

We'll continue with Vershik-Okounkov construction.

Last time: G any finite group

- G has finitely many (up to isomorphism) irreducible representations V_λ , $\lambda \in G^\wedge$.

$|G^\wedge| = \# \text{conjugacy classes in } G$

- Group algebra of G

$$\mathbb{C}[G] = \left\{ \sum_{g \in G} f_g \cdot g \right\} \quad f_g \in \mathbb{C}$$

$$\simeq \left\{ \begin{bmatrix} d_1 & & & \\ \boxed{f_{11}} & d_2 & & \\ & \boxed{f_{12}} & \ddots & \\ & & \ddots & d_N \\ & & & \boxed{f_{NN}} \end{bmatrix} \right\}$$

algebra of block diagonal matrices (\mathbb{C})
(with square blocks)

block sizes d_1, \dots, d_N are $\dim(V_\lambda)$

(Here we assume $G^\wedge = \{1, \dots, N\}$)

$$N = |G^\wedge|.$$

Explicitly : Pick linear bases in all V_λ 's. Then the represent. V_λ is given by homomorphism:

$$R_\lambda : G \rightarrow \mathrm{GL}_{d_\lambda}$$

$d_\lambda \times d_\lambda$
matrices
w/ $\det \neq 0$

$$g \mapsto R(g) = \begin{bmatrix} R_1(g) & & & \\ & R_2(g) & & \\ & & \ddots & \\ & & & R_N(g) \end{bmatrix}$$

This linearly extends to the map $\mathbb{C}[G] \rightarrow \{ \text{block-diagonal matrices} \}$

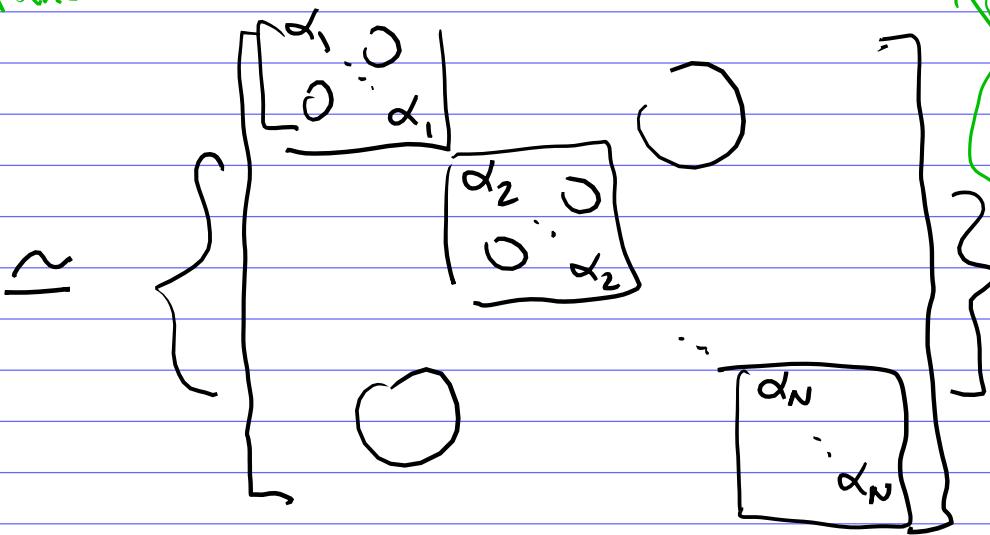
$$\sum_{g \in G} f_g g \mapsto \sum_{g \in G} f_g R(g)$$

- The center of the group algebra

$$Z_{\mathbb{C}[G]} := \left\{ f \in \mathbb{C}[G] \mid fg = gf \quad \forall g \in G \right\}$$

$$= \mathbb{C}_{\text{class}}(G) := \left\{ \sum_{g \in G} f_g \cdot g \mid g \mapsto f_g \text{ is a class function on } G \right\}$$

algebra of class functions.



$$\alpha_1, \dots, \alpha_N \in \mathbb{C}$$

- $G_0 = \{1\} \subset G_1 \subset G_2 \subset \dots$

any sequence of included groups.

- Bratteli diagram: directed

graph on vertex set $\bigcup_{i \geq 0} G_i^\wedge$

edges correspond to "branching

$$\text{rule"} \quad \text{Res}_{G_{n-1}}^{G_n} V_\lambda = \bigoplus V_\mu$$

$$\begin{matrix} \mu & \xrightarrow{m} & \lambda \\ \uparrow & & \uparrow \\ G_{n-1}^\wedge & & G_n^\wedge \end{matrix} \quad \text{if } V_\mu \text{ has appears in } \text{Res}_{G_{n-1}}^{G_n} V_\lambda$$

with multiplicity m .

- $\dim V_\lambda = \# \text{ directed paths}$

$$T = (\emptyset \rightarrow \dots \rightarrow \lambda)$$

in the Bratteli diagram

(here $G_0^\wedge = \{\emptyset\}$)

- Gelfand-Tsetlin basis of V_λ

$$\left\{ \sum_T \mid T = (\emptyset \rightarrow \dots \rightarrow \lambda) \right\}$$

$$V_\lambda \underset{\lambda \in G_n^\wedge}{\sim} \bigoplus_{\mu \in G_{n-1}^\wedge} V_\mu \underset{\nu \in G_{n-2}^\vee}{\sim} \bigoplus \left(\bigoplus V_\nu \right)$$

$$\leadsto \dots \leadsto V_\lambda = \bigoplus_T \left\{ \begin{array}{l} \text{one-dimensional} \\ \text{species} \end{array} \right\}$$

Then pick a generator s_T in each 1-dim spece.

- If Bratteli diagram does

not have multiple edges

then a Gelfand-Tsetlin

basis is unique up to

rescaling the vectors s_T .

$$G_0 \subset G_1 \subset G_2 \subset \dots$$

$$\mathbb{C}[G_0] \subset \mathbb{C}[G_1] \subset \mathbb{C}[G_2] \subset \dots$$
$$\cup \quad \cup \quad \cup$$
$$Z_0 \quad Z_1 \quad Z_2$$

$$Z_n := Z_{\mathbb{C}[G_n]} \quad \text{the center of group alg}$$

- Gelfand-Tsetlin subalgebra

$$GT_n \subset \mathbb{C}[G_n]$$

GT_n = algebra generated by Z_0, Z_1, Z_2, \dots

Proposition If we pick a GT-basis in each V_λ . Then

$$GT_n \cong \left\{ \begin{array}{l} \text{all diagonal} \\ \text{matrices} \end{array} \right\} \subset \left\{ \begin{bmatrix} \square & & & \\ & \square & & \\ & & \ddots & \\ & & & \square \end{bmatrix} \right\}$$

IS
 Z_n

In particular, GT_n is a maximal commutative subalgebra of $\mathbb{C}[G_n]$.

• The centralizer of $\mathbb{C}[G_{n-1}]$ is $\mathbb{C}[G_n]$

$$Z_{n-1,1} := \left\{ f \in \mathbb{C}[G_n] \mid f \cdot g = g \cdot f \quad \forall g \in G_{n-1} \right\}$$

all elements of $\mathbb{C}[G_n]$

that commute with all

elements of $\mathbb{C}[G_{n-1}]$

Proposition The Bratteli diagram
does not have multiple edges
iff all centralizers $Z_{n-1,1}$ are
commutative.

In this case,

- GT-basis $\{\mathfrak{f}_T\}$ is unique
(up to rescaling of \mathfrak{f}_T)
- a vector $\mathfrak{s} \in V_\lambda$ belongs
to GT-basis (up to resc.)
iff \mathfrak{s} is a common eigenvector
of all elements of GT_n
- Basis elements in GT-basis
are uniquely determined by
eigenvalues of elements of GT_n

We will not prove above Proposition.
Proofs can be found in the paper
by Vershik - Okounkov.

They are not very hard.

This is basically linear algebra.

Let's now specialize the above general construction to the case of symmetric groups S_n included into each other in the standard way:

$$S_0 \subset S_1 \subset S_2 \subset S_3 \subset \dots$$

(Young) - Jucys - Murphy

elements :

For $i=1, 2, \dots$

$$X_i := (1, i) + (2, i) + \dots + (i-1, i)$$

$$X_1 = 0$$

$$X_2 = (1, 2)$$

$$X_3 = (1, 3) + (2, 3)$$

$$X_4 = (1, 4) + (2, 4) + (3, 4)$$

etc.

$$\text{Recall, } Z_n := \mathbb{C}[S_n]$$

$$Z_{n-1} = \text{centralizer of } Z_{\mathbb{C}[S_{n-1}]}$$

$$GT_n = \text{subalg. of } \mathbb{C}[S_n]$$

generated by Z_1, Z_2, \dots, Z_n

$$Z_n \subset Z_{n-1,1} \subset GT_n \subset \mathbb{C}[S_n]$$

Clearly, $X_n = \sum_{\text{all transp. in } S_n}$
 $= \sum_{\text{all transp. in } S_{n-1}}$
 $\in \langle Z_n, Z_{n-1} \rangle \subset GT_n.$

Theorem. GT_n is the algebra generated by X_1, X_2, \dots, X_n :

$$GT_n = \langle X_1, X_2, \dots, X_n \rangle.$$

This follows from.

Theorem. $Z_{n-1,1}$ is generated by Z_{n-1} and X_n :

$$Z_{n-1,1} = \langle Z_{n-1}, X_n \rangle.$$

In particular, $Z_{n-1,1}$ is commutative. Thus the Bratteli diagram does not have multiple edges.

(It is easy to see that X_n commutes with Z_{n-1} .)

This claim can be proved by induction.

For a partition (c_1, \dots, c_e)

$$n = c_1 + \dots + c_e$$

Let $[\bar{c}_1, \dots, \bar{c}_e] := \sum_{\substack{w \in S_n \\ \text{with cyclic type} \\ c_1, \dots, c_e}} w \in \mathbb{C}[S_n]$

$$w = (\underbrace{\dots}_{c_1}) (\underbrace{\dots}_{c_2}) \dots (\underbrace{\dots}_{c_e})$$

A marked partition is
a partition with one marked
part $n = \bar{c}_1 + \dots + c_e$
(c_1 non necessarily the largest part)

$[\bar{c}_1, \dots, c_e] := \sum_{\substack{w \in S_n \\ \text{with cyclic} \\ \text{type } c_1, \dots, c_s \\ \text{s.t. cycle of size } c_1 \\ \text{contains } 'n')}$

Example $[\bar{2}, \underbrace{1, \dots, 1}_{n-2}] =$

= the sum of all transpositions
in S_n .

$[\bar{2}, \underbrace{1, \dots, 1}_{n-2}] =$ the sum of all
transp. (i, n) in S_n

$$= : X_n.$$

Easy Lemma

- Z_n has linear basis $\{C_1, \dots, C_\ell\}$
 (given by all partitions of n)
 - $Z_{n-1,1}$ has linear basis $\{\bar{C}_1, \dots, C_\ell\}$
 (given by all marked partitions of n)

(This directly follows from
definitions of $Z_n, Z_{n-1,1}$.)

All above claims about JM-elts

Lemmas All $\{\bar{c}_1, \dots, c_r\}$  

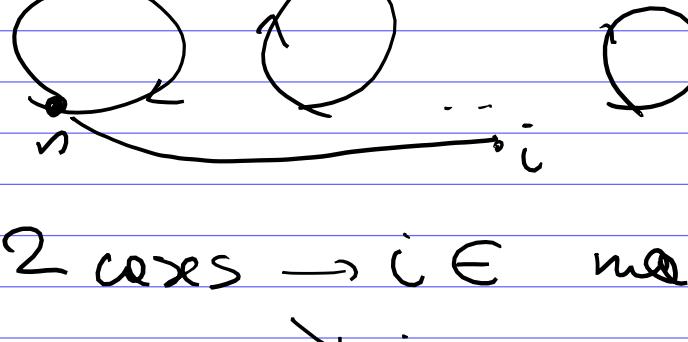
$$\underline{(c_1 + \dots + c_q) = v}$$

$$[\tilde{c}_1, \dots, \tilde{c}_e] \quad (\tilde{c}_1 + \dots + \tilde{c}_e = n-1)$$

and x_n .  (unmarked partitions of)

Project X : $\sqrt{5}$

c_1 c_2 c_3



Cycles c_i

C1 - marked
splits

\leftarrow 2 cyc

$$= \underbrace{c_1' + c_1''}_{\text{coeff.}} \left[c_1, c_1, c_2, \dots, c_e \right]$$

$$= \sum_{\substack{i \in \mathbb{F}_2 \\ \text{coeff}}} \left(\begin{array}{c} \text{some} \\ \text{non-zero} \\ \text{coeff} \end{array} \right) \left[\overline{c_1 + c_j}, c_i, \dots \hat{c_j} \dots \right]$$

(2000-08-11 14:00)

This idea

to prove

The term by the

Lemma \Rightarrow Each $[c_1, \dots, c_n]$
 $(c_1 + \dots + c_n = n)$ can be expressed
 in terms of x_1, x_2, \dots, x_n

\Leftrightarrow each element in \mathbb{Z}_n

can be expressed in x_1, \dots, x_n .

$\Leftrightarrow GT_n = \langle x_1, \dots, x_n \rangle$.

Examples

$$[2, \underbrace{1, \dots, 1}_{n-2}] = x_1 + \dots + x_n$$

$$[3, \underbrace{1, \dots, 1}_{n-3}] = x_1^2 + \dots + x_n^2 - \binom{n}{2}$$

etc.

Now we have:

Corollary Each irreducible representation V_λ of S_n has a unique (up to rescaling) basis $\{\psi_T\}$ (GT-basis)

such that the

vectors ψ_T are the common eigenvectors of JM-elements

$$x_1, \dots, x_n$$

Each basis vector ψ_T is uniquely determined by the collection (d_1, \dots, d_n) of eigenvalues

$$x_i \psi_T = d_i \psi_T.$$

Elements S_T of GT-basis

can be labelled by

- paths T in the Bratteli diagram
- vectors $(\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n$ of eigenvalues of X_1, \dots, X_n .

$$T \longleftrightarrow (\alpha_1, \dots, \alpha_n)$$

Let $\text{Spec}(n) :=$ the set of all possible vectors $(\alpha_1, \dots, \alpha_n)$ for all irreps of S_n

Equiv. relation

$$(\alpha_1, \dots, \alpha_n) \sim (\alpha'_1, \dots, \alpha'_n) \text{ if}$$

$(\alpha_1, \dots, \alpha_n)$ and $(\alpha'_1, \dots, \alpha'_n)$ correspond to vectors $S_T, S_{T'}$ in the GT-basis of the same irreducible representation V_λ .

Our goal is to describe $\text{Spec}(n) / \sim$ combinatorially

Our main tool is

Theorem The elements

s_1, \dots, s_{n-1} and x_1, \dots, x_n in $\mathbb{C}[S]$

satisfy the relations:

- Coxeter rels. for s_1, \dots, s_{n-1}

- $x_i x_j = x_j x_i, \forall i, j$

- $s_i x_j = x_j s_i, \text{ if } j \neq i, i+1$

- $s_i x_i = x_{i+1} s_i - 1$

- $s_i x_{i+1} = x_i s_i + 1.$

Proof Easy verification.

Def. The algebra with
above relations is called

Degenerate Affine Hecke Algebra
(DAHA).

Local Analysis of Spec(u).

$$(\alpha_1, \dots, \alpha_n) \in \text{Spec}(u)$$

corresp. to basis vector $s = \sum s_i e_i$ in V_λ

$$\bullet \alpha_1 = 0 \quad (\text{because } x_1 = 0)$$

$$\text{Suppose } \alpha_i = a, \alpha_{i+1} = b$$

$$x_i s = a s,$$

$$x_{i+1} s = b s$$

$$\text{Let } s' = s_i(s) \in V_\lambda$$

Consider 2 cases:

I. s & s' are lin. dependent

$$s_i^2 = 1 \Rightarrow s' = \pm s.$$

$$\text{DATA} \Rightarrow s_i x_i + 1 = s_i x_{i+1}$$

rels.

apply this to eigenvector s .

$$\pm a s + s = \pm b s$$

$$\boxed{b = a \mp 1}$$

II S, S' are linearly

independent \Rightarrow they

span 2-dim subspace

in V_λ .

The operators X_i, X_{i+1}, S_i act on the subspace $\langle S, S' \rangle$ by matrices:

$$X_i = \begin{pmatrix} a & -1 \\ 0 & b \end{pmatrix}, X_{i+1} = \begin{pmatrix} b & 1 \\ 0 & a \end{pmatrix}, S_i = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$X_i S = a_i S$$

$$X_i S' = X_i S_i(S) = (S_i X_{i+1}, -1) S$$

$$= -S + b S'.$$

etc.

DHTA relation

Observation $a \neq b$

(otherwise X_i has a

non-trivial Jordan block

$\begin{bmatrix} a & -1 \\ 0 & a \end{bmatrix}$ but we know

that X_i is diagonalizable.

Let's use the basis

$\{\tilde{S}, \tilde{S}\}$ instead of $\{S, S'\}$
where $\tilde{S} = S + (b-a)S'$.

$$X_i: \tilde{S} \mapsto b\tilde{S}$$

$$X_{i+1}: \tilde{S} \mapsto a\tilde{S}$$

the same
eigenvalue
as vector S

and $X_j \tilde{S} = \alpha_j \tilde{S}$

for any $j \neq i, i+1$

$\Rightarrow \tilde{S}$ is a common eigenvector
of X_1, \dots, X_n

$\Rightarrow \tilde{S} \in GT$ basis
(of the same irrep V_λ)

The vector of eigenvalues of \tilde{S}

is $\tilde{\alpha} = (\alpha_1, \dots, \underbrace{\alpha_{i+1}, \alpha_i, \dots, \alpha_n}_{\text{Transpose}})$

\uparrow transpose
 α_i and α_{i+1}
in vector α .

If $b = a \pm 1$ then $S_i \tilde{S} = \pm \tilde{S}$

$\Rightarrow \tilde{S} \propto s_i(\tilde{S})$ lin. dep.

$\Rightarrow S \propto s_i(S)$ lin. dep.

But we assume that $S \propto s_i(S)$
are indep \times

So we cannot have $b=a \pm 1$
in this case.

We obtain

Theorem. Let $\alpha = (\alpha_1, \dots, \alpha_n) \in \text{Spec}(A)$ correspond to vector \mathbf{v}_T in GT-basis

- $\alpha_1 = 0$
- $\alpha_i \neq \alpha_{i+1} \quad \forall i$
- if $\alpha_{i+1} = \alpha_i \pm 1$
then $s_i(\mathbf{v}_T) = \mp \mathbf{v}_T$
- If $\alpha_{i+1} \neq \alpha_i \pm 1$

then $\tilde{\alpha} = (\alpha_1, \dots, \alpha_{i+1}, \alpha_i, \dots, \alpha_n) \in \text{Spec}(A)$

$$\tilde{\alpha} \sim \alpha$$

$\tilde{\alpha}$ corresponds to basis vector $\mathbf{v}_{\tilde{T}}$

s_i preserves the 2-dim
subspace $\langle \mathbf{v}_T, \mathbf{v}_{\tilde{T}} \rangle$

- We cannot have

$$\alpha = (\alpha_1, \dots, \alpha_n) = (\dots, -a, a \pm 1, a, \dots)$$

Proof We already proved
everything except the last claim

Last claim: Suppose

$$\alpha = (\dots, \overset{i}{-a}, \overset{i+1}{a+1}, \overset{i}{a}, \dots)$$

$$s_i s_{i+1} s_i (\mathbf{v}_T) = - \mathbf{v}_T$$

.||

$$s_{i+1} s_i s_{i+1} (\mathbf{v}_T) = \mathbf{v}_T$$

Contradiction.



Claim The above conditions uniquely describe the set $\text{Spec}(n)$ & equiv. rel. \sim .

Let's be more specific.

Define An allowed transposition

as $(\alpha_1 \dots \alpha_s) \longleftrightarrow (\alpha_1 \dots \alpha_{i+1} \alpha_i \dots \alpha_s)$

if $\alpha_{i+1} \neq \alpha_i \pm 1$.

Define $\text{Cont}(n) \in \mathbb{Z}^n$
the set of vectors $(\alpha_1, \dots, \alpha_n)$
such that

- $\alpha_1 = 0$

- If $\alpha \leftrightarrow \tilde{\alpha}$ is an allowed transposition then $\tilde{\alpha} \in \text{Cont}(n)$

- If $\alpha_i = \alpha_j = a$, $i < j$, then $a-1, a+1 \in \{\alpha_{i+1}, \alpha_{i+2}, \dots, \alpha_{j-1}\}$

Let \approx be an equiv. rel. on $\text{Cont}(n)$ generated by allowed transpositions.

We proved that

$$\text{Spec}(u) \subseteq \text{Cont}(u)$$

$$\alpha \sim \alpha' \Rightarrow \alpha \approx \alpha'$$

Theorem The set $\text{Cont}(u)$

is in bijection with stand.

Young tableaux of some shape $\lambda \vdash u$

$\alpha \approx \alpha'$ if corresp.

SYT's have the same shape

So $\# \approx$ -equiv. classes

$$= p(u) (\# \text{ Young tableaux} \atop \lambda \vdash u)$$

On the other hand.

$$\#\{\sim\text{-equiv. classes in } \text{Spec}(u)\})$$

$$= \# \text{ irreps of } S_u = p(u)$$

So we get

Theorem $\text{Spec}(u)/\sim$

$$= \text{Cont}(u)/\approx$$