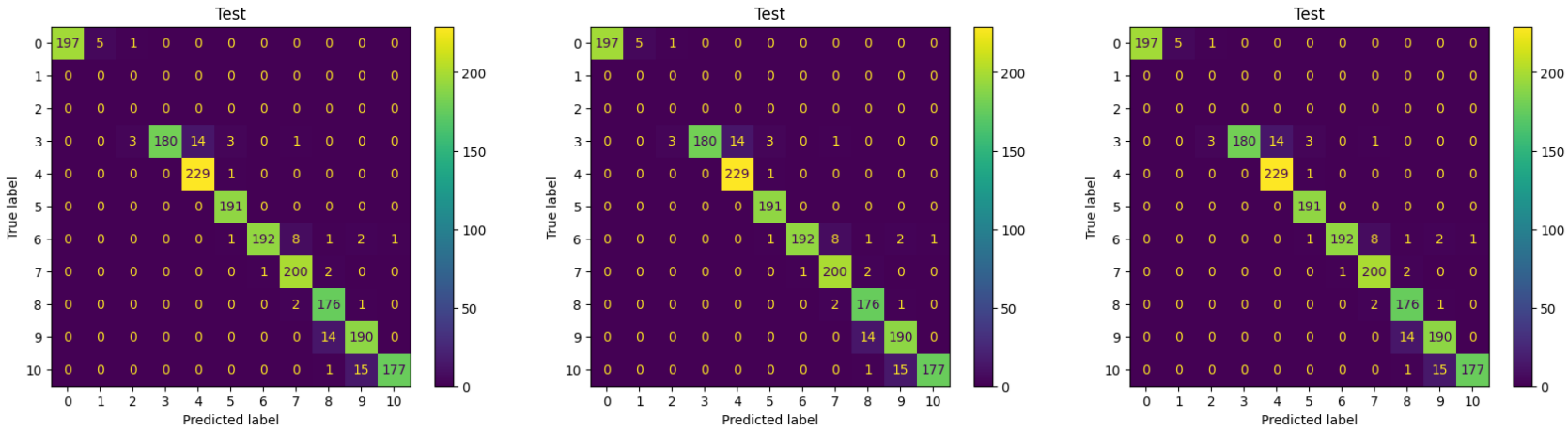


What does CNN actually do? 8





Comparison



(a) Vanilla (b) CNN (c) GPT

Figure: Confusion matrices on test dataset

Thank you for listening!