

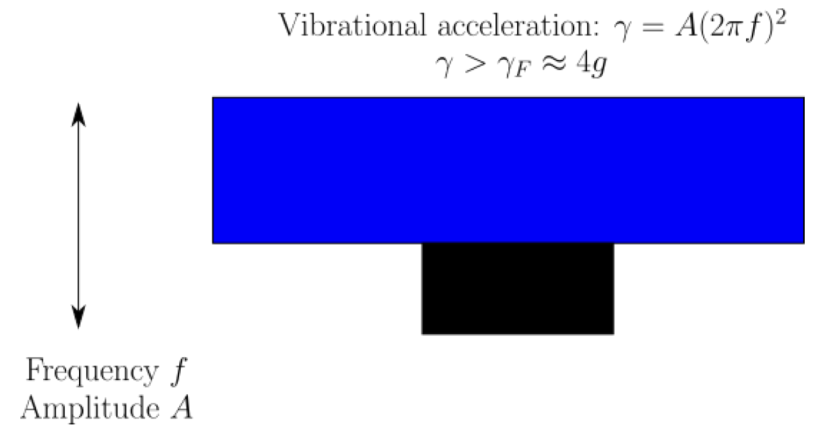
# An introduction to pilot-wave dynamics

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# Faraday waves and bouncing droplets

- Oscillate a fluid bath vertically at a frequency  $f$ , amplitude  $A$
- Above critical threshold, Faraday instability arises
- Below threshold, can bounce/walk a droplet on the decaying waves
- Wave field memory: how many bouncing periods a generated wave persists for
- Pilot wave: droplet is 'piloted' by the fluid



# Origin of the Faraday instability

- Model fluid as inviscid, irrotational
- Fluid velocity governed by Laplace's equation
- Let fluid surface height be  $\zeta(x, y)$
- Expand

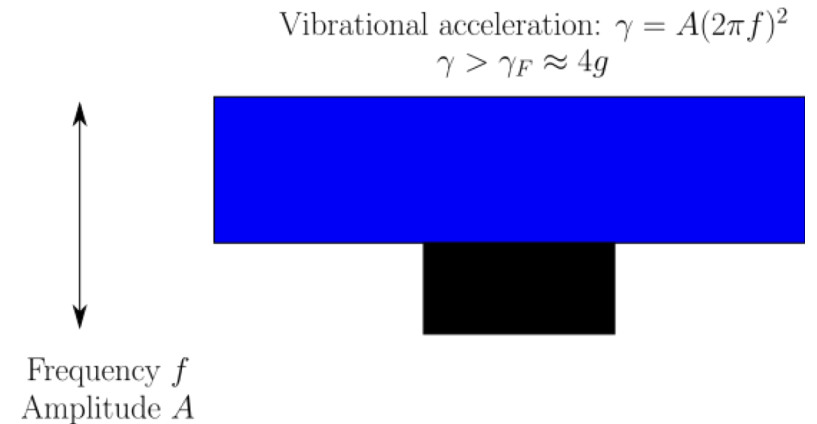
$$\zeta(x, y) = \sum_{m=0}^{\infty} a_m S_m(x, y)$$

$$\nabla^2 S_m = -k_m^2 S_m$$

- Can show that, after non-dimensionalising,

$$\frac{d^2 a_m}{dt^2} + (p_m - 2q_m \cos(2t))a_m = 0$$

Benjamin, Ursell, 1954



Fluid inertia

Restoring forces due to gravity and surface tension

External driving of the fluid

# Origin of the Faraday instability

$$\frac{d^2 a_m}{dt^2} + (p_m - 2q_m \cos(2t))a_m = 0$$

- Analysis of this equation requires Floquet theory, as there is a time-dependent forcing
- Results from Floquet theory:

$$\begin{bmatrix} a_m \\ \frac{da_m}{dt} \end{bmatrix} = Q(t)e^{tR}$$

for some periodic vector-valued function  $Q$  and real matrix  $R$ : eigenvalues of  $R$  determine growth rates of oscillations of  $a_m$

- Instability when eigenvalues have positive real part

# Trajectory equation for bouncing droplets

- Waves emitted by droplet exhibit radial symmetry
- Wavelength emitted by the droplet matches wavelength of Faraday instability,  $\lambda_F = \frac{2\pi}{k_F}$
- Radially symmetric superposition of plane waves is a **Bessel function**:

$$J_0(r) = \frac{1}{2\pi} \int_0^{2\pi} e^{ir \cos(\theta)} d\theta$$

- Below Faraday threshold, expect waves to **decay exponentially**
- **Inertia, drag** affect particle
- Force due to the wave is proportional to the **slope of the local wave field**
- Superposition of waves generated by each impact
- Assume horizontal motion slower than vertical motion: **integrate over particle trajectory, average over vertical particle motion**
- Current state depends on the droplet's entire past history!



$$\kappa_0 \ddot{\mathbf{x}}_p + \dot{\mathbf{x}}_p = -2\nabla h(\mathbf{x}_p(t), t)$$
$$h(\mathbf{x}, t) = \int_{-\infty}^t J_0(|\mathbf{x} - \mathbf{x}_p(s)|) e^{-\epsilon(t-s)} ds$$

$\epsilon$ : memory, reciprocal of how many previous droplet impacts contribute to wave field

$\epsilon = 0$  is Faraday threshold

$\epsilon = 1$  is walking threshold

$\kappa_0$ : non-dimensionalised mass

# Instability of bouncing state

- A bouncing state is given by  $\mathbf{x}_p = \mathbf{c}$
- Linearise:  $\mathbf{x}_p = \mathbf{c} + \mathbf{X}$

- Linearised equations become (using that  $J'_1(0) = \frac{1}{2}$ )

$$\kappa_0 \mathbf{X}'' + \mathbf{X}' = \frac{1}{2} \int_{-\infty}^t (\mathbf{X}(t) - \mathbf{X}(s)) e^{-\epsilon(t-s)} ds$$

- Define now

$$\begin{aligned} \mathbf{Y}(t) &= \int_{-\infty}^t \mathbf{X}(s) e^{-\epsilon(t-s)} ds \\ \kappa_0 \mathbf{X}'' + \mathbf{X}' &= \frac{1}{2} (\mathbf{X} - \mathbf{Y}) \\ \mathbf{Y}' &= \mathbf{X} - \epsilon \mathbf{Y} \end{aligned}$$

- Letting now  $\mathbf{Z} = \mathbf{X}$ , recast as a 3D linear system, find eigenvalues
- Bouncing state destabilises for  $\epsilon < 1$
- Physically: bouncing state is stabilised by drag and destabilised by the wave force

# Walking state

- Consider a 1D walker, where  $\mathbf{x}_p = ut\hat{\mathbf{e}}_x$
- Trajectory equation simplifies to

$$u = 2 \int_{-\infty}^t J_1(u(t-s)) e^{-\epsilon(t-s)} ds$$

- Integral can be evaluated exactly; find

$$u = \frac{1}{\sqrt{2}} \left( 4 - \epsilon^2 - \epsilon \sqrt{\epsilon^2 + 8} \right)^{\frac{1}{2}}$$

- Require that at  $\epsilon = 1, u = 0$ ; indeed, find that  $u = O(\sqrt{1 - \epsilon})$ , indicative of a supercritical pitchfork bifurcation



# Walking state stability

- Imagine a droplet walking at constant velocity, but is perturbed at time  $t = 0$
- Write  $x_p(t) = ut + \eta x_1(t)H(t)$ ; think of it as adding an impulsive force to the particle at  $t = 0$  so that  $x_1(0) = 0, x_1'(0) = \frac{1}{\kappa_0}$
- Linearised equation:

$$\kappa_0 x_1''(t) + x_1'(t) = \epsilon x_1(t) - 2 \int_0^\infty x_1(t-s) J_1'(us) e^{-\epsilon s} ds$$

- Convolution: use Laplace transforms and convolution theorem.

$$X(s) = \int_0^\infty x_1(t) e^{(-st)} dt$$

$$\kappa_0 \left( s^2 X(s) - \frac{s}{\kappa_0} \right) + sX(s) = \epsilon X(s) - 2X(s) \int_0^\infty J_1'(ut) e^{-t(s+\epsilon)} dt$$

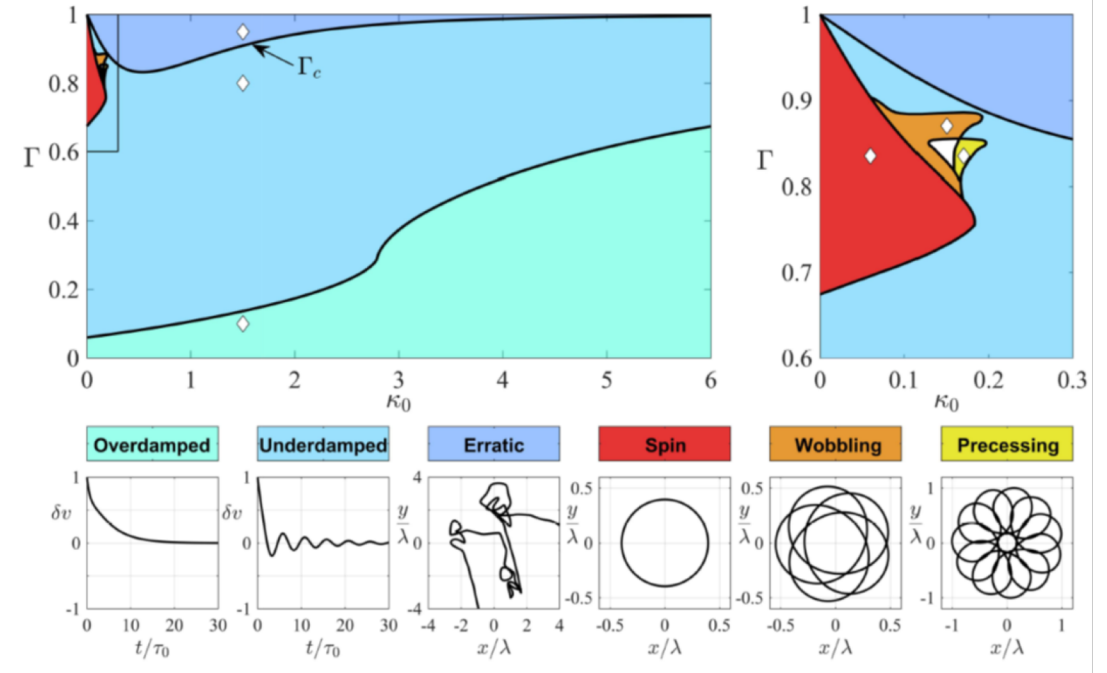
$$X(s) = s \left( \kappa_0 + s - \epsilon + \frac{2(\epsilon + s)}{u^2} \left( 1 - \frac{\epsilon + s}{\sqrt{(\epsilon + s)^2 + u^2}} \right) \right)^{-1}$$

- Observe that the Laplace transform of  $e^{at}$  is  $\frac{1}{s-a}$ ; exponential growth rates correspond to singularities of Laplace transforms
- Want the singularities of  $X(s)$  to determine exponential growth rates



# Walking state stability diagram

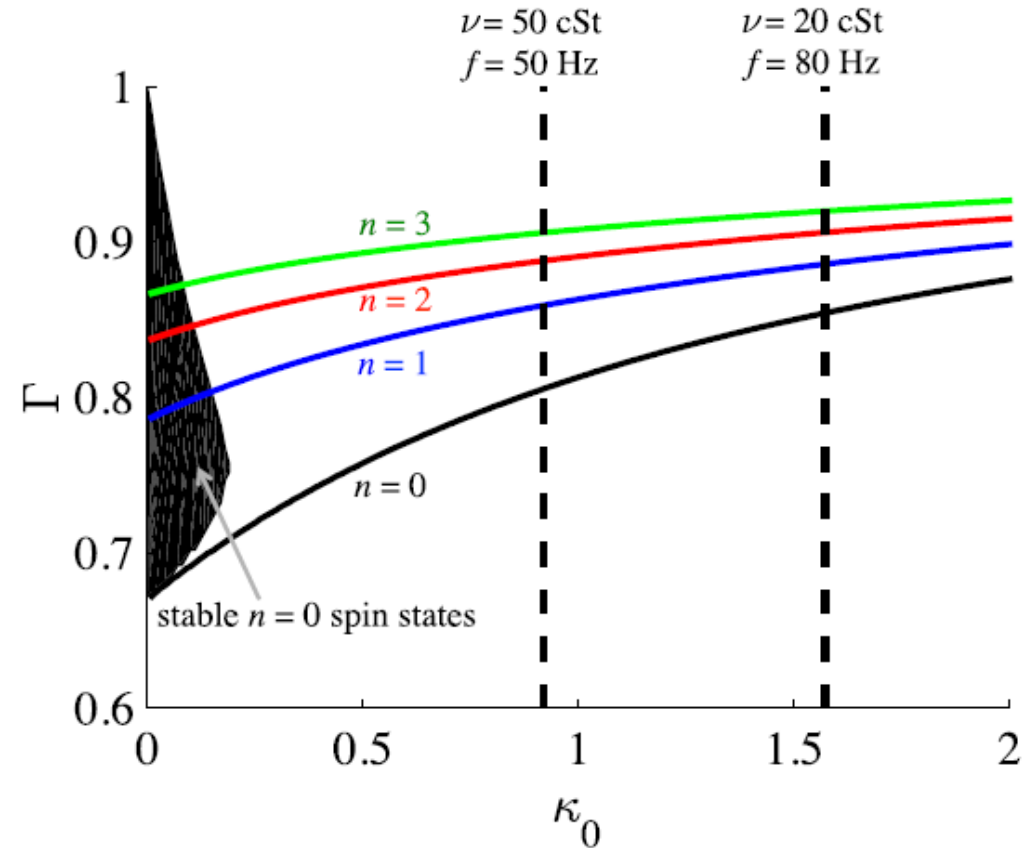
- Eigenvalue with positive real part: unstable
- No eigenvalues with positive real parts: stable
  - Most unstable eigenvalue complex: underdamped oscillations
  - Most unstable eigenvalue real: overdamped oscillations
- Spin states possible! Circular orbits



# Spin states

- $\Gamma = 1 - \epsilon$ ;  $\Gamma = 1$  is Faraday threshold
- Substituting  $\mathbf{x}_p = (r_0 \cos(\omega t), r_0 \sin(\omega t))$  into trajectory equation,
 
$$-\kappa r_0 \omega^2 = 2 \int_0^\infty J_1 \left( 2r_0 \sin \left( \frac{\omega S}{2} \right) \right) \sin \left( \frac{\omega S}{2} \right) e^{-\epsilon S} dS$$

$$r_0 \omega = 2 \int_0^\infty J_1 \left( 2r_0 \sin \left( \frac{\omega S}{2} \right) \right) \cos \left( \frac{\omega S}{2} \right) e^{-\epsilon S} dS$$
- Small region of stability for smallest radius spin states
- What happens if you add rotation to the system?



# Rotating frame

- Externally rotate the system with angular velocity  $\Omega$
- In the (non-inertial) frame of the fluid, Coriolis and centripetal forces arise
- Can show that the fluid will develop a parabolic surface to cancel the centripetal force; only consider Coriolis

$$\kappa_0 \ddot{\mathbf{x}}_p + \dot{\mathbf{x}}_p = -2\nabla h(\mathbf{x}_p(t), t) - \vec{\Omega} \times \dot{\mathbf{x}}_p$$
$$h(\mathbf{x}, t) = \int_{-\infty}^t J_0(|\mathbf{x} - \mathbf{x}_p(s)|) e^{-\epsilon(t-s)} ds$$

- Straight line walking states become circular orbits

# Stability analysis

- Consider an impulse acting at  $t = 0$ , of the form  $\eta c_r \hat{r} + \eta c_\theta \hat{\theta}$ ,  $\eta \ll 1$

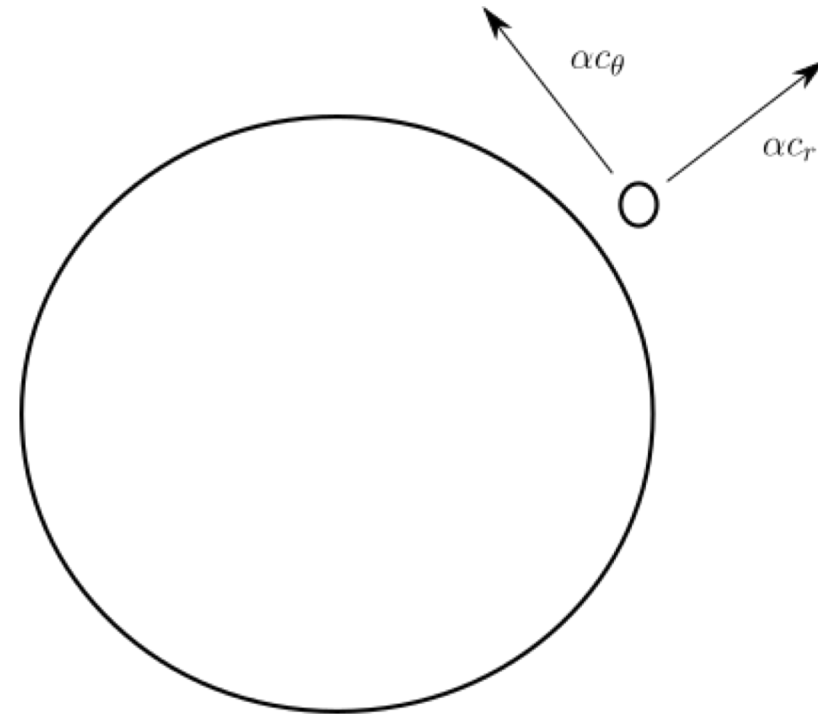
- Linearise

$$\begin{aligned} r(t) &= r_0 + \eta r_1(t)H(t) \\ \theta(t) &= \omega t + \eta \theta_1(t)H(t) \end{aligned}$$

- Obtain a 2x2 linear system for the Laplace transforms  $R(s)$ ,  $\Theta(s)$  of  $r_1(t)$ ,  $\theta_1(t)$

$$\begin{bmatrix} A(s) & -B(s) \\ C(s) & D(s) \end{bmatrix} \begin{bmatrix} R(s) \\ r_0 \Theta(s) \end{bmatrix} = \begin{bmatrix} c_r \\ r_0 c_\theta \end{bmatrix}$$

- Eigenvalues occur for values of  $s$  when the Laplace transforms are singular: determinant must vanish
- Solve  $F(s) = A(s)D(s) + B(s)C(s) = 0$



# Stability function

$$A(s) = \kappa_0(s^2 - 2\omega^2) + \epsilon + s - 2\Omega\omega + \int_0^\infty \left( J_0\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \cos(\omega t) + J_2\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \right) e^{-(\epsilon+s)t} dt - 2 \int_0^\infty J_0\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) e^{-\epsilon t} dt$$

$$D(s) = \kappa_0 s^2 + s - \epsilon + \int_0^\infty \left( J_0\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \cos(\omega t) - J_2\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \right) e^{-(\epsilon+s)t} dt$$

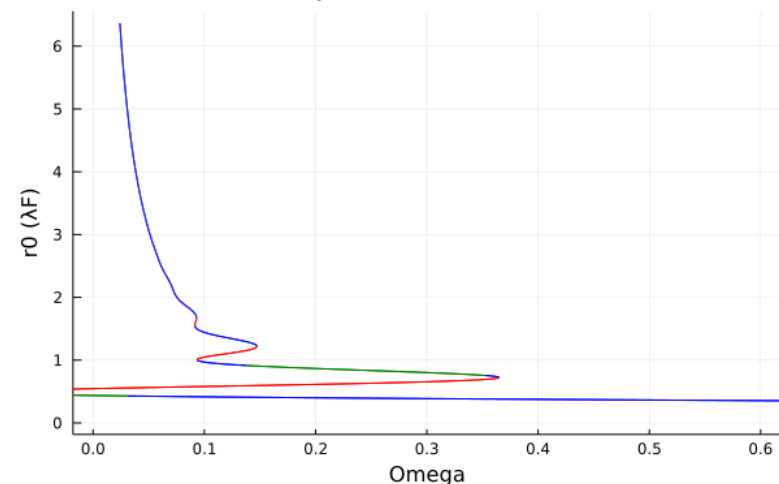
$$B(s) = 2\kappa_0\omega s + \Omega s - \epsilon(\omega\kappa_0 + \Omega) - \int_0^\infty J_0\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \sin(\omega t) e^{-(\epsilon+s)t} dt$$

$$C(s) = 2\kappa_0\omega s + 2\omega + \Omega s + \epsilon(\omega\kappa_0 + \Omega) - \int_0^\infty J_0\left(2r_0 \sin\left(\frac{\omega t}{2}\right)\right) \sin(\omega t) e^{-(\epsilon+s)t} dt$$

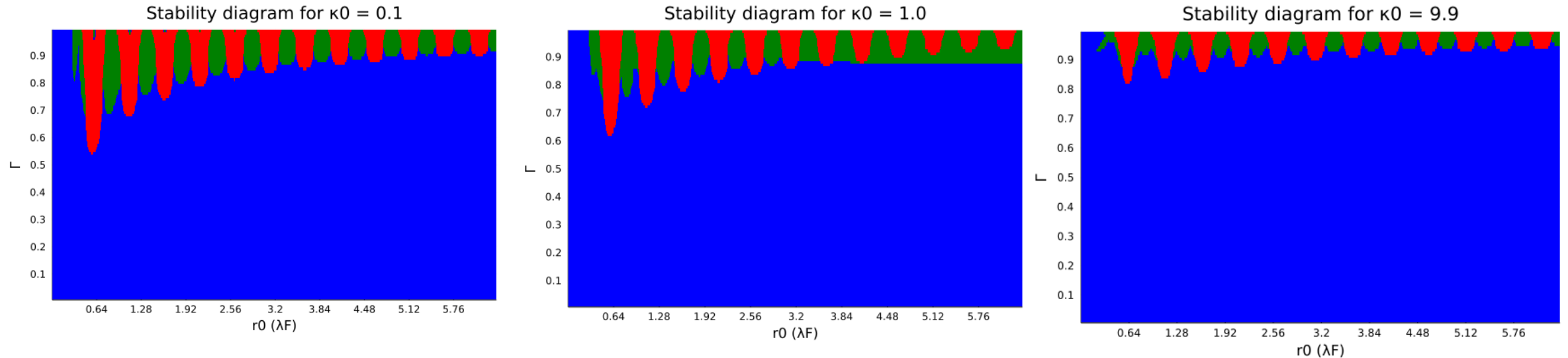
$$F(s) = A(s)D(s) + B(s)C(s)$$

- In the absence of rotation, A, D represent the stability functions for inline and lateral perturbations to 2D straight line walking
- First derived by Oza et al (2014, JFM)
- $F(0) = F(\pm i\omega) = 0$ ; trivial eigenvalues
- These represent translational and rotational symmetry

Stability for  $\Gamma = 0.76$ ,  $\kappa_0 = 0.3$



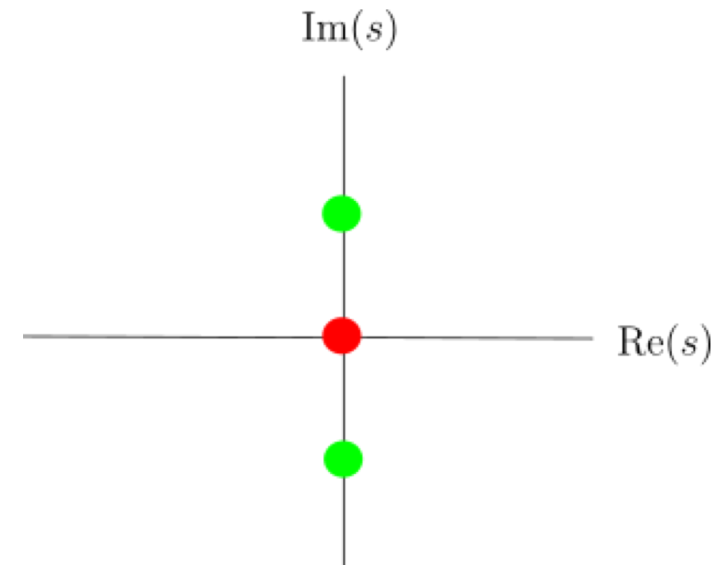
# Regime diagrams



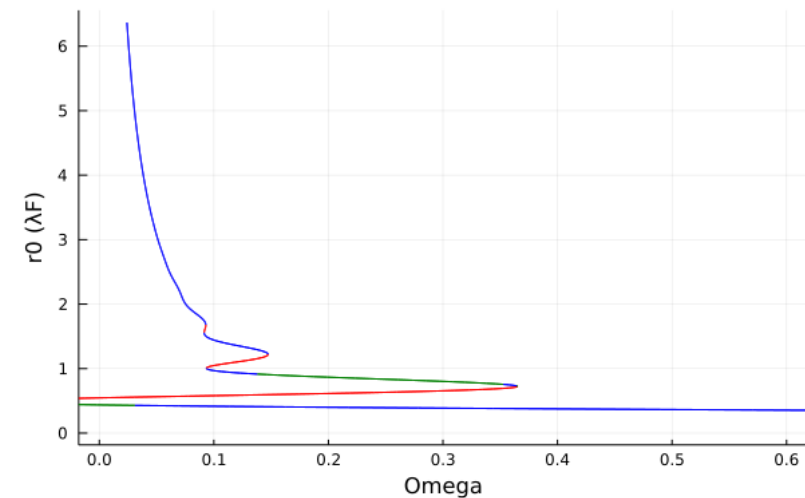
- Colour scheme: **stable**, **oscillatory unstable**, **non-oscillatory unstable**
- Horizontal slices result in the snake curves on the previous slides
- For larger mass, more stable orbital states can be observed

# Stability boundaries

- Two types of linear instabilities
  - Non-oscillatory instabilities: dominant eigenvalue is real and positive
  - Oscillatory instabilities: dominant eigenvalue is complex with positive real part
- For **non-oscillatory instabilities**, stability boundary occurs when 0 is the dominant (non-trivial) eigenvalue
  - 0 is a non-trivial eigenvalue when  $F'(0) = 0$
- For **oscillatory instabilities**, stability boundary occurs when the dominant non-trivial eigenvalue is imaginary
- On the snake curves, stability boundaries are where blue changes colour

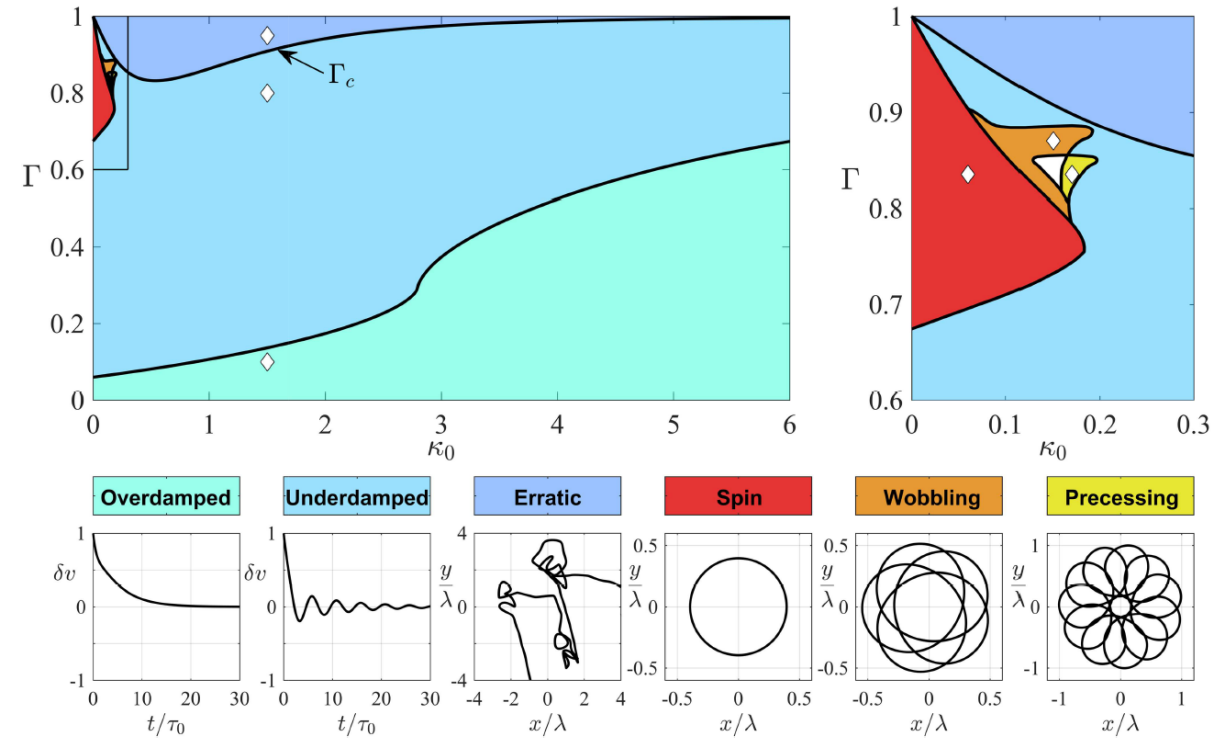
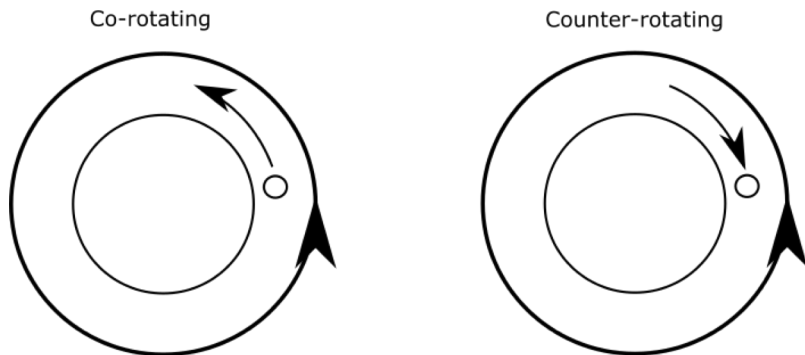


Stability for  $\Gamma = 0.76, \kappa_0 = 0.3$



# Effects of small rotation

- At zero rotation and high memory, always exists range of  $\kappa_0$  for which spin state is stable
- Not true with small rotation
- Bath rotation destroys the symmetry of the two directions of orbital states

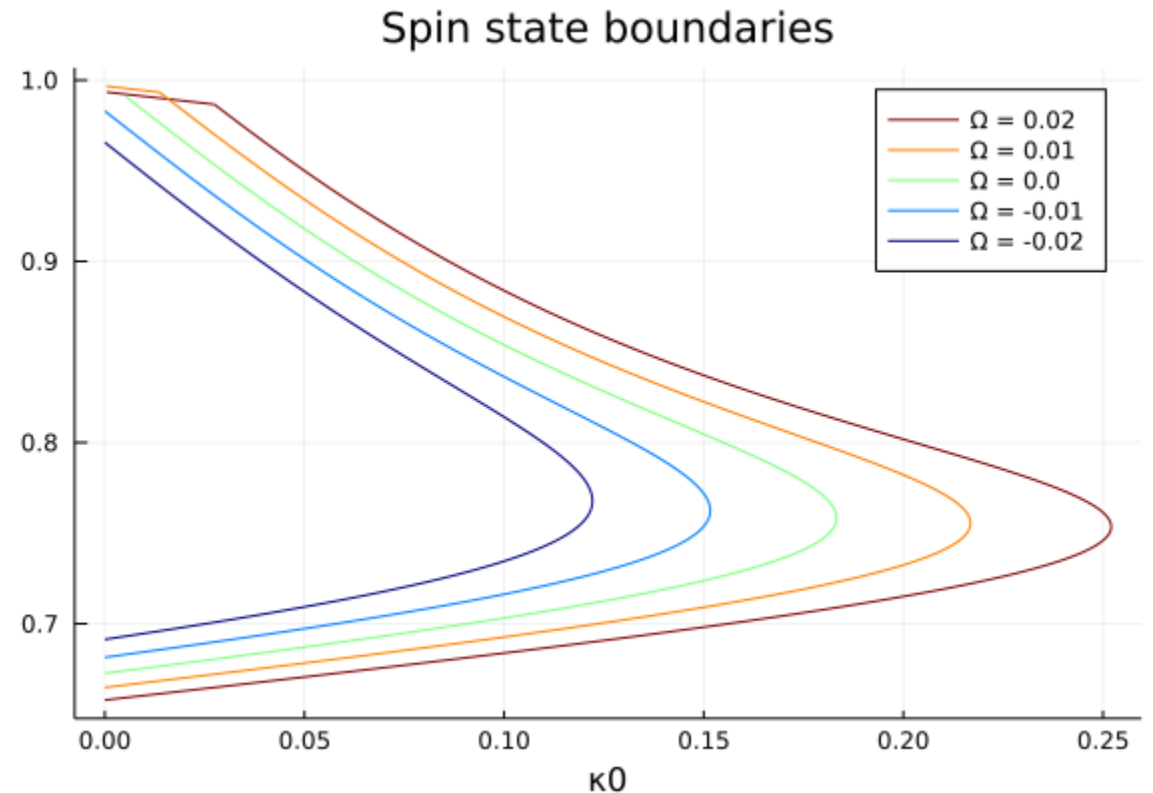


Consider bath rotation direction vs orbital direction



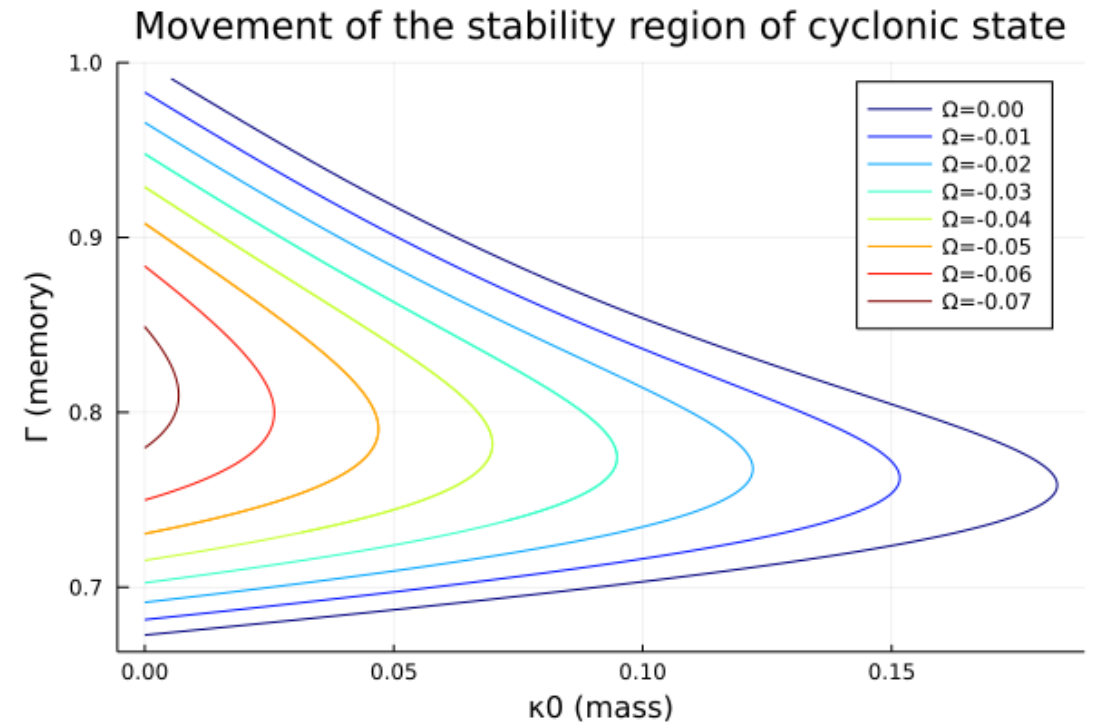
# Effects of small rotation on stability boundaries

- Here,  $\omega < 0$  for all states, so  $\Omega > 0$  corresponds to counter-rotating etc
- Counter-rotating spin states ( $\Omega = 0, \omega < 0$ ) are stabilised by weak rotation
- Co-rotating spin states are destabilised by weak rotation
- Can show asymptotically that  $\epsilon \sim 0.322\Omega$  for the stability boundary at  $\kappa_0 = 0$  for counter-rotating state, but  $\epsilon \sim -1.697\Omega$  for the co-rotating state
  - Mathematical justification for preference of counter-rotating state
- Can solve for location of the cusp asymptotically for small  $\Omega$  too



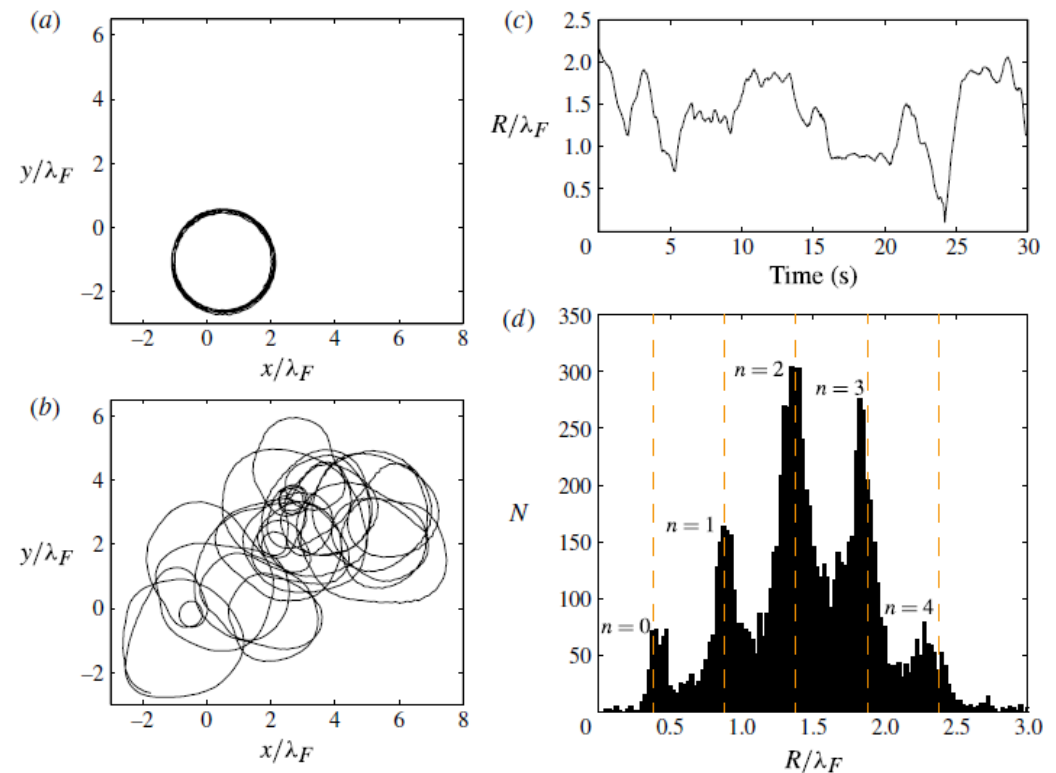
# Co-rotating state stability

- Stability region of co-rotating state shrinks with bath rotation
- Critical  $\Omega$  for which stability region vanishes is found by imposing  $\kappa_0 = \frac{d\kappa_0}{d\epsilon} = 0$  at the stability boundary
- Result:  $\Omega = -0.0732$
- No stable larger radius cyclonic states were found



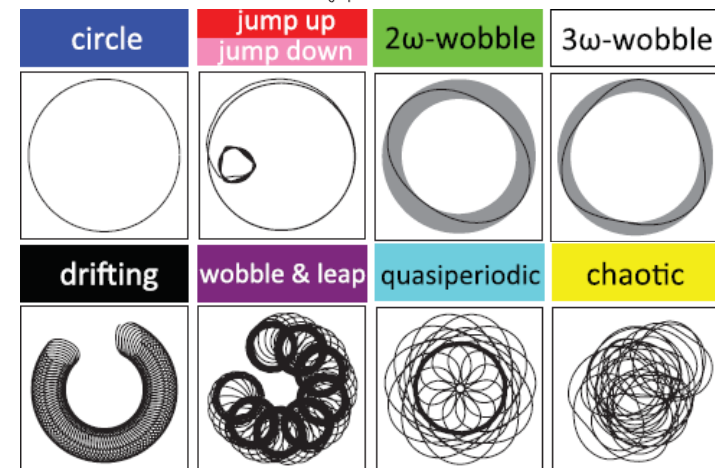
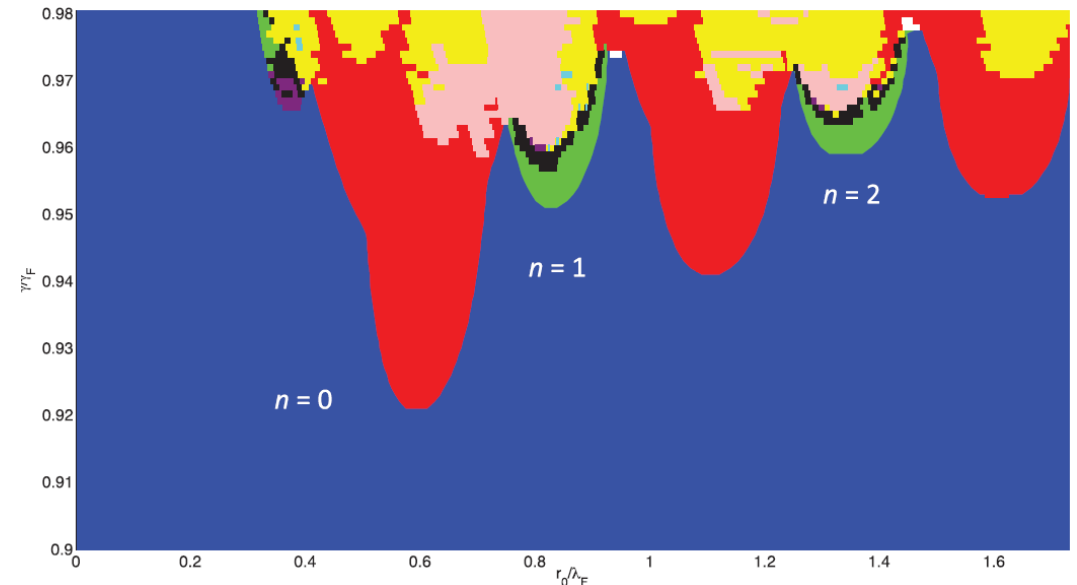
# Nonlinear dynamics: experiments (Harris et al, JFM 2014)

- Performed experiments on walking droplets in a rotating frame in high memory
- Describes onset of orbital quantization at low memory
- Wobbling orbits, chaotic orbits
  - Think of these as supercritical Hopf bifurcations of circular orbits
- Multimodal statistics when tracing histograms of radius of curvature



# Nonlinear dynamics: Oza et al. (2014) (PoF)

- Numerical solutions of trajectory equation
- Blue regions are stable, everything else linearly unstable
- Describes nonlinear behaviour in linearly unstable regions
- Simulated orbits were qualitatively in agreement with experiments of Harris



# Other developments (past, present and future)

- Past

- Hydrodynamic quantum analogs: use this system as an analogy of quantum mechanics, e.g. quantum tunnelling, quantum computers, double slit interference
- Lattices of bouncing droplets

- Present

- Me: investigating stability boundaries of rotating frame system in various asymptotic limits, like large rotation, large radius (first one is done, second one is partially done)
- Others: extension to 3D pilot wave systems, Bell's inequality

- Future

- Me: nonlinear dynamics of rotating frame, probability distributions of bouncing droplets and any relationships with quantum mechanics