18.600: Lecture 27 Conditional expectation

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Conditional probability distributions

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Interpretation and examples

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- Often useful to think of sampling (X, Y) as a two-stage process. First sample Y from its marginal distribution, obtain Y = y for some particular y. Then sample X from its probability distribution given Y = y.
- Marginal law of X is weighted average of conditional laws.

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- Can make sense of this in the continuum setting as well.
- ► In continuum setting we had $f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$. So $E[X|Y = y] = \int_{-\infty}^{\infty} x \frac{f(x,y)}{f_Y(y)} dx$

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- $E[E[X|Y = y]] = \sum_{y} p_Y(y) \sum_{x} x \frac{p(x,y)}{p_Y(y)} = \sum_{x} \sum_{y} p(x,y) x = E[X].$

Conditional variance

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- Above fact breaks variance into two parts, corresponding to these two stages.

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- Can we check the formula Var(Z) = Var(E[Z|X]) + E[Var(Z|X)] in this case?

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- But what if we allow non-constant predictors? What if the predictor is allowed to depend on the value of a random variable X that we can observe directly?
- Let g(x) be such a function. Then E[(y − g(X))²] is minimized when g(X) = E[Y|X].

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 $> 2 + 3 \cdot 2/50$