18.600: Lecture 33 Markov Chains

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Markov chains

Examples

Ergodicity and stationarity

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Ergodicity and stationarity

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 Kind of an "almost memoryless" property. Probability distribution for next state depends only on the current state (and not on the rest of the state history). For example, imagine a simple weather model with two states: rainy and sunny.

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- Given that it is sunny today, how many days to I expect to have to wait to see a rainy day?
- Over the long haul, what fraction of days are sunny?

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▶ For this to make sense, we require $P_{ij} \ge 0$ for all i, j and $\sum_{j=0}^{M} P_{ij} = 1$ for each i. That is, the rows sum to one.

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Answer: the probability distribution at time *n*.

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► If A is the one-step transition matrix, then Aⁿ is the *n*-step transition matrix.

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- Answer: state evolution is deterministic.

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Can compute
$$A^{10} = \begin{pmatrix} .285719 & .714281 \\ .285713 & .714287 \end{pmatrix}$$





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- Markov model implies time spent in any state (e.g., a marriage) before leaving is a geometric random variable.
- Not true... Can we make a better model with more states?

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- This means that the row vector

$$\pi = \left(\begin{array}{ccc} \pi_0 & \pi_1 & \dots & \pi_M \end{array}\right)$$

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- We call π the stationary distribution of the Markov chain.
- One can solve the system of linear equations
 π_j = Σ^M_{k=0} π_kP_{kj} to compute the values π_j. Equivalent to
 considering A fixed and solving πA = π. Or solving
 (A − I)π = 0. This determines π up to a multiplicative
 constant, and fact that Σπ_j = 1 determines the constant.

► If
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, then we know
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► This means that $.5\pi_0 + .2\pi_1 = \pi_0$ and $.5\pi_0 + .8\pi_1 = \pi_1$ and we also know that $\pi_0 + \pi_1 = 1$. Solving these equations gives $\pi_0 = 2/7$ and $\pi_1 = 5/7$, so $\pi = (2/7 \ 5/7)$.

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► Recall that

$$A^{10} = \begin{pmatrix} .285719 & .714281 \\ .285713 & .714287 \end{pmatrix} \approx \begin{pmatrix} 2/7 & 5/7 \\ 2/7 & 5/7 \end{pmatrix} = \begin{pmatrix} \pi \\ \pi \end{pmatrix}$$