# <span id="page-0-0"></span>General Representation Theory and Representations of Finite Groups

Jack Doyle, Lanxuan Xia Mentor: Ivan Motorin

December 18, 2024 MIT PRIMES Conference

#### <span id="page-1-0"></span>[Associative unital algebras](#page-2-0)

- **•** [Algebra](#page-3-0)
- **•** [Representations](#page-4-0)
- [Radicals](#page-9-0)

### 2 [Group Representations](#page-11-0)

- **•** [Groups](#page-12-0)
- **•** [Representations](#page-15-0)
- **[Characters](#page-19-0)**

4 D F

Þ

#### <span id="page-2-0"></span>[Associative unital algebras](#page-2-0)

- [Algebra](#page-3-0)
- **•** [Representations](#page-4-0)
- [Radicals](#page-9-0)

#### **[Group Representations](#page-11-0)**

- **[Groups](#page-12-0)**
- **•** [Representations](#page-15-0)
- [Characters](#page-19-0)  $\begin{array}{c} \bullet \\ \bullet \end{array}$

4 D F

Þ

<span id="page-3-0"></span>An associative algebra A is a vector space over a field  $k$  with an associative bilinear multiplication

 $\cdot$   $\cdot$   $A \times A \rightarrow A$ 

Furthermore, we say that A is unital if A has an element 1 such that

$$
a\cdot 1=1\cdot a=a, \quad \forall a\in A
$$

We will only work with unital algebras.

#### **Examples**

- The matrix algebra  $Mat_n(k)$  over k with basis  $E_{ii}$ ,  $1 \le i, j \le n$ , such that  $E_{ii} \cdot E_{kl} = \delta_{ik} E_{il}$  ( $\delta_{ik} = 1$  if  $j = k$  and zero otherwise).
- The free algebra  $A = k\langle x_1, \ldots, x_n \rangle$  has a basis of words in letters  $x_1, \ldots, x_n$  $x_1, \ldots, x_n$  $x_1, \ldots, x_n$  $x_1, \ldots, x_n$ . The product of two words is giv[en](#page-2-0) [by](#page-4-0) [co](#page-3-0)n[c](#page-2-0)[ate](#page-3-0)n[a](#page-1-0)[t](#page-2-0)[i](#page-10-0)[o](#page-11-0)[n.](#page-0-0)

<span id="page-4-0"></span>A finite dimensional representation of an associative algebra A is a finite dimensional vector space V with homomorphism of algebras

$$
\rho:A\to \mathsf{End}\,V.
$$

In other words,  $\rho(*)$  is a k-linear map that preserves multiplication and unit.

#### **Examples**

•  $V = A$ , for  $\rho : A \rightarrow End A$ ,  $\rho(a)$  is the operator of left multiplication by a. This is known as the regular representation.

# Definition

A subrepresentation U of V of an algebra A is a vector subspace  $U \subset V$ invariant under operators  $\rho(a): V \to V$ ,  $\forall a \in A$ .

A representation  $V$  is called irreducible if its only subrepresentations are  $V$ and 0.

## Definition

A direct sum of representations  $(V_1, \rho_1)$  and  $(V_2, \rho_2)$  is the vector space  $V_1 \oplus V_2 = \{ (v_1, v_2) | v_1 \in V_1, v_2 \in V_2 \}$  with  $\rho$  defined by  $\rho(a)(v_1, v_2) = (\rho_1(a)v_1, \rho_2(a)v_2)$  where  $v_1 \in V_2$ ,  $v_2 \in V_2$ , and  $a \in A$ .

#### Definition

A representation V is called indecomposable if it cannot be written as the direct sum of two nonzero subrepresentations.

#### Remark

The main goals in representation theory are to:

- Classify all irreducible representations of an algebra A.
- Classify all indecomposable representations of A.

We will only work with finite dimensional algebras and representations.

 $\Omega$ 

A homomorphism between two representations  $V_1$  and  $V_2$  denoted by  $\phi: V_1 \to V_2$  is a linear map that commutes with the action of A, so  $\phi(av) = a\phi(v)$  for any  $v \in V_1$  and  $a \in A$ .

## Lemma (Schur's lemma)

Suppose  $V_1, V_2$  are representations of an algebra A. Let  $\phi: V_1 \rightarrow V_2$  be a nonzero homomorphism of representations. Then: a) If  $V_1$  is irreducible, then  $\phi$  is injective. b) If  $V_2$  is irreducible, then  $\phi$  is surjective. c) If  $V_1$  and  $V_2$  are both irreducible,  $\phi$  is an isomorphism.

A semisimple representation, also known as completely reducible, is a direct sum of irreducible representations

4 D F

Þ

 $QQ$ 

<span id="page-9-0"></span>The radical of a finite dimensional algebra A, denoted  $Rad(A)$ , is the set of elements in A that act by 0 in all irreducible representations of A.

## **Definition**

- $\bullet$  A left ideal I of an algebra A is a vector subspace of A that satisfies the condition that for every  $a \in A$  and  $x \in I$ ,  $a \cdot x \in I$ .
- A right ideal I is the subspace of A with the condition that  $x \cdot a \in I$ for all  $a \in A$ ,  $x \in I$ .
- A two-sided ideal is a subspace of A which is both a left and a right ideal.

#### Remark A radical is necessarily a two-sided ideal.  $290$ 4日下 Doyle, Xia [Representation Theory](#page-0-0) December 18, 2024 10 / 25

<span id="page-10-0"></span>A finite dimensional algebra A is semisimple if  $Rad(A) = 0$ .

#### Theorem

The following are equivalent for finite dimensional algebra A:

1. A is semisimple;

2.  $\sum_i(\mathsf{dim} \mathsf{V}_i)^2=\mathsf{dim} \mathsf{A}$ , with  $\mathsf{V}_i$  's being the distinct irreducible representations of A.

3.  $A \cong \bigoplus_i Mat_{d_i}(k)$  for certain  $d_i$ .

4. Any finite dimensional representation of A is semisimple, i.e. completely reducible (hence why these algebras are also known as semisimple). 5. A is completely reducible representation of A.

 $QQ$ 

イロト イ押ト イヨト イヨ

#### <span id="page-11-0"></span>[Associative unital algebras](#page-2-0)

- **•** [Algebra](#page-3-0)
- **•** [Representations](#page-4-0)
- **•** [Radicals](#page-9-0)

#### 2 [Group Representations](#page-11-0)

- **•** [Groups](#page-12-0)
- **•** [Representations](#page-15-0)
- **[Characters](#page-19-0)**

4 D F

重

# <span id="page-12-0"></span>Group Theory

• A group represents the symmetries of an object.

#### Definition

A group G is a set with an operation  $\cdot : G \times G \rightarrow G$  (multiplication), satisfying the following requirements:

- Associative:  $(a \cdot b) \cdot c = a \cdot (b \cdot c)$ ,
- **Identity:** There is an  $e \in G$  such that  $a \cdot e = e \cdot a = a$ .
- **Inverse:** There is an  $a^{-1} \in G$  such that  $a \cdot a^{-1} = a^{-1} \cdot a = e$ ,

for all  $a, b, c \in G$ .

• Implicitly, a group is closed under multiplication.

#### **Definition**

A group homomorphism  $f: G \rightarrow H$  for two groups  $G, H$  is a map f such that  $f(g_1 \cdot g_2) = f(g_1) \cdot f(g_2)$  for all  $g_1, g_2 \in G$ . It's an isomorphism if f is bijective.

- $S_3$  is the group of permutations of three elements. So each  $\sigma \in S_3$ maps  $\sigma : \{1, 2, 3\} \to \{1, 2, 3\}$
- Multiplication: compose permutations.
- Identity permutation e maps  $x \mapsto x$ .
- We can describe permutations in terms of cycles.



Fig.1. Some permutations in  $S_3$ .

Sign of permutation: even/odd number of transpositions.

つひひ



Fig.2. Flips and Rotations in  $D_3$ .

- Combining these flips and rotations, we can get 6 possible configurations. So  $|D_3| = 6$ .
- It turns out that all possible permutations of vertices are obtainable in  $D_3$ . So  $D_3 \cong S_3$ .

 $\Omega$ 

<span id="page-15-0"></span>The group  $GL(V)$  of all invertible linear maps from a finite-dimensional k-vector space V to itself is called the general linear group of  $V$ .

#### Definition

Let G be a finite group. A representation of G is a finite-dimensional k-vector space V, with a homomorphism  $\rho_V : G \to GL(V)$ .

- Informally, a representation describes how a group acts on a vector space.
- Such a representation is equivalent to a finite-dimensional representation of the **group algebra** k[G], with basis  $\{a_{\varepsilon} | g \in G\}$  and the multiplication rule  $a_g \cdot a_h = a_{gh}$ .
- $\bullet$  Let us fix a field  $k = \mathbb{C}$ .

◂**◻▸ ◂◚▸** 

 $\Omega$ 

# Example: Cyclic Groups

• Consider the group  $C_n$  of order *n* generated by the element g. It contains the elements

$$
g,g^2,g^3,\ldots,g^n=e
$$

We call such a group cyclic.

- $\bullet$  There are precisely n non-isomorphic irreducible representations of G, all of which are one-dimensional.
- Let  $\zeta$  be a primitive *n*-th root of unity. Then we have the irreducible representations  $\mathbb{C}_1, \ldots, \mathbb{C}_n$ , with homomorphism

$$
\rho_k(g):=\zeta^k,
$$

and hence in general,

$$
\rho_k(g^a)=\zeta^{ak}.
$$

つへへ

# Example: Representations of  $S_3$

- Consider  $S_3$ , the symmetric group, describing permutations of 3 elements.
- There are two one-dimensional representations of  $S_3$ :
	- The trivial representation,  $\mathbb{C}_+$ , with  $\rho(g) := 1$ .
	- The sign representation  $\mathbb{C}_-$ , with  $\rho(g) := \text{sign}(g)$ .
- Recall that  $S_3 \cong D_3$ . So we have the **dihedral** representation  $\mathbb{C}^2$ , with  $\rho: S_3 \to GL_2(\mathbb{C})$ :

$$
\rho((12)) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}
$$

$$
\rho((123)) = \begin{pmatrix} \cos \frac{2\pi}{3} & -\sin \frac{2\pi}{3} \\ \sin \frac{2\pi}{3} & \cos \frac{2\pi}{3} \end{pmatrix}
$$

• The tautological representation  $T: \rho: S_3 \to GL_3(\mathbb{C})$ , which sends each element to the corresponding permutation  $3 \times 3$  permutation matrix.

# Theorem (Maschke)

Let G be a finite group. Then  $\mathbb{C}[G]$  is semisimple. Equivalently, if V is a representation of G then we can write

$$
V=V_1\oplus\cdots\oplus V_n,
$$

where the  $V_i$  are (not necessarily distinct) irreducible representations of G.

### Corollary (Sum-of-squares)

Let  $V_1, \ldots, V_s$  be the non-isomorphic irreducible representations of G. Then

$$
|G|=\sum_{i=1}^s \dim(V_i)^2.
$$

<span id="page-19-0"></span>Let V be a representation of G. Then define the character  $\chi_V : G \to \mathbb{C}$  as

$$
\chi_V(g):= \mathsf{Tr}|_V(\rho_V(g)).
$$

• The irreducible characters form an basis of  $F_c(G, \mathbb{C})$ , the space of class functions  $G \to \mathbb{C}$ .

4 0 8

э

 $\Omega$ 

# Orthogonality Relations

• The irreducible characters form an **orthonormal** basis of  $F_c(G, \mathbb{C})$ , under the form  $\langle , \rangle$ , defined as

$$
\langle f_1,f_2\rangle:=\frac{1}{|G|}\sum_{g\in G}f_1(g)\overline{f_2(g)}.
$$

### Theorem (Orthogonality Relations)

Let V and W be representations of G. Then

$$
\langle \chi_V, \chi_W \rangle = \dim \mathrm{Hom}_G(W, V)
$$

Moreover, if V and W are irreducible, then

$$
\langle \chi_V, \chi_W \rangle = \begin{cases} 1 & \text{if } V \cong W \\ 0 & \text{if } V \not\cong W \end{cases}
$$

#### **Corollary**

Let V be a representation of G. If  $\langle \chi_V, \chi_V \rangle = 1$ , then V is irreducible.

#### Proof.

 $\operatorname{Hom}_G(V, V) = \langle \chi_V, \chi_V \rangle = 1$  is trivial, so there are no proper subrepresentations  $W \subset V$ .

This gives us an easy way to check if a representation is irreducible.

### **Corollary**

The number of irreducible representations of G is equal to the number of conjugacy classes of G.

 $QQ$ 

イロト イ母ト イヨト イヨト

Character tables let us visualize these orthogonality relations.



Fig.3. Irreducible characters of  $S_3$ .

- Characters evaluated on representative elements.
- This shows that  $\mathbb{C}_+$ ,  $\mathbb{C}_-$ , and  $\mathbb{C}^2$  are the  $\mathsf{only}$  irreducible representations (up to an isomorphism) of  $S_3$ , since:
	- $\langle \chi_i, \chi_i \rangle = 1$
	- Sum-of-squares satisfied.
- We also have the Second Orthogonality Relations, for the columns of the character table.

# Burnside's Theorem

### Definition

- We say a group is abelian if its elements commute. For example, the group  $\mathbb{C}^\times=\mathbb{C}\setminus\{0\}$  under multiplication.
- A subgroup  $H \subset G$  is normal if for all  $g \in G$ ,  $h \in H$ , we have ghg<sup>-1</sup> = H. Then we write  $H \triangleleft G$ .
- A group G is solvable if there exists a sequence of proper normal subgroups

$$
\{1\} = G_1 \triangleleft \cdots \triangleleft G_n = G
$$

such that the successive quotients  $G_{i+1}/G_i$  are all abelian.

Suppose G is a group of order  $|G|=p^aq^b$ , where p and q are primes, and  $a, b > 0$ . Then G is solvable.

 $200$ 

イロト イ押ト イヨト イヨト

# Burnside's Theorem

### Definition

- We say a group is abelian if its elements commute. For example, the group  $\mathbb{C}^\times=\mathbb{C}\setminus\{0\}$  under multiplication.
- A subgroup  $H \subset G$  is normal if for all  $g \in G$ ,  $h \in H$ , we have  $ghg^{-1} = H$ . Then we write  $H \triangleleft G$ .
- A group G is solvable if there exists a sequence of proper normal subgroups

$$
\{1\} = G_1 \triangleleft \cdots \triangleleft G_n = G
$$

such that the successive quotients  $G_{i+1}/G_i$  are all abelian.

#### Theorem (Burnside)

Suppose G is a group of order  $|G| = p^a q^b$ , where p and q are primes, and  $a, b > 0$ . Then G is solvable.

 $200$ 

 $\left\{ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right.$ 

<span id="page-25-0"></span>

### P. Etingof. et al.

Introduction to Representation Theory. AMS, 2011.



#### M. Artin.

Algebra (2nd ed.) Prentice Hall, 2011.

4 D F

э