# 18.336/6.335 Fast Methods for Partial Differential and Integral Equations Spring 2013 

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## 4 Integral Equation Methods

### 4.1 The Exterior Problem

Once again, let us return to the Poisson Equation:

$$
\Delta u=f, \quad x \in \Omega, \Omega \in \mathbb{R}^{d}, d=\{2,3\}
$$

However, unlike before, let us consider the exterior problem with no physical finite boundary. That is, there is no finite "box" enclosing the problem domain; instead we impose the following condition out at infinity:

$$
\lim _{|x| \rightarrow \infty} u(x)=0
$$

The exterior problem is very common. Example applications include:

- Molecular Dynamics, where $\nabla u=E$ is the electric field, and the objective is to calculate the electrostatic forces between different molecules. There is no obvious boundary to the interaction.
- The Conservation Corrector in fluid calculations, where fluid velocity correction is $\nabla u$ and $f$ comes from another part of the fluid code. The domain is a vast fluid body, e.g. the ocean.
- Electrochemistry: electrostatic potential $=u$. Charge is everywhere but yet again no definite boundary.

Consider using the finite difference approach to solve the exterior problem. The domain of interest for $u$ is usually known in advance, but the solution domain and grid must be much larger in order to approximate the boundary out at infinity. Let $K$ be the 1D Dirichlet boundary condition finite difference method matrix. The 2D case is $K \otimes I+I \otimes K$. The 3D case is $K \otimes I \otimes I+I \otimes K \otimes I+I \otimes I \otimes K$. As each kronecker product increases the dimension of the governing matrix by one exponent, it is very expensive indeed to expand the computation to approximate the radiation condition.

### 4.2 Introducing the Green's function

An alternative approach is to use integral equations. If $G\left(x-x^{\prime}\right)$ is defined such that $\int\left(\Delta_{x} G\left(x-x^{\prime}\right)\right) f\left(x^{\prime}\right) \mathrm{d} x^{\prime}=$ $f(x)$ then $\Delta_{x} G\left(x-x^{\prime}\right)=\delta\left(x-x^{\prime}\right)$. Let

$$
u(x) \equiv \int_{\Omega} G\left(x-x^{\prime}\right) f\left(x^{\prime}\right) \mathrm{d} x^{\prime}, \quad x \in \Omega
$$

then,

$$
\Delta u=f, \quad x \in \Omega
$$

Informally, this definition can be written as:

$$
\Delta G=\delta
$$

where $\delta$ is the Dirac delta generalized function.
The 2D Laplacian Green's function is the following:

$$
G_{2 D}(\boldsymbol{r})=\frac{1}{2 \pi} \ln |\boldsymbol{r}|
$$

The 3D Laplacian Green's function is:

$$
G_{3 D}(\boldsymbol{r})=\frac{1}{4 \pi} \frac{1}{|\boldsymbol{r}|} .
$$

In physics, the Green's function is known as the response due to a point charge; in electrical engineering it is known as the impulse response; in mathematics it is known as the fundamental solution. Regardless, we only want to know $u(x)$ given that $x \in \Omega_{\text {important }}$ :

$$
u(x)=\int_{\Omega_{\text {important }}} G\left(x-x^{\prime}\right) f\left(x^{\prime}\right) \mathrm{d} x^{\prime}
$$

Now we evaluate the integral numerically using quadrature:

$$
u(x) \approx \sum_{j} W\left(x_{j}\right) G\left(x-x_{j}\right) f\left(x_{j}\right)
$$

where $x_{j}$ are quadrature points and $W$ are quadrature weights. Standard quadrature is ineffective around $x=x^{\prime}$. Assuming unit areas, we can defining box averages:

$$
u_{i}=\int_{b o x, i} u\left(x^{\prime}\right) \mathrm{d} x^{\prime}
$$

and

$$
f_{i}=\int_{b o x, i} f\left(x^{\prime}\right) \mathrm{d} x^{\prime}
$$

Substituting to the original equation:

$$
\begin{aligned}
u_{b o x, i} & =\int_{b o x, i} \int_{\text {allboxes }} G\left(x-x^{\prime}\right) f\left(x^{\prime}\right) \mathrm{d} x^{\prime} \mathrm{d} x \\
& =\int_{b o x, i} \sum_{j} \int_{b o x, j} G\left(x-x^{\prime}\right) f\left(x^{\prime}\right) \mathrm{d} x^{\prime} \mathrm{d} x
\end{aligned}
$$

Suppose we make the only approximation in this problem:

$$
f(x)_{x \in b o x, j} \approx f_{b o x, j}
$$

Then we can write

$$
\begin{aligned}
u_{b o x, i} & =\int_{b o x, i} \sum_{j}\left(\int_{b o x, j} G\left(x-x^{\prime}\right) \mathrm{d} x^{\prime}\right) f_{b o x, j} \mathrm{~d} x \\
& =\sum_{j} f_{b o x, j} \int_{b o x, i} \int_{b o x, j} G\left(x-x^{\prime}\right) \mathrm{d} x^{\prime} \mathrm{d} x
\end{aligned}
$$

When discretized we can write:

$$
u_{b o x}=\overline{\bar{G}} f_{b o x}
$$

where the matrix $\overline{\bar{G}}$ is Toeplitz, but not circulant:

$$
\left[\begin{array}{c}
u_{b o x, 1} \\
u_{b o x, n}
\end{array}\right]=\left[\begin{array}{ccccc}
g_{0} & g_{-1} & g_{-2} & \cdots & g_{-n} \\
g_{1} & g_{0} & g_{-1} & \ddots & \vdots \\
g_{2} & g_{1} & g_{0} & \ddots & g_{-2} \\
\vdots & \ddots & \ddots & \ddots & g_{-1} \\
g_{n} & \cdots & g_{2} & g_{1} & g_{0}
\end{array}\right]\left[\begin{array}{c}
f_{b o x, 1} \\
\\
\\
f_{b o x, n}
\end{array}\right]
$$

We can make $\overline{\bar{G}}$ circulant by embedding it within a bigger matrix of $2 n-1$ by $2 n-1$.


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