

Velocity Inversion Using the Quadratic Wasserstein Metric

Srinath Mahankali

Mentor: Prof. Yunan Yang (NYU)

Stuyvesant High School

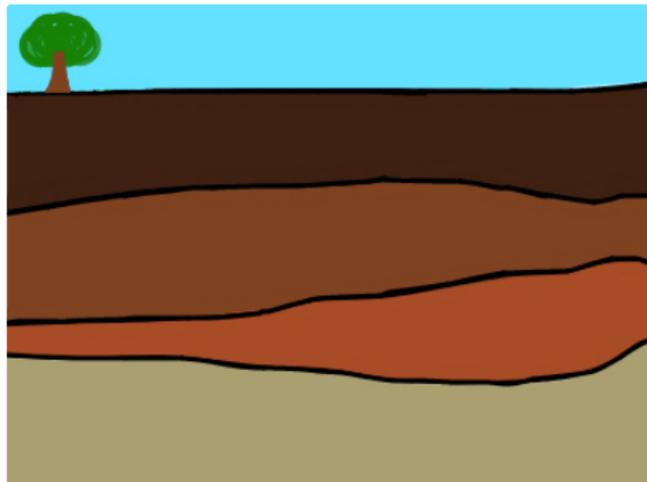
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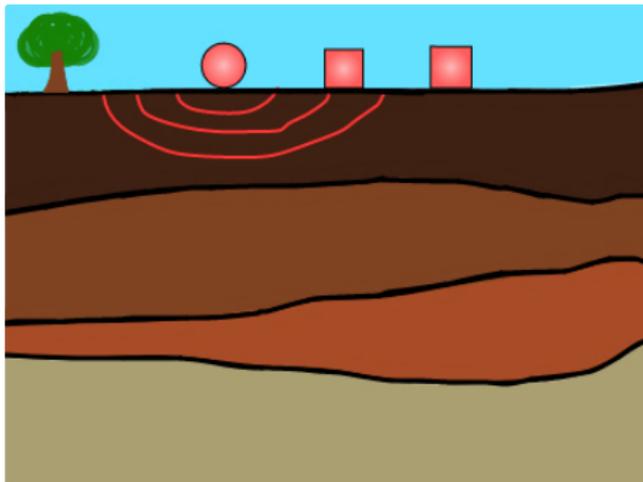
Motivation

- Goal: find materials lying underground and their positions



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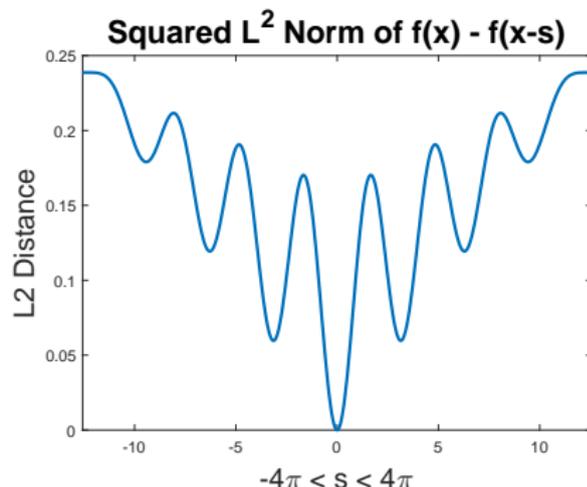
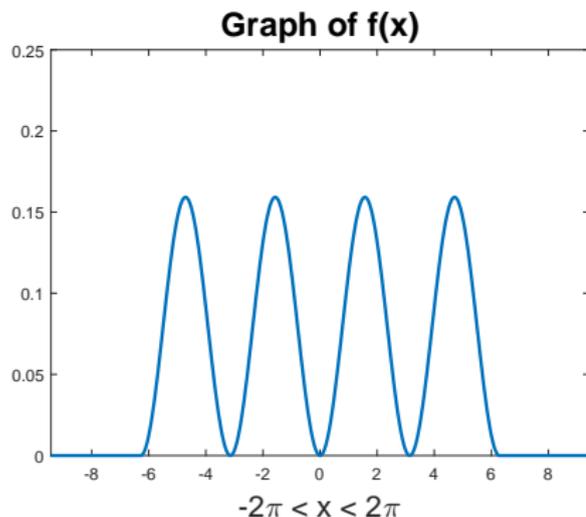
- $$\begin{cases} \frac{1}{c(\mathbf{x})^2} \frac{\partial^2 \psi}{\partial t^2} - \left(\frac{\partial^2 \psi}{\partial x_1^2} + \frac{\partial^2 \psi}{\partial x_2^2} + \cdots + \frac{\partial^2 \psi}{\partial x_n^2} \right) = f(\mathbf{x}, t), \\ \psi(\mathbf{x}, 0) = 0, \psi_t(\mathbf{x}, 0) = 0 \text{ on } \Omega, \\ \nabla \psi \cdot \mathbf{n} = 0 \text{ on } \partial\Omega \end{cases}$$

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- $\mathcal{C}^*(\mathbf{x}) = \operatorname{argmin} J(g(\mathcal{C}), h)$ where J is the objective function
- Convexity with respect to the velocity is beneficial

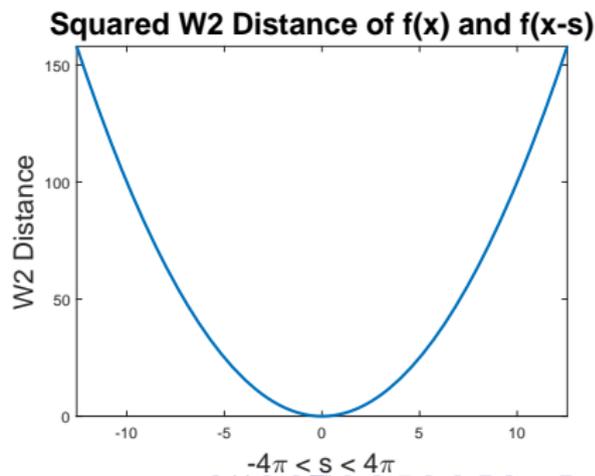
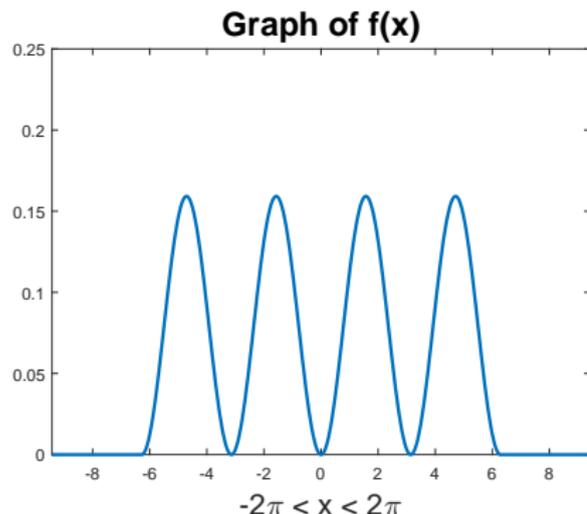
Problems With the Squared L^2 Norm

- Beydoun-Tarantola, 1988
 - Nonconvexity of squared L^2 norm and local minima
- Brossier et al, 2010
 - Sensitivity of L^2 norm to noise



An Alternative Objective Function

- Engquist-Froese, 2013 introduced the Wasserstein metric for FWI
- Yang, 2019
 - Convexity in translations and dilations of the data
 - Insensitivity to noise
- Engquist et al, 2020
 - Low-frequency bias



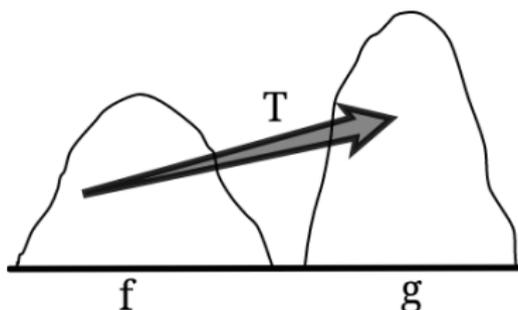
What is the Wasserstein Metric?

- Optimal transport introduced by Monge

Definition

The p^{th} Wasserstein metric is defined as

$$W_p(f, g) = \left(\inf_{T \in \mathbb{M}(\mu, \nu)} \int_{\Omega} |x - T(x)|^p d\mu \right)^{\frac{1}{p}}.$$



What is the Wasserstein Metric?

- Explicit formula when data is in one dimension

Theorem

Let \tilde{g} and \tilde{h} be two probability distributions defined on \mathbb{R} , and let $G(t) = \int_{-\infty}^t \tilde{g}(s) ds$ and $H(t) = \int_{-\infty}^t \tilde{h}(s) ds$. Then

$$W_2^2(\tilde{g}, \tilde{h}) = \int_0^1 (G^{-1}(s) - H^{-1}(s))^2 ds.$$

The Constrained Optimization Problem

- $$\begin{cases} \frac{1}{c(\mathbf{x})^2} \frac{\partial^2 \psi}{\partial t^2} - \left(\frac{\partial^2 \psi}{\partial x_1^2} + \frac{\partial^2 \psi}{\partial x_2^2} + \cdots + \frac{\partial^2 \psi}{\partial x_n^2} \right) = f(\mathbf{x}, t), \\ \psi(\mathbf{x}, 0) = 0, \psi_t(\mathbf{x}, 0) = 0 \text{ on } \Omega, \\ \nabla \psi \cdot \mathbf{n} = 0 \text{ on } \partial\Omega \end{cases}$$

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- $C^*(\mathbf{x}) = \operatorname{argmin} W_2^2(g(C), h)$

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- $\mathcal{C}^*(\mathbf{x}) = \operatorname{argmin} W_2^2(g(\mathcal{C}), h)$
- Previous results involve convexity in changes of the data

Challenges and Solutions

- Wave data is generally not a probability distribution

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- Computing the W_2 distance is difficult for higher dimensions

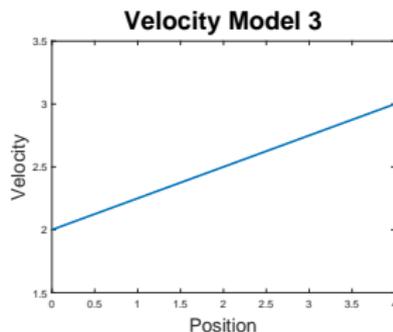
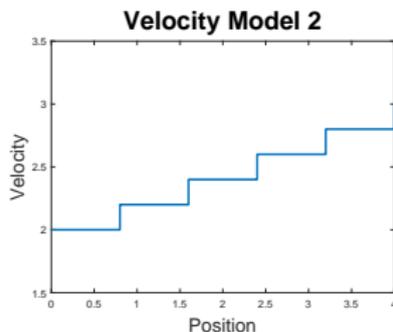
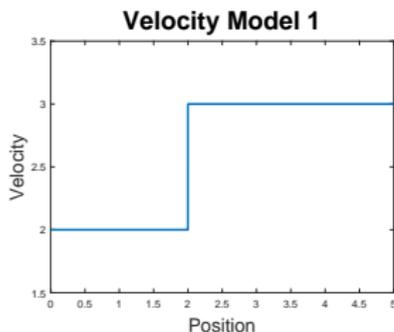
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- Computing the W_2 distance is difficult for higher dimensions
 - Data is only a function of time \rightarrow apply one dimensional formula
- No explicit solution for wave equation in general

Velocity Models in One Dimension

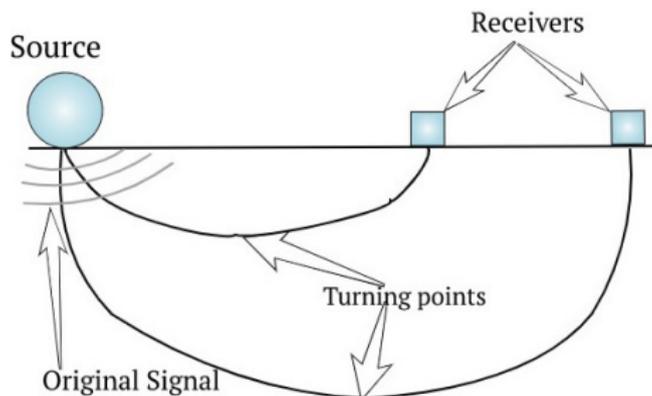


Theorem

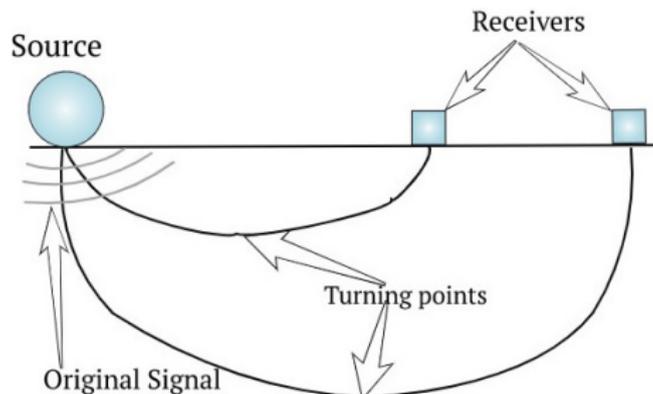
Suppose $f(t)$ is nonnegative and compactly supported, and let k be the velocity parameter in these three cases. Then $W_2^2(g(k), h)$ is convex in k over the interval $(0, k^*]$.

- Velocity function of the form $\mathcal{C}(X, z) = a + bz$

Ray Tracing



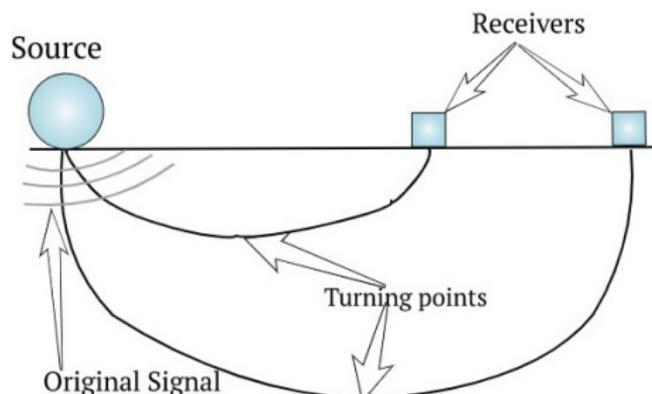
Ray Tracing



- Distance and travelttime formulas:

$$X = 2p \int_0^{z_p} \frac{dz}{\sqrt{u^2(z) - p^2}}$$
$$T = 2 \int_0^{z_p} \frac{u^2(z)}{\sqrt{u^2(z) - p^2}} dz$$

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- For source wave data $f(t)$, the predicted wave data is approximated by $A_{\text{pred}} f(t - T_{\text{pred}})$

Velocity Model in Two Dimensions

Theorem

Assume $f(t)$ is nonnegative and compactly supported. Then, $W_2^2(\tilde{g}, \tilde{h})$ is jointly convex in a, b over the following region U :

$$U := \{(a, b) \in \mathbb{R}^2 : a, b > 0, \frac{bX_r}{2a} \geq S_0, T(X_r, a, b) \geq T(X_r, a^*, b^*)\}$$

for some positive constant S_0 .

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- For large X_r , the convex region contains (a^*, b^*)

Velocity Model in Two Dimensions

Theorem

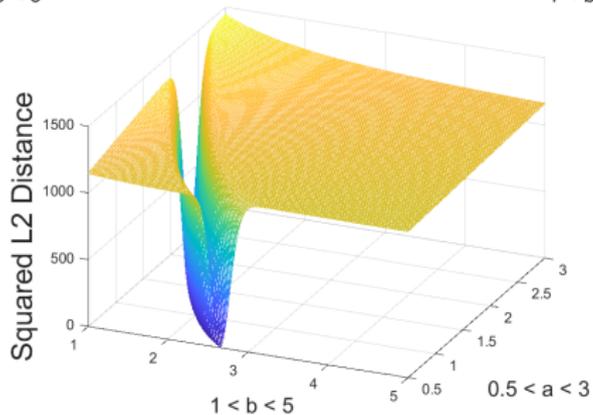
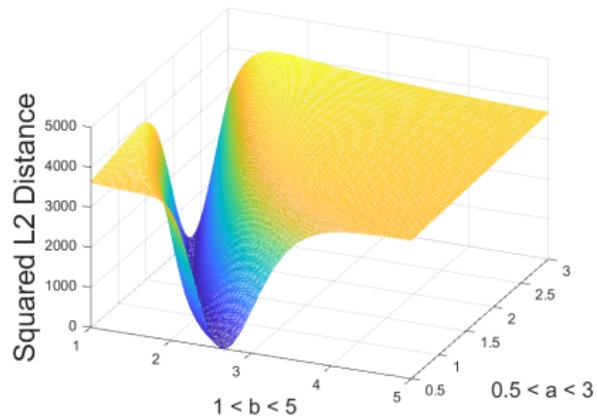
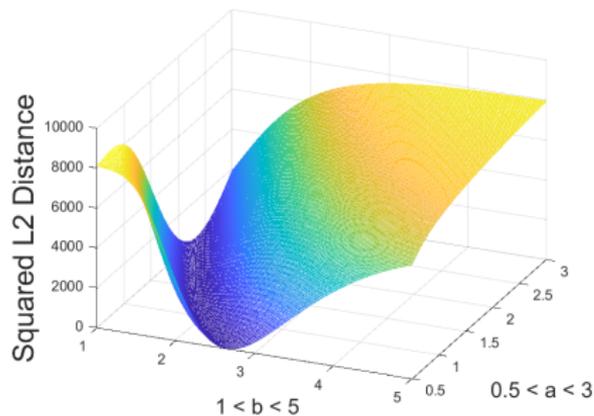
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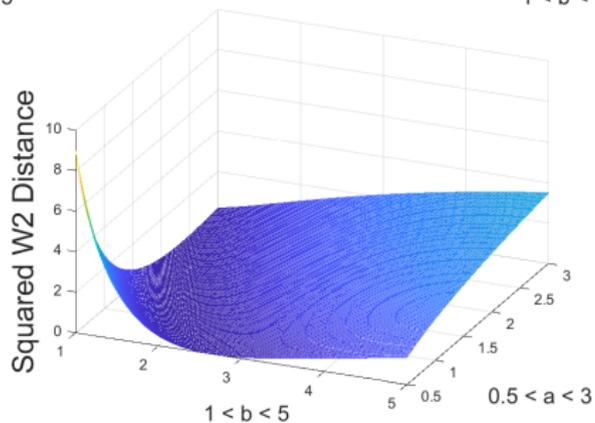
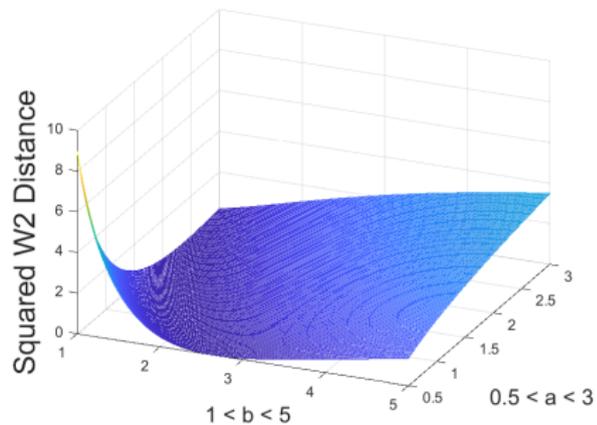
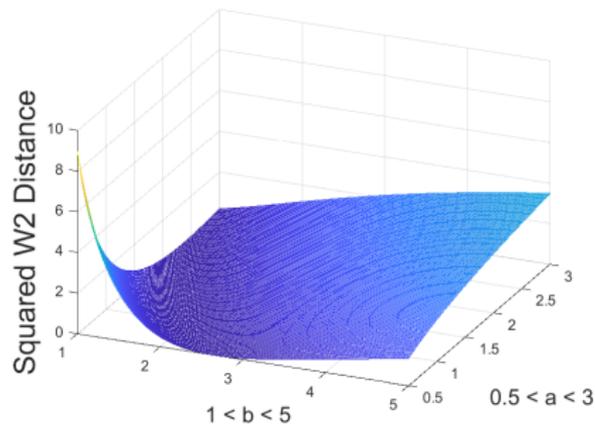
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- For large X_r , the convex region contains (a^*, b^*)
- Nonuniqueness of solution fixed by adding multiple receiver locations

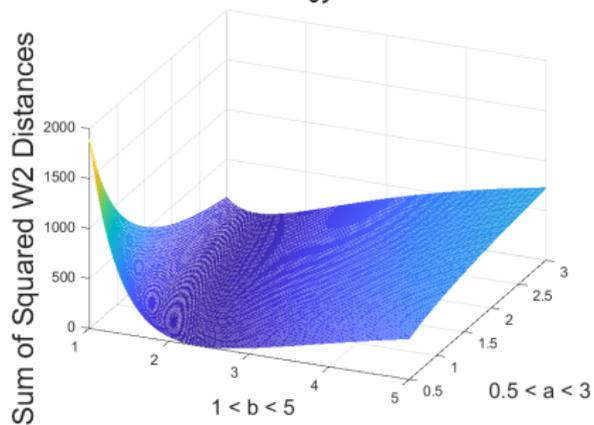
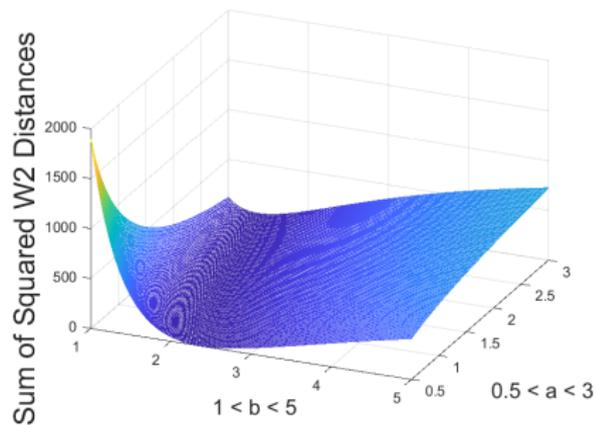
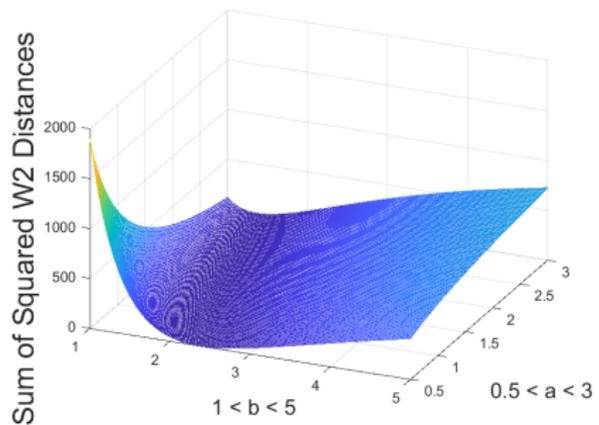
Velocity Model in Two Dimensions



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Velocity Model in Two Dimensions



- Study models with a larger number of parameters

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- Possible to study convexity using frequency instead of time domain

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Link to my paper (posted on PRIMES website):

<https://arxiv.org/abs/2009.00708>

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