

$$x = x(u, v), \quad y = y(u, v), \quad z = z(u, v).$$

there (u, v) varies through some region D (the domain) in the u, v -plane. (as w/ parametric curves, each choice of parameters gives a point of the surface; set of all choices $\rightarrow$ whole surface.)

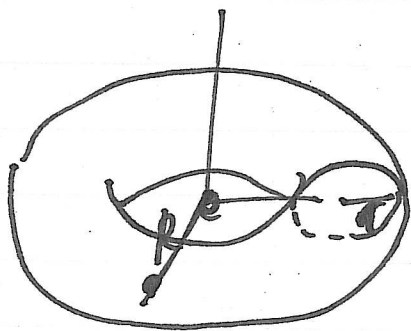
E.g. $\vec{r}(u, v) = \langle 2\cos u, v, 2\sin u \rangle$

What's the surface?

E.g. $\vec{r}(u, v) = \langle x_0, y_0, z_0 \rangle + u\vec{a} + v\vec{b}$ where

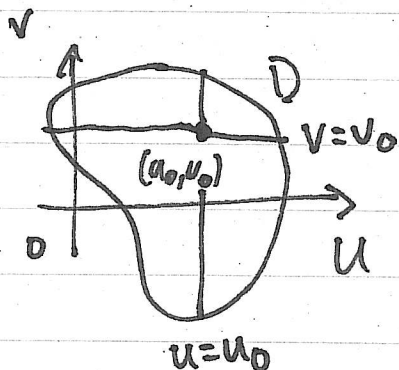
$\vec{a}, \vec{b}$ fixed 3D vectors (not parallel)

E.g. How to parametrize a torus?



Surface area of parametric surface

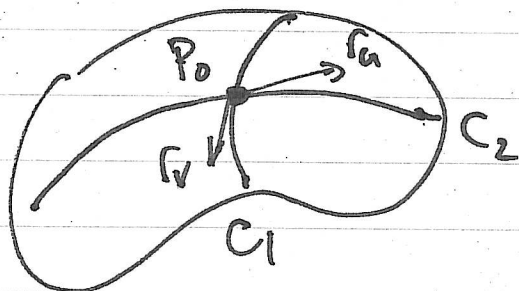
Idea: cut the surface into many little patches;
approximate area of each patch by area of
tangent plane.



$$P_0 = \vec{r}(u_0, v_0)$$

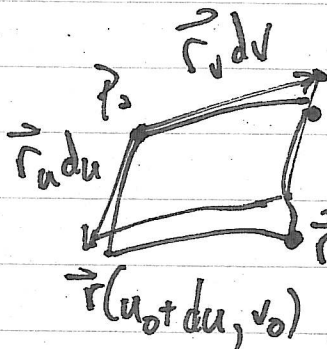
$\vec{r}(u_0, v)$ is a curve
on the surface (a "grid
curve") w/ tangent vector

$$\vec{r}_v(u_0, v_0) = \langle x_v(u_0, v_0), y_v(u_0, v_0), z_v(u_0, v_0) \rangle$$



at the point P_0 , & similarly

w/ C_2 , $\vec{r}(u, v_0)$, $\vec{r}_u(u_0, v_0)$.



little patch of surface associated to
the ~~square~~ rectangle
 (u_0, v_0) (u_0+du, v_0)
 (u_0, v_0+dv) (u_0+du, v_0+dv)

the u, v -plane is closely approximated by the

parallelogram w/ edges $\vec{r}_u du$ & $\vec{r}_v dv$

$$\Rightarrow dSA = |\vec{r}_u du \times \vec{r}_v dv| = |\vec{r}_u \times \vec{r}_v| du dv$$

$$\Rightarrow SA = \iint_D |\vec{r}_u \times \vec{r}_v| du dv$$

E.g. We saw that torus has parametric eqns

$$\vec{r}(u, v) = \langle (b + a \cos u) \cos v, (b + a \cos u) \sin v, a \sin u \rangle.$$

Thus $\vec{r}_u = \langle -a \sin u \cos v, -a \sin u \sin v, a \cos u \rangle$

& $\vec{r}_v = \langle -(b + a \cos u) \sin v, (b + a \cos u) \cos v, 0 \rangle$

$$\& SA = \int_0^{2\pi} \int_0^{2\pi} \left| \det \begin{bmatrix} \hat{i} & \hat{j} & \hat{k} \\ \vec{r}_u & \vec{r}_v & \end{bmatrix} \right| du dv$$

$$= \iint \text{etc.}$$

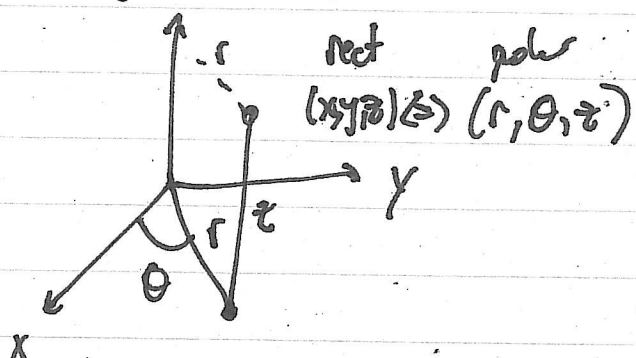
HW: derive the formula for SA of a surface

$$z = f(x, y).$$

(Maybe also for surfaces
of rotation?)

Cylindrical coordinates

Another useful coord. system: extends polar to 3D



Translation:

$$\begin{cases} x = r \cos \theta & y = r \sin \theta & z = z \\ r^2 = x^2 + y^2 & \tan \theta = \frac{y}{x} & z = z \end{cases}$$

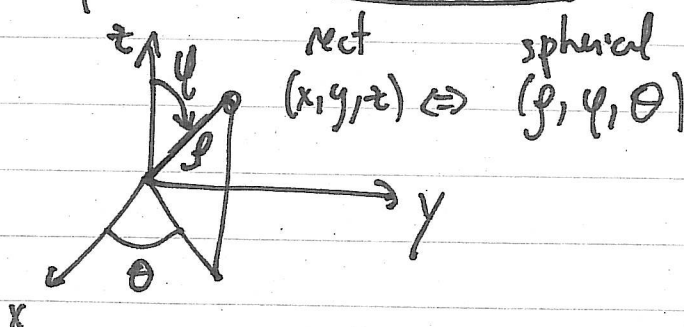
Simple graphs in cylindrical coords:

- $r = a$
- $\theta = \kappa$
- $z = a$
- $z = r$
- $z^2 + r^2 = a^2$

Cylindrical coordinates are most frequently used when describing objects with a high degree of axial symmetry.

Spherical coordinates

17.1



Translation

$$\begin{cases} x = \rho \sin \varphi \cos \theta & y = \rho \sin \varphi \sin \theta \\ z = \rho \cos \varphi \end{cases}$$

$$\rho^2 = x^2 + y^2 + z^2 \quad \tan \varphi = \frac{\sqrt{x^2 + y^2}}{z} \quad \tan \theta = \frac{y}{x}$$