

# On the anisotropic Calderón problem

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# Outline

Prologue: solutions to the Schrödinger equation

The anisotropic Calderón problem

Carleman weights and warped products

The geodesic ray transform

Quasimodes and semiclassical measures

# Solutions of the Schrödinger equation

**Aim:** Construct solutions of the **Schrödinger equation** on an open bounded set  $\Omega \subset \mathbf{R}^n$

$$-\Delta u + qu = 0$$

with an  $L^\infty$  potential  $q$  on  $\Omega$ .

One method: use **complex geometrical optics** solutions

Introduced by **Sylvester and Uhlmann** Construction presented in this introduction by **Kenig, Sjöstrand and Uhlmann**

## Complex geometrical solutions

Pick  $x_0$  **not in** the convex hull of  $\bar{\Omega}$ .

Coordinates in  $\bar{\Omega}$

$$t = \log |x - x_0| \in \mathbf{R}, \quad \omega = \frac{x - x_0}{|x - x_0|} \in S_{>\alpha_0}^{n-1},$$

with respect to which the Laplace operator reads

$$\Delta = e^{-\frac{n+2}{2}t} (\partial_t^2 + \hat{\Delta}_{S^{n-1}}) e^{\frac{n-2}{2}t}$$

where  $\hat{\Delta}_{S^{n-1}} = \Delta_{S^{n-1}} - (n-2)^2/4$ .

## Hemisphere caps

### Definition

A compact manifold with boundary  $(M, g)$  is said to be *simple* if its boundary  $\partial M$  is *strictly convex* and if the *exponential map*  $\exp_x : U_x \rightarrow M$  defined on its maximal set of definition is a *diffeomorphism* for all  $x \in M$ .

Cap strictly smaller than the northern hemisphere

$$S_{>\alpha_0}^{n-1} = \{x \in S^{n-1} : x_n > \alpha_0\}, \quad 0 < \alpha_0 < 1,$$

is a simple manifold.

Geodesic *ray transform* is *injective* on simple manifolds and there are *stability estimates* !

## Complex geometrical optics solutions

Approximate solutions of the Schrödinger equation of the form

$$u = e^{-\left(s + \frac{n-2}{2}\right)t} v_s(\omega), \quad s = \tau + i\lambda, \quad \lambda > 0$$

where  $v_s$  is a **quasimode of  $\widehat{\Delta}_{S^{n-1}}$**

$$(\widehat{\Delta}_{S^{n-1}} + s^2)v_s = \mathcal{O}_{L^2(S_+^{n-1})}(1).$$

With this choice, we have

$$\Delta u = e^{-\left(s + \frac{n+2}{2}\right)t} (\widehat{\Delta}_{S^{n-1}} + s^2)v_s$$

and therefore  $u$  is an approximate solution of the Schrödinger equation

$$\| |x - x_0|^{s + \frac{n-2}{2}} (-\Delta + q)u \|_{L^2(\Omega)} = \mathcal{O}(1).$$

## Quasimodes

Pick  $y \in \partial S_+^{n-1}$  on the **equator**

$$\widehat{\Delta}_{S^{n-1}} + s^2 = (\sin \theta)^{-\frac{n-2}{2}} \left( \partial_\theta^2 + s^2 \frac{1}{\sin^2 \theta} \widetilde{\Delta}_{S^{n-2}} \right) (\sin \theta)^{\frac{n-2}{2}}$$

$\theta = d_{S^{n-1}}(\theta, \omega)$  is the **distance** to  $y$ , i.e. the **colatitude** with respect to the pole  $y$ ,

$\eta \in S^{n-2}$ , remaining angular variables,

Quasimode on the sphere

$$v_s(\omega) = (\sin \theta)^{-\frac{n-2}{2}} e^{is\theta} b(\eta), \quad \omega = \exp_y(\theta \eta)$$

$b$  is **any** smooth function

**Approximate** solutions can be upgraded to **exact** solutions of the Schrödinger equation of the form

$$u = e^{-\left(s + \frac{n-2}{2}\right)t} (v_s(\omega) + \mathcal{O}(\tau^{-1}))$$

thanks to **Carleman** estimates.



## Semiclassical measure

Choose  $u_1, u_2$  to be the solutions

$$u_1(x) = e^{-\left(s + \frac{n-2}{2}\right)t} (v_s(\omega) + \mathcal{O}(\tau^{-1})),$$

$$u_2(x) = e^{-\left(-\bar{s} + \frac{n-2}{2}\right)t} (v_{-\bar{s}}(\omega) + \mathcal{O}(\tau^{-1}))$$

with  $s = \tau + i\lambda$ , we have

$$\int q u_1 u_2 dx = \int_{S_+^{n-1}} \underbrace{\int_{-\infty}^{\infty} e^{2i\lambda t} e^{2t} q(x_0 + e^t \omega) dt}_{=Q(\lambda, \omega)} v_s v_{-\bar{s}} d\omega + \mathcal{O}(\tau^{-1})$$

and passing to the **limit as  $\tau \rightarrow \infty$**  from  $\int q u_1 u_2 dx$  we finally control

$$\int_{S_+^{n-2}} \left( \int_0^\pi Q(-2\lambda, \exp_y(\theta\eta)) e^{-2\lambda\theta} d\theta \right) b^2(\eta) d\eta$$

## The attenuated geodesic ray transform

Varying  $b$ ,  $\int q u_1 u_2 dx$  we control the **attenuated geodesic ray transform**

$$T_{2\lambda}Q(y, \eta) = \int_0^\pi Q(\lambda, \exp_y(\theta\eta)) e^{-2\lambda\theta} d\theta$$

which is **injective** (and for which we have stability estimates) when  $\lambda$  is **small**.

The **maximal principle** allows to recover **large** frequencies  $\lambda$  of  $Q(\lambda, \cdot)$ .

## Remarks

What have we used in this construction?

1. the **warped structure** of  $(\Omega, dx^2) \subset (\mathbf{R}^+ \times S_{>\alpha_0}^{n-1}, e^{2t}(dt^2 \times g_{S^{n-1}}))$ ,
2. the existence of **Carleman estimates** to upgrade approximate solutions to exact ones,
3. the explicit computation of **semiclassical** measures and the relation with an attenuated geodesic ray transform.

One can therefore adapt this construction to **Riemannian manifolds with boundary** presenting a similar structure (**DSF, Kenig, Salo, Uhlmann**).

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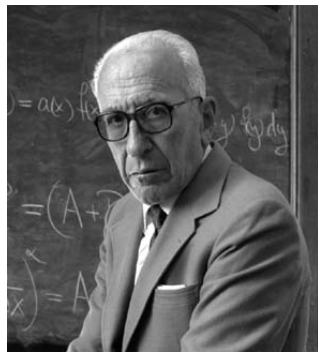
The geodesic ray transform

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## The Calderón problem

*On an inverse boundary value problem,*

Seminar on Numerical Analysis  
and its Applications to  
Continuum Physics, Rio de  
Janeiro,  
Editors W.H. Meyer and M.A.  
Raupp,  
Sociedade Brasileira de  
Matematica (1980), 65–73.



[http://en.wikipedia.org/wiki/Alberto\\_Calderón](http://en.wikipedia.org/wiki/Alberto_Calderón)

In a foundational paper of 1980, A. Calderón asked the following question:

Is it possible to determine the **electrical conductivity** of a body by making current and voltage measurements at the **boundary**?

## Riemannian rigidity

In fact, one can state the inverse problem with a **geometric flavour**.

Let  $(M, g)$  be a **compact Riemannian manifold with boundary**  $\partial M$  of dimension  $n \geq 3$  and  $q$  a **bounded measurable function**.

Consider the **Dirichlet problem**

$$\begin{cases} (\Delta_g + q)u = 0 \\ u|_{\partial M} = f \in H^{\frac{1}{2}}(\partial M) \end{cases}$$

and define the associated **Dirichlet-to-Neumann map** (under a natural spectral assumption)

$$\Lambda_{g,q}u = \partial_\nu u|_{\partial M}$$

where  $\nu$  is a **unit normal** to the boundary.

If  $q = 0$ , we use  $\Lambda_g = \Lambda_{g,0}$  as a short notation.

## Riemannian rigidity

The inverse problem is whether the DN map determines the metric  $g$ .

There is a **gauge invariance**, that is by isometries which leave **the boundary points unchanged**:

$$\Lambda_{\varphi^*g} = \Lambda_g, \quad \varphi|_{\partial M} = \text{Id}_{\partial M}$$

**Inverse problem**: Does the Dirichlet-to-Neumann map  $\Lambda_{g,q}$  determine the potential  $q$  and the metric  $g$  **modulo such isometries**?

If  $n \geq 3$  and  $q = 0$  this is a generalization of the **anisotropic conductivity problem** and one passes from one to the other by

$$\gamma^{jk} = \sqrt{\det g} g^{jk}, \quad g^{jk} = (\det \gamma)^{-\frac{2}{n-2}} \gamma^{jk}.$$

## Conformal metrics

There is a **conformal** gauge transformation

$$\Delta_{cg}u = c^{-1}(\Delta_g + q_c)(c^{\frac{n-2}{4}}u), \quad q_c = c^{\frac{n+2}{4}}\Delta_g(c^{\frac{n-2}{4}})$$

which translates at the boundary into

$$\Lambda_{cg,q}f = c^{-\frac{n+2}{4}}\Lambda_{g,q+q_c}(c^{\frac{n-2}{4}}u) + \frac{n-2}{4}c^{-\frac{1}{2}}\partial_\nu cf.$$

So if one knows  $c, \partial_\nu c$  at the boundary (**boundary determination**) then one can deduce one DN map from the other.

**A more reasonable inverse problem:**  $\Lambda_{cg} = \Lambda_g \Rightarrow c = 1$ .

Note that there is **no isometry gauge invariance** in this case.



## Some references $n \geq 3$

- 1987 Sylvester-Uhlmann: isotropic case
- 1989 Lee-Uhlmann: boundary determination, analytic metrics, no potential, determination of the metric
- 2001 Lassas-Uhlmann: improvement on topological assumptions
- 2007 Kenig-Sjöstrand-Uhlmann: small subsets of the boundary,  $n \geq 3$ , global Carleman estimates with logarithmic weights, introduction of limiting Carleman weights.
- 2009 Guillarmou-Sa Baretto: Einstein manifolds, no potential, determination of the metric, unique continuation argument
- 2009 DSF-Kenig-Salo-Uhlmann: fixed admissible geometries, determination of a smooth potential, CGOs
- 2011 DSF-Kenig-Salo: fixed admissible geometries, determination of an unbounded potential, CGOs

## Remarks

1. **Analytic metrics case** fairly well understood. The **smooth case** remains a challenging problem.
2. There are **limitations** in the method using CGO construction: the existence of **limiting Carleman weights**
3. We will concentrate on the case of identifiability of the metric within a **conformal class**

$$\Lambda_{cg} = \Lambda_g \Rightarrow c = 1.$$

4. With **boundary determination**

$$\Lambda_{cg} = \Lambda_g \Rightarrow c|_{\partial M} = 1, \quad \partial_\nu c|_{\partial M} = 0.$$

it is enough to solve the inverse problem on the Schrödinger equation with a **fixed metric**

$$\Lambda_{g,q_1} = \Lambda_{g,q_2} \Rightarrow q_1 = q_2.$$

## A density property

Green's formula and the fact that  $\Lambda_{g,q}^* = \Lambda_{g,\bar{q}}$  yield

$$\int_M (q_1 - q_2) u_1 \overline{u_2} \, dV = \int_{\partial M} (\Lambda_{g,q_1} - \Lambda_{g,q_2}) u_1 \overline{u_2} \, dS = 0$$

for **all pairs**  $(u_1, u_2)$  of solutions of the Schrödinger equations  $(-\Delta_g + q_1)u_1 = 0$ ,  $(-\Delta_g + \bar{q}_2)u_2 = 0$ . So we are reduced to the following **density property**

Is the linear span of **products**  $u_1 \overline{u_2}$  of solutions  $u_1, u_2$  to two Schrödinger equations with two potentials  $q_1$  and  $\bar{q}_2$  dense in, say,  $L^1(M)$  ?

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## Warped products

Let  $(M_0, g_0)$  be a compact Riemannian manifold (with boundary) and let  $\psi$  be a smooth function on  $\mathbf{R}$ , the **warped product**  $(\mathbf{R}, dt^2) \times_{e^{2\psi}} (M_0, g_0)$  is the manifold  $\mathbf{R} \times M_0$  endowed with the following **metric**

$$dt^2 + e^{2\psi(t)} g_0.$$

Our **fixed metric**  $g$  will be **conformal** to such a **warped product**.

Two reasons for this choice:

- Warped metrics admit **limiting Carleman weights**.
- This is the natural setting to solve equations by **separation of variables**.

## Unwarping warped products

An open manifold which is **conformally imbedded** in the **warped product** of the Euclidean line  $\mathbf{R}$  and a Riemannian manifold  $(M_0, g_0)$  of dimension  $n - 1$  **admits limiting Carleman weights**. Indeed the metric on  $\mathbf{R} \times_{e^{2\psi}} M_0$  is conformal to

$$e^{-2\psi(t)} dt^2 + g_0$$

and one can make the change of variable

$$t' = \int_0^t e^{-\psi(t'')} dt''$$

to reduce the metric to

$$dt'^2 + g_0$$

where  $\varphi(t') = t'$  is a **natural limiting Carleman weight**.

## Limiting Carleman weights

### Definition

A *limiting Carleman weight* on an open Riemannian manifold is smooth *real-valued* function *without critical points* such that

$$\frac{1}{i} \{ \overline{p_\varphi}, p_\varphi \} = 0 \quad \text{on } p_\varphi^{-1}(0)$$

where  $p_\varphi(x, \xi) = |\xi|_g^2 - |d\varphi|_g^2 + 2i\langle \xi, d\varphi \rangle_g$  is the semiclassical principal symbol of the conjugated operator  $e^{\tau\varphi}(-\Delta_g)e^{-\tau\varphi}$ .

This notion was introduced by Kenig-Sjöstrand-Uhlmann.  
In a product metrics  $g = dt^2 + g_0$ ,  $\varphi = t$  is a limiting weight:

$$p_\varphi = (\tau + i)^2 + g_0 = \tau^2 + g_0 - 1 + 2i\tau$$

$$\frac{1}{i} \{ \overline{p_\varphi}, p_\varphi \} = 4\{\tau^2 + g_0 - 1, \tau\} = \frac{\partial g_0}{\partial t} = 0.$$

## Carleman estimates

### Theorem

There exist two constants  $C, \tau_0 > 0$  such that

$$|\operatorname{Re} s| \|e^{st} w\|_{L^2} + \|e^{st} dw\|_{L^2} \leq C \|e^{st} (\partial_t^2 + \Delta_{g_0} + q) w\|_{L^2}$$

for all  $w \in C_0^\infty(\mathbf{R} \times M_0)$  and all  $s \in \mathbf{C}$  such that  $|\operatorname{Re} s| \geq \tau_0$ .

By **Hahn-Banach**, one can construct a correction term  $r_s$  such that

$$\begin{aligned} (\partial_t^2 + \Delta_g + q)(e^{st} r_{s,q}) &= e^{st} f \\ \|r_{s,q}\|_{L^2} &\leq |\operatorname{Re} s|^{-1} \|f\|_{L^2}. \end{aligned}$$

**Remark:** There exist  $L^p$  versions of Carleman estimates with limiting weights in this context (DSF, Kenig, Salo) which can be viewed as version of estimates of **Jerison and Kenig** and of **Kenig, Ruiz and Sogge** on manifolds.



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## The geodesic ray transform

The unit sphere bundle :

$$SM_0 = \bigcup_{x \in M_0} S_x, \quad S_x = \{(x, \xi) \in T_x M_0; |\xi|_g = 1\}.$$

Boundary:  $\partial(SM_0) = \{(x, \xi) \in SM_0; x \in \partial M_0\}$  union of **inward and outward** pointing vectors:

$$\partial_{\pm}(SM_0) = \{(x, \xi) \in SM_0; \pm \langle \xi, \nu \rangle \leq 0\}.$$

Denote by  $t \mapsto \gamma(t, x, \xi)$  the unit speed geodesic starting at  $x$  in direction  $\xi$ , and let  $\tau(x, \xi)$  be **the time** when this geodesic **exits**  $M_0$ .

**Geodesic ray transform** :

$$T_0 f(x, \xi) = \int_0^{\tau(x, \xi)} f(\gamma(t, x, \xi)) dt, \quad (x, \xi) \in \partial_+(SM_0).$$

# Simple manifolds

## Definition

A compact manifold  $(M_0, g_0)$  with boundary is **simple** if for any  $p \in M_0$  the **exponential map**  $\exp_p$  with its maximal domain of definition is a **diffeomorphism** onto  $M_0$ , and if  $\partial M_0$  is **strictly convex** (that is, the second fundamental form of  $\partial M_0 \hookrightarrow M_0$  is positive definite).

1. Simple manifolds are **non-trapping**.
2. Simple manifolds are diffeomorphic to **a ball**.
3. A hemisphere is **not simple**.

## Injectivity of the ray transform

Injectivity of the ray transform is known to hold for

1. **Simple manifolds** of any dimension.
2. Manifolds of dimension  $\geq 3$  that have strictly convex boundary and are **globally foliated by strictly convex hypersurfaces** (Uhlmann-Vasy).
3. A class of non-simple manifolds of any dimension such that there are sufficiently many geodesics without conjugate points and the metric is **close to a real-analytic one** (Stefanov-Uhlmann).
4. There are **counterexamples** to injectivity of the ray transform.

## Main results in a conformal class

### Theorem

Let  $(M, g)$  be a compact manifold with boundary which can be embedded in the warped product of the Euclidean line and another manifold. Let  $q_1, q_2 \in C(M)$  such that 0 is not a Dirichlet eigenvalue of the corresponding Schrödinger operators. Assume in addition that the *ray transform in the transversal manifold is injective*. If  $\Lambda_{g, q_1} = \Lambda_{g, q_2}$ , then  $q_1 = q_2$ .

### Corollary

Let  $(M, g)$  be a compact manifold with boundary which can be embedded in the warped product of the Euclidean line and another manifold. Assume in addition that the *ray transform in the transversal manifold is injective*. If  $\Lambda_{cg} = \Lambda_g$ , then  $c = 1$ .

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## Separation of variables

We are interested in the **density** of the set of **products** of solutions of Schrödinger equations. Let us start by **harmonic functions**  $u$  using separation of variables

$$\Delta_g(w(t)v(x)) = (\partial_t^2 + \Delta_{g_0})(w(t)v(x)) = 0$$

and for  $s \in \mathbf{C}$  take

$$(D_t^2 - s^2)w = 0, \quad (\Delta_{g_0} + s^2)v = 0$$

i.e.  $u = e^{st}v_s$ ,  $(\Delta_{g_0} + s^2)v_s = 0$ .

By **Hahn-Banach**, one can construct a correction term  $r_s$  such that

$$\begin{aligned} (\partial_t^2 + \Delta_g + q)(e^{st}r_{s,q}) &= -e^{st}(\Delta_{g_0} + s^2 + q)v_s \\ \|r_{s,q}\|_{L^2} &\leq |\operatorname{Re} s|^{-1} \|(\Delta_{g_0} + s^2 + q)v_s\|_{L^2}. \end{aligned}$$

So it **suffices** to require  $(\Delta_{g_0} + s^2)v_s = o_{L^2}(\operatorname{Re} s)$  and  $v_s = O_{L^2}(1)$  to obtain a **solution of the Schrödinger equation** of the form

$$u = e^{st}(v_s + r_{s,q}), \quad r_{s,q} = o_{L^2}(1).$$

## Quasimodes

We take  $h = (\operatorname{Re} s)^{-1}$  as a **semiclassical parameter** and write  $s = h^{-1} + i\lambda$ . We consider the family of products  $u_1 \overline{u_2}$  of  $u_1 = e^{-st}(v_s + r_{s,q_1})$  and  $u_2 = e^{st}(v_s + r_{s,\overline{q_2}})$  when  $s \in \mathbf{C}$

$$e^{-2i\lambda t} |v_s|^2 + o(1)$$

where  $v_s$  is a **quasimode**

$$(h^2 \Delta_{g_0} + (1 + i\lambda h)^2)v_s = o_{L^2}(h).$$

The density property we are looking for will be satisfied if we can find quasimodes such that

$$\lim_{h \rightarrow 0} \int_M q e^{-2i\lambda t} |v_s|^2 dt dV_{g_0} = \lim_{h \rightarrow 0} \int_{M_0} \hat{q}(2\lambda, x) |v_s|^2 dV_{g_0} = 0$$

for  $q \in C_0^0(\mathbf{R} \times M_0)$  **implies**  $q = 0$ .



## Semiclassical measures

In fact, one is lead to study the measures which are **limits of**  $|v_s|^2 dV_{g_0}$  when  $\operatorname{Re} s \rightarrow \infty$  where  $v_s$  is a quasimode.

If one lifts those measures to the cotangent bundle  $T^*M_0$ , one obtains **semiclassical defect measures**. These are in fact supported in the cosphere bundle  $S^*M_0$  and satisfy a **transport equation** (loosely speaking, they are **invariant under the cogeodesic flow** when  $\lambda = 0$ ).

In a previous work, we (**Carlos Kenig, Mikko Salo, Gunther Uhlmann** and myself) were able to construct quasimodes in a **simple manifold** which concentrate on a **geodesic**  $\gamma$ , thus obtaining

$$T_\lambda(\hat{q}(0, \cdot))(\gamma) = \int_0^L e^{-2\lambda r} \hat{q}(2\lambda, \gamma(r)) dr = 0$$

for **all geodesics**  $\gamma$  and all  $\lambda \geq 0$ .

## Getting rid of the attenuation

Although it seems that one needs the **injectivity of an attenuated** geodesic ray transform to conclude  $q = 0$ , it suffices to deal with the case  **$\lambda = 0$** . Indeed from

$$\int_0^{L(x,\theta)} \hat{q}(0, \exp_x(r\theta)) \, dr = 0$$

one gets  $\hat{q}(0, \cdot) = 0$ . **Differentiating**

$$\int_0^{L(x,\theta)} e^{-2\lambda r} \hat{q}(\lambda, \exp_x(r\theta)) \, dr = 0$$

with respect to  $\lambda$  at  $\lambda = 0$ , one gets

$$\int_0^{L(x,\theta)} \partial_\lambda \hat{q}(0, \exp_x(r\theta)) \, dr = 0$$

hence  $\partial_\lambda \hat{q}(0, \cdot) = 0$ . Etc. Since  $\hat{q}$  is **analytic with respect to  $\lambda$**  we get  $q = 0$ .

# Quasimodes

One of the contribution of our work is the construction of such quasimodes — **concentrating** on a **non-closed geodesic**  $\gamma$  — in the general case. This construction can be done in two ways:

- using **Gaussian beams** [▶ Gauss](#),
- by a **microlocal approach** [▶ Micro](#).

To simplify, we will take  $\lambda = 0$ .

## Microlocal construction

There is a **canonical transformation**  $\varsigma$  which sends the cogeodesic  $\Gamma$  to the line  $\Lambda = \mathbf{R} \times \{0, \varepsilon_m\}$  ( $\varepsilon_m = (0, \dots, 0, 1)$ ) with  $m = \dim M_0 = n - 1$ ). **Quantizing** such a transformation by **semiclassical Fourier integral operators** one gets

$$V_h \left( \sqrt{-h^2 \Delta_{g_0}} - 1 \right) U_h = hD_1 + O(h^\infty)$$

Our quasimode will be

$$v_h = U_h(1 \otimes w_h(x')), \quad \text{WF}_{\text{sc}}(w_h) = \{(0, \varepsilon_m)\},$$

this is a quasimode microlocally near  $\Gamma$  and also away from  $\Gamma$  since

$$\text{WF}_{\text{sc}}(v_h) \subset \Gamma.$$

The choice for  $w_h$  is a **wave packet** (or coherent state).

## An application of Egorov's theorem

The **semiclassical defect measure** associated to the quasimode  $v_h$  can be computed using **Egorov's theorem**:

$$\begin{aligned} \int_{M_0} (\text{Op}_h a) v_h \overline{v_h} dV_{g_0} &= \int_{\mathbf{R}^m} U_h^* (\text{Op}_h a) U_h w_h \overline{w_h} dx_1 dx' \\ &= \int_{\mathbf{R}^m} (\text{Op}_h \varsigma^* a) w_h \overline{w_h} dx_1 dx' + O(h) \end{aligned}$$

and since the defect measure associated to wave packets concentrated near  $(0, \varepsilon_n)$  is  $\delta_{(0, \varepsilon)}$  passing to the limit we get

$$\int_{\Lambda} \varsigma^* a = \int_{\Gamma} a.$$

Hence the semiclassical measure is the **measure on  $\Gamma$**  (and its projection on  $M_0$  the **measure on the geodesic  $\gamma$** ).

## Gaussian beams

We look for quasimodes of the form  $v_h = e^{\frac{i}{h}\Phi} a$ , we have

$$(h^2 \Delta_{g_0} - 1)v_h = e^{\frac{i}{h}\Phi} (h^0(1 - |\mathrm{d}\Phi|_{g_0}^2)a + h(2L_{\nabla\Phi} + \Delta_{g_0}\varphi)a + h^2 \Delta_{g_0}a)$$

- **Eikonal equation:**  $|\mathrm{d}\Phi|_{g_0}^2 = 1$ , a solution given by  $\Phi_{g_0} = d_{g_0}(x, x_0)$  if there are **no conjugate points**,
- **Transport equation** :  $(L_{\nabla_{g_0}\Phi} + \frac{1}{2}\Delta_{g_0}\Phi)a = 0$ , again explicit solutions in **simple manifolds**.

In the case of general manifolds, an alternative is to solve **approximately** those equations close to a geodesic and use a **complex phase**  $\Phi$ .

## Gaussian beams in Euclidean space

Our **geodesic**:  $\gamma = \{(x_1, 0) : x_1 \in [0, T]\}$

Approximate **eikonal equation**:  $(d\Phi)^2 = 1 + \mathcal{O}(|x'|^4)$

Approximate **transport equation**:  $L_{\nabla\Phi}a + \frac{1}{2}\Delta\Phi a = \mathcal{O}(|x'|^2)$

**Phase**:  $\Phi(x) = x_1 + \frac{1}{2}\langle Q(x_1)x', x' \rangle$  with  $\text{Im } Q(x_1) > cI_n$  so that

$$\begin{aligned} (d\Phi)^2 - 1)e^{\frac{i}{\hbar}\Phi}a &= \mathcal{O}(|x'|^4)e^{-\frac{c}{\hbar}|x'|^2} = \mathcal{O}(\hbar^2) \\ \left(L_{\nabla\Phi}a + \frac{1}{2}\Delta\Phi a\right)e^{\frac{i}{\hbar}\Phi} &= \mathcal{O}(|x'|^2)e^{-\frac{c}{\hbar}|x'|^2} = \mathcal{O}(\hbar) \end{aligned}$$

Solving the approximate eikonal equation

$$\begin{aligned} (d\Phi)^2 - 1 &= \langle \dot{Q}(x_1)x', x' \rangle + (Q(x_1)x')^2 + \mathcal{O}(|x'|^4) \\ &= \langle (\dot{Q} + Q^2)x', x' \rangle + \mathcal{O}(|x'|^4) \end{aligned}$$

leads to a **Riccati** equation on the matrix  $\dot{Q} + Q^2 = 0$

## Gaussian beams in Euclidean space

Solving the approximate eikonal equation

$$\left( L_{\nabla\Phi} + \frac{1}{2}\Delta\Phi \right) a = \partial_{x_1} a + \frac{1}{2} \text{Tr} Q(x_1) a + \langle Qx', \nabla_{x'} a \rangle + \mathcal{O}(|x'|^2)$$

leads if  $a$  is **independent on  $x'$**  to

$$a = c \exp \left( -\frac{1}{2} \int_0^{x_1} \text{Tr} Q(t) dt \right)$$

An explicit **Gaussian beam**:

$$v_h = h^{-\frac{n-2}{4}} e^{-\frac{1}{2} \int_0^{x_1} \text{Tr} Q(t) dt} e^{i\frac{x_1}{h}} e^{\frac{i}{2h} \langle Q(x_1)x', x' \rangle},$$

$$\dot{Q} + Q^2 = 0.$$

Modulus of a Gaussian beam

$$|v_h|^2 = h^{-\frac{n-2}{2}} e^{-\int_0^{x_1} \text{Tr} \text{Re} Q(t) dt} e^{-\frac{1}{2} \langle \text{Im} Q(x_1)x', x' \rangle},$$



## Limit measure

For **Riccati matrices**, we have  $e^{-\int_0^{x_1} \text{Tr Re } Q(t) dt} = \sqrt{\frac{\det \text{Im } Q(x_1)}{\det \text{Im } Q(0)}}$

therefore passing to the limit in

$$\int \hat{q}(0, x) |v_h|^2 dx = \int_{-\infty}^{\infty} \left( h^{\frac{n-2}{2}} \int_{\mathbf{R}^{n-2}} \sqrt{\frac{\det \text{Im } Q(x_1)}{\det Q(0)}} e^{-\frac{1}{2} \langle \text{Im } Q(x_1) x', x' \rangle} \hat{q}(0, x) dx' \right) dx_1$$

gives

$$\lim_{h \rightarrow 0} \int \hat{q}(0, x) |v_h|^2 dx = c_n \int_{-\infty}^{\infty} \hat{q}(0, x_1, 0) dx_1 = c_n T_0(\hat{q}(0, \cdot))(\gamma)$$

an information on the **geodesic ray transform**  $T_0$  of  $\hat{q}(0, \cdot)$ .