

# Knot Theory

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# What Is A Knot?

## Definition (Knot)

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# What Is A Knot?

## Definition (Knot)

A **knot** is a closed curve in space that does not intersect itself anywhere and is embedded in three dimensions.

## Definition (Link)

Informally, a **link** is a set of knots that are knotted together. The number of knots is called the number of **components**.

# Essential Questions in Knot Theory

In this presentation, we address two important questions in Knot Theory:

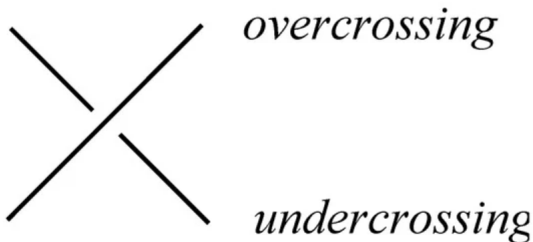
- How can we distinguish knots?
- How can we tell if two knots are the same?

# Representing Knots

We use a knot's projection in the 2D plane to represent it. We can use arrows to denote a knot's direction that one is traveling in while they trace the knot.

## Definition (Crossing)

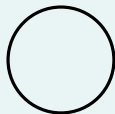
A **crossing** is a point in a knot's projection where it crosses itself.



# Important Knots

## Example (Unknot)

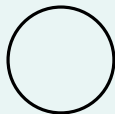
The **unknot** or **trivial knot** is a knot that has a projection with 0 crossings.



# Important Knots

## Example (Unknot)

The **unknot** or **trivial knot** is a knot that has a projection with 0 crossings.



## Example (Trefoil Knot)

The **trefoil** knot is represented as below. It is a nontrivial knot with the least number of crossings.



# Knot Composition

## Definition (Composition)

We define **knot composition** as a process to combine two knots into one according to the following steps:

- 1 Remove an arc from the outside of each knot projection
- 2 Connect the four endpoints with two new arcs. If this introduces a new crossing, select a different arc to remove in step 1.

For two knots  $J$  and  $K$ ; we denote their composition as  $J\#K$ :

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## Example

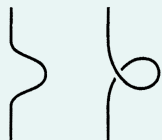
# Reidemeister Moves

## Definition (Reidemeister Moves)

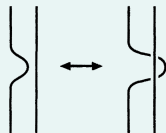
A **Reidemeister move** is one of three moves that change the projection of a knot while preserving the knot.

Kurt Reidemeister showed that a series of Reidemeister moves and planar isotopies can relate any two projections of the same knot.

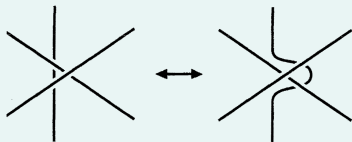
## Example



Type I



Type II



Type III

# Invariants

## Definition (Knot Invariant)

A **knot invariant** is a quantity or a property of a knot that remains unchanged by ambient isotopy, i.e. by Reidemeister moves or planar isotopies.

# Tricolorability

## Definition (Strand)

For any projection of a link, we define a **strand** to be a segment of the link projection that connects two undercrossings with only overcrossings in between.

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## Definition (Tricolorability)

A link is **tricolorable** if we can color each of its strands one of 3 different colors according to the following two rules:

- 1 At every crossing, either all the strands are the same color or they are all different colors
- 2 At least 2 of the 3 colors are used

# Tricolorability Examples

## Example (The Unknot)

The unknot only has one strand, so at most we can use one color to color it. This fails the condition that we use at least 2 out of the 3 colors, so the unknot is not tricolorable.

# Tricolorability Examples

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## Example (Trefoil Knot)

The trefoil knot is tricolorable, as shown below.



# Tricolorability As An Invariant

## Theorem

*Reidemeister moves preserve tricolorability.*

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## Proof.

Since Reidemeister moves preserve tricolorability, there is no sequence of Reidemeister moves that will change a projection of a tricolorable knot to a knot that is not tricolorable. It follows that the unknot and trefoil knot are distinct up to Reidemeister moves, as desired.  $\square$

# Linking Number

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## Example ( $6_3$ knot)

# Linking Number as an Invariant

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## Example

Type III Reidemeister moves don't change linking number

# Surfaces

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Informally, a **surface** or two-manifold is defined as an object such that every point on the object has a neighborhood contained within the object that is “equivalent” to a disk.



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## Definition (Homeomorphism)

A **homeomorphism** is a bijective, continuous map between surfaces such that its inverse map is also continuous.

# Genus

Definition (Genus of a surface)

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## Theorem

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# Surfaces With Boundary

## Definition (Boundary Component)

A surface with boundary is a surface without boundary where at least one open disk, called a **boundary component**, has been removed.



# Orientability

## Definition (Orientable surface)

A surface in a three-dimensional space is **orientable** if it has two sides we can paint two different colors so that the two colors only meet along the boundary of a surface. A surface that does not satisfy this property is **nonorientable**.

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## Example (Möbius Band)

A Möbius Band is *nonorientable* because if we were to start painting a side one color, we would find that we've painted the whole surface that same color because it only has one side.

# Seifert Surfaces

A Seifert surface for a knot  $K$  is an orientable surface with a boundary component that is the given knot  $K$ .



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Definition (Genus of a knot)

The genus of a knot  $K$  is the minimal genus of any Seifert surface of  $K$ .

# Seifert's Algorithm

Algorithm (Seifert Algorithm)

Seifert's algorithm constructs a Seifert surface  $S$  for any given projection of a knot  $K$ .

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## Proposition

*The trivial knot is the only knot with genus 0, because it is the only knot that is the boundary of an embedded disk.*

Given a knot  $K$ , let  $g(K)$  be the genus of  $K$ . Then,

$$g(J \# K) = g(J) + g(K):$$

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Because genus is nonnegative, all nontrivial knots have genus  $\geq 1$ . By our earlier theorem, the composition of two nontrivial knots then has genus  $\geq 2$  and therefore is not the trivial knot, which has genus 0. Hence, the trivial knot must be prime.  $\square$

# Acknowledgements

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- Our families
- The audience for listening to this presentation



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