Notation and Nomenclature

$\begin{array}{c} {\bf A} \\ {\bf A}_{ij} \\ {\bf A}_i \\ {\bf A}^{ij} \\ {\bf A}^n \end{array}$ $\begin{array}{c} {\bf A}^{-1} \\ {\bf A}^+ \\ {\bf A}^{1/2} \\ ({\bf A})_{ij} \\ {\bf A}_{ij} \\ [{\bf A}]_{ij} \\ {\bf a} \\ {\bf a}_i \\ {a_i} \\ {a} \end{array}$	Matrix Matrix indexed for some purpose Matrix indexed for some purpose Matrix indexed for some purpose or Matrix indexed for some purpose or The n.th power of a square matrix The inverse matrix of the matrix \mathbf{A} The pseudo inverse matrix of the matrix \mathbf{A} (see Sec. 3.6) The square root of a matrix (if unique), not elementwise The (i, j) .th entry of the matrix \mathbf{A} The ij -submatrix, i.e. \mathbf{A} with i.th row and j.th column deleted Vector (column-vector) Vector indexed for some purpose The i.th element of the vector \mathbf{a} Scalar
$\Re z$	Real part of a scalar
$\Re z$	Real part of a vector
$\Re Z$	Real part of a matrix
$\Im z$	Imaginary part of a scalar
$\Im z$	Imaginary part of a vector
$\Im Z$	Imaginary part of a matrix
$\begin{array}{c} \det(\mathbf{A}) \\ \mathrm{Tr}(\mathbf{A}) \\ \mathrm{diag}(\mathbf{A}) \\ \mathrm{eig}(\mathbf{A}) \\ \mathrm{vec}(\mathbf{A}) \\ \mathrm{sup} \\ \mathbf{A} \\ \mathbf{A}^{T} \\ \mathbf{A}^{-T} \\ \mathbf{A}^{*} \\ \mathbf{A}^{H} \end{array}$	Determinant of \mathbf{A} Trace of the matrix \mathbf{A} Diagonal matrix of the matrix \mathbf{A} , i.e. $(\operatorname{diag}(\mathbf{A}))_{ij} = \delta_{ij}A_{ij}$ Eigenvalues of the matrix \mathbf{A} The vector-version of the matrix \mathbf{A} (see Sec. 10.2.2) Supremum of a set Matrix norm (subscript if any denotes what norm) Transposed matrix The inverse of the transposed and vice versa, $\mathbf{A}^{-T} = (\mathbf{A}^{-1})^T = (\mathbf{A}^T)^{-1}$. Complex conjugated matrix Transposed and complex conjugated matrix (Hermitian)
$\mathbf{A} \circ \mathbf{B}$	Hadamard (elementwise) product
$\mathbf{A} \otimes \mathbf{B}$	Kronecker product
0	The null matrix. Zero in all entries.
Ι	The identity matrix
Ϳ ^{ij}	The single-entry matrix, 1 at (i, j) and zero elsewhere
Σ	A positive definite matrix
Λ	A diagonal matrix

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1 Basics

$$(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1} \tag{1}$$

$$(\mathbf{ABC}...)^{-1} = ...\mathbf{C}^{-1}\mathbf{B}^{-1}\mathbf{A}^{-1}$$
(2)
$$(\mathbf{A}^{T})^{-1} = (\mathbf{A}^{-1})^{T}$$
(3)

$$(\mathbf{A}^{T})^{T} = (\mathbf{A}^{T})^{T}$$
(3)
$$(\mathbf{A} + \mathbf{B})^{T} = \mathbf{A}^{T} + \mathbf{B}^{T}$$
(4)

$$(\mathbf{A}\mathbf{B})^T = \mathbf{B}^T \mathbf{A}^T$$
 (5)

$$(\mathbf{A}\mathbf{B}\mathbf{C}...)^T = \dots \mathbf{C}^T \mathbf{B}^T \mathbf{A}^T$$
(6)

$$(\mathbf{A}^{H})^{-1} = (\mathbf{A}^{-1})^{H}$$
 (7)

$$(\mathbf{A} + \mathbf{B})^H = \mathbf{A}^H + \mathbf{B}^H \tag{8}$$

$$(\mathbf{AB})^H = \mathbf{B}^H \mathbf{A}^H \tag{9}$$

$$(\mathbf{ABC}...)^H = ...\mathbf{C}^H \mathbf{B}^H \mathbf{A}^H \tag{10}$$

1.1 Trace

$$Tr(\mathbf{A}) = \sum_{i} A_{ii}$$
(11)
$$Tr(\mathbf{A}) = \sum_{i} \lambda_{i} \qquad \lambda_{i} = \operatorname{eig}(\mathbf{A})$$
(12)

$$\operatorname{Tr}(\mathbf{A}) = \sum_{i} \lambda_{i}, \quad \lambda_{i} = \operatorname{eig}(\mathbf{A})$$
(12)
$$\operatorname{Tr}(\mathbf{A}) = \operatorname{Tr}(\mathbf{A}^{T})$$
(13)

$$Ir(\mathbf{A}) = Ir(\mathbf{A}^{-})$$
(13)
$$Tr(\mathbf{AB}) = Tr(\mathbf{BA})$$
(14)

$$Tr(\mathbf{A} + \mathbf{B}) = Tr(\mathbf{A}) + Tr(\mathbf{B})$$
(11)
(14)

$$\operatorname{Tr}(\mathbf{ABC}) = \operatorname{Tr}(\mathbf{BCA}) = \operatorname{Tr}(\mathbf{CAB})$$
 (16)

$$\mathbf{a}^T \mathbf{a} = \operatorname{Tr}(\mathbf{a}\mathbf{a}^T) \tag{17}$$

1.2 Determinant

Let **A** be an $n \times n$ matrix.

$$\det(\mathbf{A}) = \prod_{i} \lambda_{i} \qquad \lambda_{i} = \operatorname{eig}(\mathbf{A}) \tag{18}$$

$$\det(c\mathbf{A}) = c^n \det(\mathbf{A}), \quad \text{if } \mathbf{A} \in \mathbb{R}^{n \times n}$$
(19)

$$det(\mathbf{A}^{T}) = det(\mathbf{A})$$
(20)
$$det(\mathbf{A}\mathbf{B}) = det(\mathbf{A}) det(\mathbf{B})$$
(21)

$$det(\mathbf{AB}) = det(\mathbf{A}) det(\mathbf{B})$$
(21)
$$det(\mathbf{A}^{-1}) = 1/det(\mathbf{A})$$
(22)

$$\det(\mathbf{A}^{n}) = 1/\det(\mathbf{A})$$
(22)

$$\det(\mathbf{A}^{n}) = \det(\mathbf{A})^{n}$$
(23)

$$\det(\mathbf{I} + \mathbf{u}\mathbf{v}^{T}) = 1 + \mathbf{u}^{T}\mathbf{v}$$
(24)

For n = 2:

$$\det(\mathbf{I} + \mathbf{A}) = 1 + \det(\mathbf{A}) + \operatorname{Tr}(\mathbf{A})$$
(25)

For n = 3:

$$det(\mathbf{I} + \mathbf{A}) = 1 + det(\mathbf{A}) + Tr(\mathbf{A}) + \frac{1}{2}Tr(\mathbf{A})^2 - \frac{1}{2}Tr(\mathbf{A}^2)$$
(26)

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$$det(\mathbf{I} + \mathbf{A}) = 1 + det(\mathbf{A}) + Tr(\mathbf{A}) + \frac{1}{2} + Tr(\mathbf{A})^2 - \frac{1}{2}Tr(\mathbf{A}^2) + \frac{1}{6}Tr(\mathbf{A})^3 - \frac{1}{2}Tr(\mathbf{A})Tr(\mathbf{A}^2) + \frac{1}{3}Tr(\mathbf{A}^3)$$
(27)

For small ε , the following approximation holds

$$\det(\mathbf{I} + \varepsilon \mathbf{A}) \cong 1 + \det(\mathbf{A}) + \varepsilon \operatorname{Tr}(\mathbf{A}) + \frac{1}{2} \varepsilon^2 \operatorname{Tr}(\mathbf{A})^2 - \frac{1}{2} \varepsilon^2 \operatorname{Tr}(\mathbf{A}^2)$$
(28)

1.3 The Special Case 2x2

Consider the matrix ${\bf A}$

$$\mathbf{A} = \left[\begin{array}{cc} A_{11} & A_{12} \\ A_{21} & A_{22} \end{array} \right]$$

Determinant and trace

$$\det(\mathbf{A}) = A_{11}A_{22} - A_{12}A_{21} \tag{29}$$

$$Tr(\mathbf{A}) = A_{11} + A_{22} \tag{30}$$

Eigenvalues

$$\lambda^{2} - \lambda \cdot \operatorname{Tr}(\mathbf{A}) + \det(\mathbf{A}) = 0$$

$$\lambda_{1} = \frac{\operatorname{Tr}(\mathbf{A}) + \sqrt{\operatorname{Tr}(\mathbf{A})^{2} - 4 \det(\mathbf{A})}}{2} \qquad \lambda_{2} = \frac{\operatorname{Tr}(\mathbf{A}) - \sqrt{\operatorname{Tr}(\mathbf{A})^{2} - 4 \det(\mathbf{A})}}{2}$$

$$\lambda_{1} + \lambda_{2} = \operatorname{Tr}(\mathbf{A}) \qquad \lambda_{1}\lambda_{2} = \det(\mathbf{A})$$

Eigenvectors

$$\mathbf{v}_{1} \propto \begin{bmatrix} A_{12} \\ \lambda_{1} - A_{11} \end{bmatrix} \qquad \mathbf{v}_{2} \propto \begin{bmatrix} A_{12} \\ \lambda_{2} - A_{11} \end{bmatrix}$$
$$\mathbf{A}^{-1} = \frac{1}{\det(\mathbf{A})} \begin{bmatrix} A_{22} & -A_{12} \\ -A_{21} & A_{11} \end{bmatrix} \qquad (31)$$

Inverse