

Beyond Additivity: Sparse Isotonic Shapley Regression toward Nonlinear Explainability

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Acknowledgment: Thanks to Dr. Alterovitz, Dr. Xie, Dr. Pei,
and the PRIMES program

Background and Motivation

- ▶ **Shapley values**: fair credit in cooperative games (Shapley 1953).
 - Feature set: $F = \{1, \dots, p\}$; coalition **payoff** $\nu_A = \nu(A) \forall A \subseteq F$.
 - Shapley value β_j quantifies fair share/importance of feature j
 - V_A : link between observed payoffs and underlying feature contributions: $\nu_A = V_A(\{\beta_j\}_{j \in A}) + \text{noise}$
- ▶ Widely used for **feature attribution** in explainable AI (**XAI**)
 - Regression: p-values. Complex ‘**black-box**’ *trees/neural nets*?
- ▶ Challenge a): **Additivity** of payoffs: $V_A(\{\beta_j\}_{j \in A}) = \sum_{j \in A} \beta_j$
 - Diverse payoff methods (R^2 , TreeSHAP, Sobol indices, etc.) exist; Shapley is applied *blindly* without checking its **axioms**!
 - Fryer (21)’s “**taxicab**” payoff $V_A = \max_{j \in A} \beta_j$ (*winner-takes-all*)
- ▶ Challenge b): **Dense**, non-sparse attributions: $\beta \in \mathbb{R}^p$, p large
 - Most features **negligible**. Dense Shapley + thresholding = **greedy**!
- ▶ Need **unified** “nonlinear + sparse” attribution.

Recasting Shapley: A Statistical Framework

- ▶ A **weighted** least squares formulation recovers the Shapley values:

$$\min_{\beta, c} \sum_A w_{\text{SH}}(A) (\nu_A - \sum_{j \in A} \beta_j - c)^2 \text{ s.t. } c = \nu_{\emptyset}, c + \sum_{j=1}^p \beta_j = \nu_F,$$

where $w_{\text{SH}}(A) = \frac{p-1}{\binom{p}{|A|}|A|(p-|A|)}$. See Lundberg & Lee (17).

- ▶ Under $w_{\text{SH}}(\emptyset) = +\infty, w_{\text{SH}}(F) = +\infty, \nu_A \leftarrow \nu_A - \nu_{\emptyset}$, we obtain

$$\nu_A \sim \mathcal{N}(\mu_A, \sigma_A^2), \mu_A = \sum_{j \in A} \beta_j^*, \sigma_A^2 \propto \binom{p}{|A|} |A|(p-|A|) \left(\propto \frac{1}{w_{\text{SH}}(A)} \right)$$

- ▶ Many payoff functions **violate** the **Gaussian** assumption due to **range constraints**, **skewness**, **heavy tails**, & **heterogeneity**.
- ▶ We propose to consider $T(\nu_A) \sim \mathcal{N}(\sum_{j \in A} T(\beta_j^*), \sigma_A^2)$.

Univariate T -Mappings for Nonlinear Payoffs

- ▶ Our proposal restores additivity in a *transformed domain* using a univariate, invertible function $T(\cdot)$:

$$V_A(\{\beta_j\}_{j \in A}) = T^{-1}\left(\sum_{j \in A} T(\beta_j)\right).$$

- ▶ Simple T -mapping captures **rich**, **multivariate** payoff structures.
- ▶ Special case: $T(x) = |x|^d$, then $V_A = \|\beta_A\|_d$.
 - $d = 1, 2$: ℓ_1/ℓ_2 -ball. $d \rightarrow \infty$: $V_A = \max_{j \in A} |\beta_j|$ (**winner-takes-all**)
- ▶ Exponential/log/odds transforms for other nonlinearities.
- ▶ Nicely, our method will learn $T(\cdot)$ in a purely *data-driven* manner, and **bypass** the need to specify its analytical form.

Sparse Isotonic Shapley Regression (SISR)

$$\begin{aligned} \min_{\beta, T(\cdot)} \quad & \sum_{A \subseteq 2^F} w_{\text{SH}}(A) \{T(\nu_A) - \sum_{j \in A} T(\beta_j)\}^2 \\ \text{s.t.} \quad & \|\beta\|_0 \leq s, T \in \mathcal{M}, \sum_{j=1}^p (T(\beta_j))^2 = 1 \end{aligned}$$

- **Monotonicity:** $\mathcal{M}$ constrains T to be increasing $\rightarrow$ preserve ranking of feature importance: $\beta_i \geq \beta_j \Rightarrow T(\beta_i) \geq T(\beta_j)$.
- **Normalization:** The scale constraint prevents degeneracy and anchors the model scale (& yields a closed form update for β !)
- **Sparsity:** We enforce explicit support control via ℓ_0 , selecting the most relevant features during optimization, not after.
 - $\lambda \sum |T(\beta_j)|$: over-shrinks and requires a fine λ grid search. s : an *upper bound*, simple to specify & tune (**RIC**, Foster & George 94)

Equivalent Reformulations

- **Challenges:** (i) functional T , (ii) double nonconvex constraints
- Let $\gamma_j = T(\beta_j)$. As $T(0) = 0$, the optimization problem becomes

$$\min_{\gamma, T} \sum_{A \subseteq 2^F} w_{\text{SH}}(A) \left(T(\nu_A) - \sum_{j \in A} \gamma_j \right)^2 \text{ s.t. } \|\gamma\|_0 \leq s, \|\gamma\|_2 = 1, T \in \mathcal{M}$$

- As $T(\cdot)$ is only evaluated at observed $\nu_A (A \subseteq 2^F)$, we **discretize** the problem by introducing $t = [T(\nu_A)] \in \mathbb{R}^{2^p}$, $\nu = [\nu_A]$, $\delta = [\sum_{j \in A} \gamma_j] = Z\gamma \in \mathbb{R}^{2^p}$ with $Z \in \mathbb{R}^{2^p \times p}$ the ‘incidence matrix’
- Introducing $E(\nu) = \{(i, j) : \nu_i \leq \nu_j\}$ to encode the pairwise ordering and $W = \text{diag}\{w_{\text{SH}}(A)\}_{A \subseteq 2^F}$, it suffices to solve

$$\min_{\gamma, t} \frac{1}{2} (t - \delta)^\top W (t - \delta) \text{ s.t. } \delta = Z\gamma, \\ \|\gamma\|_0 \leq s, \|\gamma\|_2 = 1, t_i \leq t_j \forall (i, j) \in E(\nu)$$

Two-Block Alternating Optimization

- ▶ For $\vec{t}$, the problem reduces to a *weighted isotonic regression* (de Leeuw et al 09). We solved it by an efficient *stack*-based weighted variant of Pool-Adjacent-Violators Algorithm (**PAVA**).
- ▶ For γ , we use a “surrogate function” trick to deal with δ , leading to an *iterative normalized hard*-thresholding algorithm:

$$\gamma^{\text{new}} = \frac{\mathcal{H}(y; s)}{\|\mathcal{H}(y; s)\|_2}, \quad \text{where } y = \gamma^{\text{old}} - \frac{1}{\rho} Z^\top W (Z\gamma^{\text{old}} - t).$$

where $\mathcal{H}(\cdot; s)$ keeps the s largest entries of y , sets others to zero.

A Global Convergence Theorem

- ▶ We **rigorously proved** the algorithm has global convergence
- ▶ Let $\rho \geq \|Z^\top W Z\|_2$, with $\|\cdot\|_2$ the matrix **spectral norm**.
- ▶ For any initial point $\gamma^{(0)}$ satisfying $\|\gamma^{(0)}\|_0 \leq s$ and $\|\gamma^{(0)}\|_2 = 1$, the sequence $\{\gamma^{(k)}\}$ generated by the SISR algorithm produces non-increasing (and thus **convergent**) function values:

$$l(\gamma^{(k+1)}) \leq l(\gamma^{(k)}) \quad \text{for all } k \geq 0.$$

- ▶ Furthermore, if $\rho > \|Z^\top W Z\|_2$, $\|\gamma^{(k+1)} - \gamma^{(k)}\|_2 \rightarrow 0$ as $k \rightarrow \infty$.

SISR Algorithm Outline

Input: $\nu = [\nu_A]_{A \subseteq 2^F} \in \mathbb{R}^{2^p}$ (baseline-adjusted, such that $\nu_\emptyset = 0$), sparsity level s , initial vector $t^{(0)} \in \mathbb{R}^{2^p}$, and the design matrix $Z \in \mathbb{R}^{2^p \times p}$ and diagonal weight matrix W as constructed before.

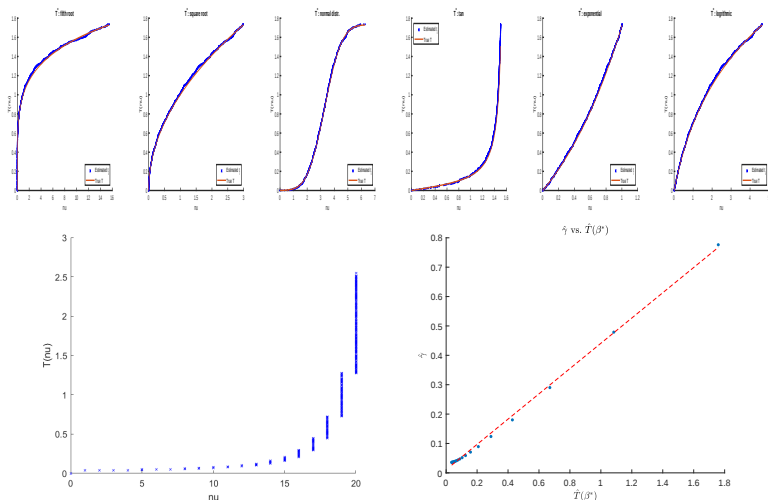
- 1: Initialize $t \leftarrow t^{(0)}$, $\gamma \leftarrow 0$
- 2: $\rho \leftarrow \|Z^\top W Z\|_2$
- 3: **repeat**
- 4: **while** not converged **do**
- 5: $\xi \leftarrow \mathcal{H}(\gamma - \frac{1}{\rho} Z^\top W (Z\gamma - t); s)$
- 6: $\gamma \leftarrow \frac{\xi}{\|\xi\|_2}$
- 7: **end while**
- 8: $\delta \leftarrow Z\gamma$
- 9: Update t by fitting a weighted isotonic regression (W, Z) to δ
- 10: **until** convergence
- 11: **return** t, γ

Data Insights

- ▶ **Domain adaptation:** Strong evidence that SISR accurately recovers the underlying transformation $\hat{T}$.
- ▶ **Sparsity recovery:** Robust SISR support recovery even in challenging settings; lower sparsity yields faster computation.
- ▶ **Feature dependence and irrelevance:** Correlation drives curvature; sparsity yields piecewise behavior with distinct-slope segments. (Even without correlation, irrelevant features can distort raw worths, undermining additivity.)
- ▶ **Prostate data:** Plain Shapley can assign spurious importance with correlated or irrelevant predictors; SISR's importance aligns with corroborating diagnostics.
- ▶ **Boston housing:** Standard Shapley ranks/signs shift with payoff scaling; SISR remains stable, preserving interpretation.

Domain Adaptation

- SISR accurately recovers the true T^* for various **nonlinear** forms (top: 5th root, sqrt, normal, tan, exp, log; bottom: max)

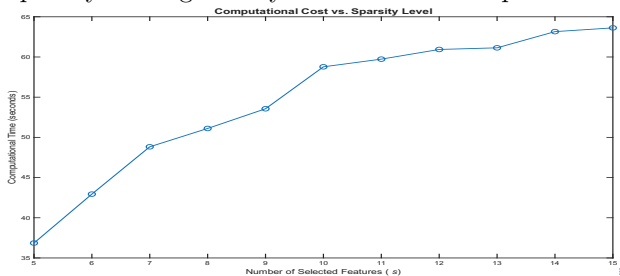


Sparsity Recovery

- **Affn:** $\langle \hat{\gamma}, \gamma^* \rangle \times 100$, **affinity** to measure estimation accuracy
- **Supp:** $|\text{supp}(\hat{\gamma}) \cap \text{supp}(\gamma^*)|/s^* \times 100\%$, support recovery rate for correct feature identification. (Tuning: RIC)
- The support recovery rate remains surprisingly strong even under challenging cases—SISR consistently identifies the correct features

noise scale	5e-3		1e-2		5e-2		1e-1		2e-1	
	Affn	Supp	Affn	Supp	Affn	Supp	Affn	Supp	Affn	Supp
$p = 10$	99.6	100%	99.5	100%	97.9	100%	88.7	98.7%	66.2	80.7%
$p = 15$	99.9	100%	97.8	100%	79.9	100%	70.9	98.0%	57.6	73.3%
$p = 20$	87.9	100%	80.3	100%	68.9	100%	63.2	96.0%	54.3	65.3%
$p = 25$	74.0	100%	70.5	100%	65.5	100%	60.6	90.7%	52.1	62.0%

- Lower sparsity levels generally lead to faster computation



R^2 -Payoffs

- ▶ Standard R^2 -constructed payoffs fail to satisfy Shapley!
 - Both **correlated** and **irrelevant** features induce strong nonlinearity
 - **Correlation** drives curvature; **sparsity** introduces breaks.
- ▶ SISR adaptively learns the transformation needed to calibrate payoffs and restore additivity. ($\theta : x_i \sim N(0, \Sigma), \Sigma_{ij} = \theta^{|i-j|}$)

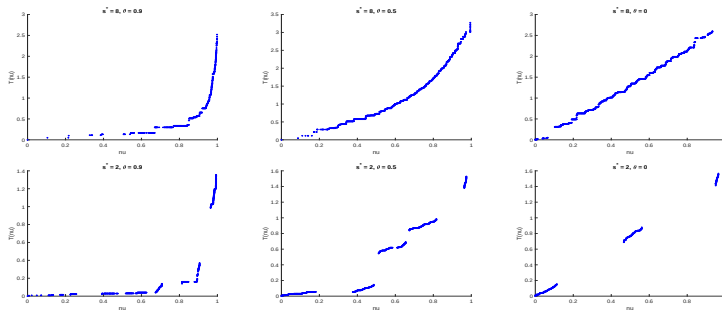


Figure: Estimated $\hat{T}(\nu)$ across varying **sparsity** levels ($s = 8, 2$, top to down) and **feature correlation** strengths ($\theta = 0.9, 0.5, 0$, left to right).

Case Study: Prostate Cancer

- ▶ Response: $\log(\text{cancer volume})$ (`lcavol`). Predictors: age (`age`), seminal vesicle invasion (`svi`, binary), $\log(\text{capsular penetration})$ (`lcp`), $\log(\text{prostate specific antigen})$ (`lpsa`), and so on.

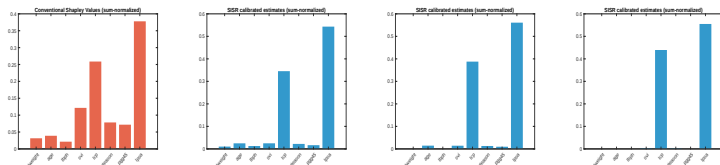


Figure: Raw Shapley (left) and SISR-calibrated values ($s = 8, 6, 4$); RIC identifies $s = 6$ as optimal.

- ▶ Both methods agree that `lcp` and `lpsa` are dominant
- ▶ `svi`: Naive Shapley ranks it **3rd** ($> 10\%$), while SISR-calibrated $\hat{\gamma}$ gives it nearly **zero**.
 - Independent checks: Stepwise AIC/BIC both exclude `svi`; very last variable selected by LASSO; p -value = 0.6 in the full model.

Case Study: Boston Housing

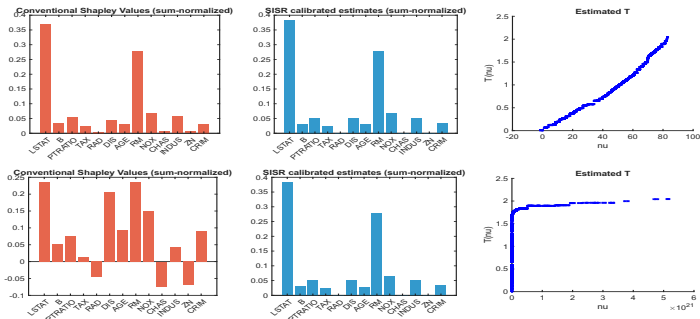


Figure: Top: MSE payoff, bottom: Exponential payoff

- ▶ Trained **XGBOOST** to predict median home value
- ▶ Standard Shapley values are **highly sensitive** to the payoff scale!
 - The importance of DIS increases from minor to **leading**
 - CHAS and other variables even receive **negative** attributions
- ▶ In contrast to sign and rank changes, SISR remains **robust**, learning a nonlinear transformation that yields stable attributions

Limitations

- ▶ **Scalability:** Coalition-level objects live in dimension 2^p ($t \in \mathbb{R}^{2^p}$ and $Z \in \mathbb{R}^{2^p \times p}$), and the isotonic step runs over all subsets.
 - In practice, handling $p > 25$ is difficult without **randomized**/approximate strategies.
- ▶ **Outlier sensitivity:** Extreme coalition payoffs (ν_A) can contaminate the estimation of T
 - They can bend $\hat{T}$ toward extremes and biasing attributions
- ▶ **No uncertainty quantification:** We only provide point estimates for T and γ with no standard errors or CIs.

Future Directions

- ▶ **Randomized PAV:** Develop an approximate, streaming/distributed isotonic solver for $T(\cdot)$.
- ▶ **Robust SISR:** Replace the quadratic loss with *robust* alternatives (e.g., L1, Huber loss) to learn a transformation that is more resilient to data imperfections.
- ▶ **Payoff Pooling:** *Integrate* diverse payoff specifications to enhance stability of feature rankings, and construct an aggregated surrogate model

Conclusions and Contributions

- ▶ We introduced **SISR**, the first unified framework to address **nonlinearity** and **sparsity** in Shapley-based explanations.
- ▶ First to show that **irrelevant** features and inter-feature **dependencies** can induce nonlinearity in payoff structures.
- ▶ It learns a data-driven payoff transformation **nonparametrically** (via PAVA) *without* a predefined basis expansion or other parametric representation, and enforces sparsity inherently.
- ▶ Simple and efficient closed-form updates with **theoretical** convergence guarantees.
- ▶ Extensive experiments show SISR stabilizes attributions and correctly identifies relevant features, avoiding **rank/sign** distortions common in standard Shapley values, offering an **interpretable** framework for complex XAI attribution tasks.

Acknowledgements

I would like to express my deepest gratitude to my mentor, **Dr. Gil Alterovitz**, for his unwavering support and encouragement.

I am also sincerely grateful to **Dr. Ning Xie** and **Pei Shaojun** for their insightful suggestions and coordination throughout this project.

Finally, my thanks to the **PRIMES program** for providing this wonderful research opportunity.