

# Math 1B worksheet

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1. Consider the linear first-order differential equation

$$ty'(t) + 2y(t) = t^3, \quad t > 0. \quad (1)$$

Define the homogeneous equation

$$ty'(t) + 2y(t) = 0. \quad (2)$$

- (a) If  $y(t)$  is a solution of the homogeneous equation (2) and  $C$  is a constant, prove that  $Cy(t)$  is also a solution of (2).  
(b) Is part (a) true, say, for  $C = 2$ , if we replace (2) by the equation  $y' = y^2$ ?  
(c) Find the general solution of (2).  
(d) Show that the difference of any two solutions of (1) is a solution of (2).  
(e) Find the general solution of (1).  
(f) Find the solution of (1) satisfying  $y(1) = 0$ .
2. Consider the predator-prey system

$$\frac{dx}{dt} = -x + 2xy, \quad \frac{dy}{dt} = y - 3xy.$$

We will always assume that  $x$  and  $y$  are positive, except in the last part of the problem. We will sketch a graph of the trajectory of this system in the  $(x, y)$ -plane with the initial condition  $x(0) = y(0) = 1$ .

- (a) Which of the variables  $x$  and  $y$  represents the population of predators and which one represents the population of prey? Explain.  
(b) Find all equilibrium solutions and draw them on the graph.  
(c) Find for which  $(x, y)$  the value  $dx/dt$  is positive and when it is negative. Do the same for  $dy/dt$  and use this information to separate the graph into four regions based on the signs of  $dx/dt$  and  $dy/dt$ .  
(d) Assume that  $y$  is a function of  $x$  and use the chain rule to get a differential equation for  $y(x)$ . Using separation of variables, find an algebraic equation satisfied by  $(x(t), y(t))$  at all times.  
(e) Using part (c), find all the possible intersection points of the trajectory with the lines  $x = x_e$  and  $y = y_e$ , where  $(x_e, y_e)$  is the equilibrium point. Use this information to sketch the trajectory  $(x(t), y(t))$ .  
(f) What happens if we initially had  $x = 0$ ? What about  $y = 0$ ?

## Hints and answers

1. (a) Multiply the equation (2) by  $C$ .  
(b) No: the function  $2y$  satisfies the equation  $(2y)' = (2y)^2/2$ , not the original equation.  
(c)  $y = Ct^{-2}$ .  
(e)  $y = \frac{t^3}{5} + Ct^{-2}$ .  
(f)  $y = \frac{t^3 - t^{-2}}{5}$ .
2. (a)  $x$  is the population of the predators and  $y$  is the population of the prey.  
(b) The only equilibrium solution for  $x > 0$ ,  $y > 0$  is  $(x_e, y_e) = (1/3, 1/2)$ .  
(c) We have  $dx/dt > 0$  iff  $y > 1/2$  and  $dy/dt > 0$  iff  $x < 1/3$ . The trajectory should go around the equilibrium point in the clockwise direction.  
(d)  $\frac{dy}{dx} = \frac{y-3xy}{-x+2xy}$ ; separating variables, we find

$$2y - \ln y = -3x + \ln x + C.$$

Substituting the initial condition  $x = y = 1$ , we get  $C = 5$ .

- (e) Assume that  $y = y_e = 1/2$ ; then by the above,

$$-3x + \ln x = \ln 2 - 4.$$

The function  $-3x + \ln x$  increases for  $x < x_e$  and decreases for  $x > x_e$ . It goes to  $-\infty$  as  $x \rightarrow 0$  and as  $x \rightarrow +\infty$ . Finally, the value of this function at  $x_e$  is  $-\ln 3 > \ln 2 - 4$ . Therefore, our trajectory can intersect the line  $y = y_e$  only at two points, one of which lies below the equilibrium point and one above.

Similar analysis shows that our trajectory can intersect the line  $x = x_e$  only at two points, one of which lies to the left of the equilibrium point and one to the right. Therefore (there is a certain gap in reasoning here, though — can you see it?) the trajectory will be periodic.

- (f) For  $x = 0$ , we get  $dx/dt = 0$  and  $dy/dt = y$ . Therefore,  $x$  will stay zero and  $y$  will grow exponentially. Similarly, if  $y$  was initially zero, then it will stay zero and  $x$  will decrease exponentially to zero.