

**INTRODUCTION  
TO  
LINEAR  
ALGEBRA  
Fifth Edition**

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**MANUAL FOR INSTRUCTORS**

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## Problem Set 12.1, page 544

- 1 When 7 is added to every output, the mean increases by 7 and the variance does not change (because new variance comes from (distance)<sup>2</sup> to the new mean).

New sample mean and new expected mean : Add 7. New variance : No change.

- 2 If we add  $\frac{1}{3}$  to  $\frac{1}{7}$  (fraction of integers divisible by 3 *plus* fraction divisible by 7) we have **double counted** the integers divisible by both 3 and 7. This is a fraction  $\frac{1}{21}$  of all integers (because these double counted numbers are multiples of 21). So the fraction divisible by 3 or 7 or both is

$$\frac{1}{3} + \frac{1}{7} - \frac{1}{21} = \frac{7}{21} + \frac{3}{21} - \frac{1}{21} = \frac{9}{21} = \frac{3}{7}.$$

- 3 In the numbers from 1 to 1000, each group of ten numbers will contain each possible ending  $x = 1, 2, 3, \dots, 0$ . So those endings all have the same probability  $p_i = \frac{1}{10}$ .

Expected mean of that last digit  $x$  :

$$m = E[x] = \sum p_i x_i = \frac{1}{10} \sum_{i=0}^9 i = \frac{45}{10} = 4.5$$

The best way to find the variance  $\sigma^2 = 8.25$  is **in the last line below and in problem**

**12.1.7.** The slower way to find  $\sigma^2$  is

$$\sigma^2 = E[(x - 4.5)^2] = \sum_{i=0}^9 p_i (x_i - 4.5)^2 = \frac{1}{10} \sum_{i=0}^9 (i - 4.5)^2$$

We can separate  $(i - 4.5)^2$  into  $(i^2 - 9i + (4.5)^2)$  and add from  $i = 0$  to  $i = 9$  :

$$\begin{aligned} \frac{1}{10} \left( \sum_0^9 i^2 - 9 \sum_0^9 i + \sum_0^9 (4.5)^2 \right) &= \frac{1}{10} (285 - 9(45) + 10(4.5)^2) \\ &= \frac{1}{10} (285 - 405 + 202.5) = \frac{82.5}{10} = 8.25 = \frac{33}{4}. \end{aligned}$$

Notice that 202.5 is half of 405—like  $Nm^2$  and  $2Nm^2$  in equation (4), page 536.

**I should have extended equation (4) to its best form :**

$$\sigma^2 = E[(x - m)^2] = E[x^2] - m^2$$

That quickly gives  $\frac{285}{10} - (4.5)^2 = 8.25 =$  same answer.

- 4** For numbers ending in 0, 1, 2, ..., 9 the squares end in  $x = 0, 1, 4, 9, 6, 5, 6, 9, 4, 1$ . So the probabilities of  $x = 0$  and 5 are  $p = \frac{1}{10}$  and the probabilities of  $x = 1, 4, 6, 9$  are  $p = \frac{1}{5}$ . The mean is

$$m = \sum p_i x_i = \frac{0}{10} + \frac{5}{10} + \frac{1}{5}(1 + 4 + 6 + 9) = 4.5 = \text{same as before.}$$

The variance using the improvement of equation (4) is

$$\begin{aligned} \sigma^2 &= E[x^2] - m^2 = \frac{1}{10}0^2 + \frac{1}{10}5^2 + \frac{1}{5}(1^2 + 4^2 + 6^2 + 9^2) - m^2 \\ &= \frac{25}{10} + \frac{134}{5} - 20.25 = \mathbf{9.05} \end{aligned}$$

- 5** For numbers from 1 to 1000, the first digit is  $x = 1$  for 1000 and 100-199 and 10-19 and 1 (112 times). The first digit is  $x = 2$  for 200-299 and 20-29 and 2 (111 times). The other first digits  $x = 3$  to 9 also happen (111 times). Total (1000 times) is correct.

The average first digit is the mean, close to  $\frac{1}{9}(1 + 2 + \dots + 9) = 5$ :

$$m = \sum p_i x_i = \frac{112}{1000}(1) + \frac{111}{1000}(2+3+\dots+9) = \frac{112 + 111(44)}{1000} = \frac{4996}{1000} = 4.996 \approx 5.$$

The variance is

$$\begin{aligned} \sigma^2 &= E[(x - m)^2] = E[x^2] - m^2 = \frac{112}{1000}(1^2) + \frac{111}{1000}(2^2 + \dots + 9^2) - m^2 \\ &= \frac{112 + 111(284)}{1000} - m^2 \approx \frac{31635}{1000} - 5^2 = \mathbf{6.635}. \end{aligned}$$

- 6** The first digits of  $157^2, 312^2, 696^2$ , and  $602^2$  are **2, 9, 4, 3**. The sample mean is  $\frac{1}{4}(2 + 9 + 4 + 3) = \frac{18}{4} = \mathbf{4.5}$ . The sample variance with  $N - 1 = 3$  is

$$S^2 = \frac{1}{3} [(-2.5)^2 + (4.5)^2 + (-.5)^2 + (-1.5)^2] = \frac{1}{3} [29].$$

- 7** This question is about the fast way to compute  $\sigma^2$  using  $m^2$ . The mean  $m$  is probably already computed:

$$\begin{aligned} \sigma^2 &= \sum p_i (x_i - m)^2 = \sum p_i (x_i^2 - 2mx_i + m^2) \\ &= \sum p_i x_i^2 - 2m \sum p_i x_i + m^2 \sum p_i \\ &= \sum p_i x_i^2 - 2m^2 + m^2 = \sum p_i x_i^2 - m^2 = E[x^2] - m^2. \end{aligned}$$

- 8 For  $N = 24$  samples, all equal to  $x = 20$ ,

$$\mu = \frac{1}{N} \sum x_i = \frac{24}{24}(20) = \mathbf{20} \quad \text{and} \quad S^2 = \frac{1}{N-1} \sum (x_i - \mu)^2 = \mathbf{0}$$

For 12 samples of  $x = 20$  and 12 samples of  $x = 21$ ,

$$\mu = \frac{12(20) + 12(21)}{24} = \mathbf{20.5} \quad \text{and} \quad S^2 = \frac{1}{N-1} \sum (x_i - \mu)^2 = \frac{1}{23} 24 \left(\frac{1}{2}\right)^2 = \frac{\mathbf{6}}{\mathbf{23}}.$$

- 9 This question asks you to set up a random 0-1 generator and run it a million times to find the average  $A_{1000000}$ .

One way is to use MATLAB's **rand** command with a uniform distribution between 0 and 1. Add  $\frac{1}{2}$  to go between 0.5 and 1.5, then find the integer part (0 or 1). Using your computed average  $A_N$  (its mean is  $m = \frac{1}{2}$  since 0 and 1 are equally likely for every sample) find the normalized variable  $X$ :

$$X = \frac{A_N - \frac{1}{2}}{2\sqrt{N}} = \frac{A_N - \frac{1}{2}}{2000} \quad \text{for } N = \text{one million.}$$

- 10 The average number of heads in  $N$  fair coin flips is  $m = N/2$ . This is obvious—but how to derive it from probabilities  $p_0$  to  $p_N$  of 0 to  $N$  heads? We have to compute

$$m = 0p_0 + 1p_1 + \cdots + Np_N \quad \text{with} \quad p_i = \frac{b_i}{2^N} = \frac{1}{2^N} \frac{N!}{i!(N-i)!}$$

A useful fact is  $p_i = p_{N-i}$ . The probability of  $i$  **heads** equals the probability of  $i$  **tails**.

If we take just those two terms in  $m$ , they give

$$ip_i + (N-i)p_{N-i} = ip_i + (N-i)p_i = Np_i$$

So we can compute  $m$  two ways and add:

$$\begin{aligned} m &= 0p_0 + 1p_1 + \cdots + (N-1)p_{N-1} + Np_N \\ m &= Np_0 + (N-1)p_1 + \cdots + 1p_{N-1} + 0p_N \\ 2m &= Np_0 + Np_1 + \cdots + Np_{N-1} + Np_N \\ &= N(p_0 + p_1 + \cdots + p_{N-1} + p_N) = \mathbf{N}. \end{aligned}$$

Then  $m = N/2$ . The average number of heads is  $N/2$ .

$$\begin{aligned}
11 \quad \mathbf{E}[x^2] &= \mathbf{E}[(x - m)^2 + 2xm - m^2] \\
&= \mathbf{E}[(x - m)^2] + 2m \mathbf{E}[x] - m^2 \mathbf{E}[1] \\
&= \sigma^2 + 2m^2 - m^2 = \sigma^2 + m^2
\end{aligned}$$

12 The first step multiplies two independent 1-dimensional integrals (each one from  $-\infty$  to  $\infty$ ) to produce a 2-dimensional integral over the whole plane :

$$2\pi \int_{-\infty}^{\infty} p(x) dx \int_{-\infty}^{\infty} p(y) dy = 2\pi \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p(x) p(y) dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-x^2/2} e^{-y^2/2} dx dy.$$

The second step changes to polar coordinates ( $x = r \cos \theta$ ,  $y = r \sin \theta$ ,  $dx dy = r dr d\theta$ ,  $x^2 + y^2 = r^2$  with  $0 \leq \theta \leq 2\pi$  and  $0 \leq r \leq \infty$ ). Notice  $-x^2/2 - y^2/2 = -r^2/2$ :

$$\int_{\text{plane}} \int e^{-r^2/2} r dr d\theta = \int_{\theta=0}^{2\pi} \int_{r=0}^{\infty} e^{-r^2/2} r dr d\theta$$

The  $r$  and  $\theta$  integrals give the answers 1 and  $2\pi$  :

$$\int_{r=0}^{\infty} e^{-r^2/2} r dr = \left[ -e^{-r^2/2} \right]_{r=0}^{\infty} = 1 \quad \int_{\theta=0}^{2\pi} 1 d\theta = 2\pi.$$

The trick was to get  $e^{-r^2/2} r dr$  (which is a perfect derivative of  $-e^{-r^2/2}$ ) by combining  $e^{-x^2/2} dx$  and  $e^{-y^2/2} dy$  (which can *not* be separately integrated from  $a$  to  $b$ ).

## Problem Set 12.2, page 554

1 (a) Mean  $m = \mathbf{E}[x] = (0)(1 - p) + (1)(p) = p$  when the probability of heads is  $p$ . Here  $x = 0$  for tails and  $x = 1$  for heads. Notice that  $0^2 = 0$  and  $1^2 = 1$  so  $\mathbf{E}[x^2] = \mathbf{E}[x] = p$ .

$$\text{Variance } \sigma^2 = \mathbf{E}[x^2] - m^2 = p - p^2$$

(b) These are independent flips ! So the  $N$  by  $N$  covariance matrix  $V$  is diagonal. The diagonal entries are the variances  $\sigma^2 = p - p^2$  for each flip. Then the rule (16–17–18) gives the overall variance of the sum from  $N$  flips :

$$\text{overall variance} = [1 \ 1 \dots 1] V \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = N\sigma^2 = N(p - p^2)$$

This is just saying : Add the variances for the  $N$  independent experiments. Here those  $N$  experiments just repeat one experiment.

- 2 I am just imitating equation (2) in the text. Now the experiments are numbered 3 and 5. They have means  $m_3$  and  $m_5$ . The covariance  $\sigma_{35}$  adds up **joint probabilities**  $p_{ij}$  times (distance  $x_i - m_3$ ) times (distance  $y_j - m_5$ ). Here  $x_i$  and  $y_j$  are outputs from experiments 3 and 5 :

$$\sigma_{35} = \sum_{\text{all } i, j} p_{ij} (x_i - m_3) (y_j - m_5).$$

- 3 The 3 by 3 covariance matrix  $V$  will be a sum of rank one matrices  $V_{ijk} = UU^T$  multiplied by the joint probability  $p_{ijk}$  of outputs  $x_i, y_j, z_k$ . I am copying equation (12) :

$$V = \sum_{\text{all } i, j, k} p_{ijk} UU^T \quad U = \begin{bmatrix} \text{output } x_i - \text{mean } \bar{x} \\ \text{output } y_j - \text{mean } \bar{y} \\ \text{output } z_k - \text{mean } \bar{z} \end{bmatrix}$$

These matrices  $UU^T = \text{column times row}$  are positive semidefinite with rank 1 (unless  $U = \mathbf{0}$ ). The sum  $V$  is positive *definite* unless the 3 experiments are dependent.

Notice that the means  $\bar{x}, \bar{y}, \bar{z} = m_1, m_2, m_3$  have to be computed before the variances.

- 4 We are told that the 3 experiments are *independent*. Then the *covariances are zero* off the main diagonal of  $V$ . This covariance matrix only shows “covariances with itself” = “variances”  $\sigma_1^2, \sigma_2^2, \sigma_3^2$  on the main diagonal.

$$V = \begin{bmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \sigma_2^2 & 0 \\ 0 & 0 & \sigma_3^2 \end{bmatrix}.$$

- 5** The point is that some output  $X = x_i$  must occur. So the possibilities are  $Y = y_j$  and  $X = x_1$ , or  $Y = y_j$  and  $X = x_2$ , or  $Y = y_j$  and  $X = x_3$  et cetera. The total probability of  $Y = y_j$  is the sum of the conditional probabilities that  $Y = y_j$  when  $X = x_i$ .

Here is another way to say this **law of total probability**. When  $B_1, B_2, \dots$  are separate disjoint outcomes that together account for all possible outcomes, then for any  $A$

$$\text{Prob}(A) = \sum_i \text{Prob}(A \cap B_i) = \sum_i \text{Prob}(A|B_i) \text{Prob}(B_i).$$

- 6**  $\text{Prob}(A|B)$  = **conditional probability** of  $A$  given  $B$  satisfies this axiom:

$$\text{Prob}(A \text{ and } B) = \text{Prob}(A|B) \text{Prob}(B).$$

Reason: If both  $A$  and  $B$  occur, then  $B$  must occur—and knowing that  $B$  occurs,  $\text{Prob}(A|B)$  gives the probability that  $A$  also occurs.

This axiom is saying that  $p_{ij} = \text{Prob}(A|B) p_i$

where  $B$  is the event  $x = x_i$  which has  $\text{Prob}(B) = p_i$ .

- 7** The joint probabilities  $p_{ij} = \text{Prob}(x = x_i \text{ and } y = y_j)$  are in the matrix  $P$ :

$$P = \begin{bmatrix} 0.1 & 0.3 \\ 0.2 & 0.4 \end{bmatrix} \text{ with entries adding to 1.}$$

$$\text{Problem 6 says that } \text{Prob}(Y = y_2|X = x_1) = \frac{p_{12}}{p_{11} + p_{12}} = \frac{0.3}{0.1 + 0.3} = \frac{3}{4}.$$

Problem 5 says that  $\text{Prob}(X = x_1) = p_{11} + p_{12} = 0.1 + 0.3 = \mathbf{0.4}$ .

- 8** This product rule of conditional probability is the axiom in Solution 12.2.6 above:

$$\text{Prob}(A \text{ and } B) = \text{Prob}(A \text{ given } B) \text{ times Prob}(B).$$

9 This discussion of Bayes' Theorem is much too compressed! Let me reproduce three equations from Wolfram MathWorld. Here  $A$  and  $B$  are possible "sets" = "outcomes from an experiment" and the simple-looking identity (\*) connects conditional and unconditional probabilities.

We know from 8 that  $\text{Prob}(A \text{ and } B) = \text{Prob}(A \text{ given } B) \text{ times } \text{Prob}(B)$

Reversing  $A$  and  $B$  gives  $\text{Prob}(A \text{ and } B) = \text{Prob}(B \text{ given } A) \text{ times } \text{Prob}(A)$

$$(*) \text{ Therefore } \text{Prob}(B \text{ given } A) = \frac{\text{Prob}(A \text{ given } B) \text{Prob}(B)}{\text{Prob}(A)}$$

MathWorld gives this extension to non-overlapping sets  $A_1, \dots, A_n$  whose union is  $A$ :

$$\text{Prob}(A_i \text{ given } A) = \frac{\text{Prob}(A_i) \text{Prob}(A \text{ given } A_i)}{\sum_j \text{Prob}(A_j) \text{Prob}(A \text{ given } A_j)}$$

### Problem Set 12.3, page 560

1 The two equations from two measurements are

$$\begin{aligned} x = b_1 \\ x = b_2 \end{aligned} \quad \text{or} \quad \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} x \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad \text{or} \quad A\mathbf{x} = \mathbf{b}.$$

The covariance matrix  $V$  is diagonal since the measurements are independent:

$$V = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}.$$

The weighted least squares equation is  $A^T V^{-1} A \hat{\mathbf{x}} = A^T V^{-1} \mathbf{b}$ .

$$A^T V^{-1} A = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}$$

$$A^T V^{-1} \mathbf{b} = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \frac{b_1}{\sigma_1^2} + \frac{b_2}{\sigma_2^2}$$

Then  $\hat{\mathbf{x}}$  is the ratio of those numbers:

$$\hat{\mathbf{x}} = \frac{b_1/\sigma_1^2 + b_2/\sigma_2^2}{1/\sigma_1^2 + 1/\sigma_2^2}$$



The variance of that estimate  $\hat{\mathbf{x}}$  should be written as in (13) :

$$\mathbb{E} [(\hat{\mathbf{x}} - \mathbf{x})(\hat{\mathbf{x}} - \mathbf{x})^T] = (A^T V^{-1} A)^{-1} = \left( \frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2} \right)^{-1}.$$

2 (a) In the limit  $\sigma_2 \rightarrow 0$  the ratio  $\hat{\mathbf{x}}$  approaches  $b_2$  because :

$$\text{(Multiply } \hat{\mathbf{x}} \text{ above and below by } \sigma_1^2 \sigma_2^2) \quad \hat{\mathbf{x}} = \frac{b_1 \sigma_2^2 + b_2 \sigma_1^2}{\sigma_2^2 + \sigma_1^2} \rightarrow \frac{b_2 \sigma_1^2}{\sigma_1^2} = \mathbf{b}_2.$$

The second equation  $x = b_2$  is 100% accurate if its variance is  $\sigma_2 = 0$ .

(b) If  $\sigma_2 \rightarrow \infty$  then  $1/\sigma_2^2 \rightarrow 0$  and  $\hat{\mathbf{x}} \rightarrow \frac{b_1/\sigma_1^2}{1/\sigma_1^2} = \mathbf{b}_1$ . We are getting *no information* from the totally unreliable measurement  $x = b_2$ .

3 The key fact of **independence** is in the equation  $p(x, y) = p(x)p(y)$ . Then

$$\begin{aligned} \iint p(x, y) dx dy &= \iint p(x)p(y) dx dy = \int p(x) dx \int p(y) dy = (1)(1) = \mathbf{1}. \\ \iint (x + y) p(x, y) dx dy &= \iint x p(x)p(y) dx dy + \iint y p(x)p(y) dx dy \\ &= \int x p(x) dx \int p(y) dy + \int p(x) dx \int y p(y) dy \\ &= (m_x)(1) + (1)(m_y) = m_x + m_y. \end{aligned}$$

4 Continue Problem 3 to find variances  $\sigma_x^2$  and  $\sigma_y^2$  and to see covariance  $\sigma_{xy} = 0$  :

$$\begin{aligned} \iint (x - m_x)^2 p(x, y) dx dy &= \int (x - m_x)^2 p(x) dx \int p(y) dy = \boldsymbol{\sigma}_x^2 \\ \iint (x - m_x)(y - m_y) p(x, y) dx dy &= \int (x - m_x) p(x) dx \int (y - m_y) p(y) dy = (0)(0). \end{aligned}$$

5 We are inverting a 2 by 2 matrix using  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$  :

$$\begin{aligned} V^{-1} &= \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}^{-1} = \frac{1}{\sigma_1^2 \sigma_2^2 - \sigma_{12}^2} \begin{bmatrix} \sigma_2^2 & -\sigma_{12} \\ -\sigma_{12} & \sigma_1^2 \end{bmatrix} = & \rho = \frac{\sigma_{12}}{\sigma_1 \sigma_2} \\ \frac{1}{\sigma_1^2 \sigma_2^2 (1 - \rho^2)} \begin{bmatrix} \sigma_2^2 & -\sigma_{12} \\ -\sigma_{12} & \sigma_1^2 \end{bmatrix} &= \frac{1}{1 - \rho^2} \begin{bmatrix} 1/\sigma_1^2 & -\rho/\sigma_1 \sigma_2 \\ -\rho/\sigma_1 \sigma_2 & 1/\sigma_2^2 \end{bmatrix} \end{aligned}$$

6 The right hand side of  $\hat{x}_{k+1}$  shows the **gain factor**  $1/(k+1)$ :

$$\hat{x}_k + \frac{1}{k+1}(b_{k+1} - \hat{x}_k) = \frac{b_1 + \dots + b_k}{k} + \frac{1}{k+1} \left( b_{k+1} - \frac{b_1 + \dots + b_k}{k} \right) = \frac{b_1 + \dots + b_{k+1}}{k+1}$$

Check that each number  $b_1, b_2, \dots, b_k, b_{k+1}$  is correctly divided by  $k+1$ :

$$\frac{1}{k} - \frac{1}{k+1} \frac{1}{k} = \frac{1}{k} \left( \frac{k+1}{k+1} - \frac{1}{k} \right) = \frac{1}{k+1}.$$

7 We are considering the case when all the measurements  $b_1, b_2, \dots, b_{k+1}$  have the same variance  $\sigma^2$ . We know that the correct variance of their average is  $W_{k+1} = \sigma^2/(k+1)$ .

We want to see how this answer comes from equation (18) when we have the correct  $W_k = \sigma^2/k$  from the previous step, and we update to  $W_{k+1}$ :

$$(18) \text{ says that } W_{k+1}^{-1} = W_k^{-1} + A_{k+1}^T V_{k+1}^{-1} A_{k+1} = \frac{k}{\sigma^2} + [1] [1/\sigma^2] [1] = \frac{k}{\sigma^2} + \frac{1}{\sigma^2} = \frac{k+1}{\sigma^2}.$$

So  $W_{k+1} = \sigma^2/(k+1)$  is correct at the new step (and forever by induction).

8 The three equations have variances  $\sigma^2, s^2, \sigma^2$  and they have *zero covariances*. (This makes the step-by-step Kalman filter possible.) We can divide the equations by  $\sigma, s, \sigma$  to produce *unit variances* (which lead to ordinary unweighted least squares). We are given  $F = 1$ :

$$\begin{bmatrix} 1/\sigma & 0 \\ -1/s & 1/s \\ 0 & 1/\sigma \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} b_0/\sigma \\ 0 \\ b_1/\sigma \end{bmatrix} \text{ is our } A\mathbf{x} = \mathbf{b}.$$

The normal equation (now unweighted) is  $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ :

$$\begin{bmatrix} \frac{1}{\sigma^2} + \frac{1}{s^2} & -\frac{1}{s^2} \\ -\frac{1}{s^2} & \frac{1}{\sigma^2} + \frac{1}{s^2} \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} \frac{b_0}{\sigma^2} \\ \frac{b_1}{\sigma^2} \end{bmatrix}.$$

The determinant of this  $A^T A$  is  $\det = \frac{1}{\sigma^4} + \frac{2}{\sigma^2 s^2}$ . The solution is

$$\hat{x}_1 = \frac{1}{\det} \left( \frac{b_0}{\sigma^4} + \frac{b_0}{\sigma^2 s^2} + \frac{b_1}{\sigma^2 s^2} \right) \quad \hat{x}_2 = \frac{1}{\det} \left( \frac{b_0}{\sigma^2 s^2} + \frac{b_1}{\sigma^2 s^2} + \frac{b_1}{\sigma^4} \right).$$

9 With  $A = I$  and  $\mathbf{u}^T = \mathbf{v}^T = [1 \ 2 \ 3]$  we can use the direct formula for  $M^{-1}$ :

$$(I - \mathbf{u}\mathbf{v}^T)^{-1} = I + \frac{\mathbf{u}\mathbf{v}^T}{1 - \mathbf{v}^T\mathbf{u}} = I + \frac{1}{1 - 14} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 - \frac{1}{13} & \frac{2}{13} & \frac{3}{13} \\ \frac{2}{13} & 1 - \frac{4}{13} & \frac{6}{13} \\ \frac{3}{13} & \frac{6}{13} & 1 - \frac{9}{13} \end{bmatrix}. \text{ Multiply } \mathbf{b} = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix} \text{ to get } \mathbf{y} = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix} - \frac{16}{13} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 10 \\ -19 \\ 4 \end{bmatrix}.$$

Instead of this formula for  $(I - \mathbf{u}\mathbf{v}^T)^{-1}$ , try steps 1 and 2:

**Step 1** with  $A = I$  gives  $\mathbf{x} = \mathbf{b}$  and  $\mathbf{z} = \mathbf{u}$ .

**Step 2** gives  $\mathbf{y} = \mathbf{b} - \frac{\mathbf{v}^T\mathbf{u}}{13} \mathbf{u} = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix} - \frac{16}{13} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  as before.

10 We are asked to check that  $M\mathbf{y} = \mathbf{b}$  using the update formula. Start with

$$M\mathbf{y} = (A - \mathbf{u}\mathbf{v}^T) \left( \mathbf{x} + \frac{\mathbf{v}^T\mathbf{x}}{c} \mathbf{z} \right)$$

$$= A\mathbf{x} - \mathbf{u}(\mathbf{v}^T\mathbf{x}) + \frac{\mathbf{v}^T\mathbf{x}A\mathbf{z}}{c} - \frac{\mathbf{u}(\mathbf{v}^T\mathbf{z})(\mathbf{v}^T\mathbf{x})}{c}$$

Since  $A\mathbf{x} = \mathbf{b}$  we hope the other 3 terms combine to give zero when  $A\mathbf{z} = \mathbf{u}$

$$\mathbf{u}\mathbf{v}^T\mathbf{x} \left[ -1 + \frac{1}{c} - \frac{\mathbf{v}^T\mathbf{z}}{c} \right] = \frac{\mathbf{u}\mathbf{v}^T\mathbf{x}}{c} [-c + 1 - \mathbf{v}^T\mathbf{z}] = \mathbf{0} \text{ from the formula for } c$$

11 Multiply **columns times rows** to see that the new  $\mathbf{v}$  changes  $A^T A$  to

$$\begin{bmatrix} A^T & \mathbf{v} \end{bmatrix} \begin{bmatrix} A \\ \mathbf{v}^T \end{bmatrix} = A^T A + \mathbf{v}\mathbf{v}^T$$

So adding the new row to  $A$  (and of course the new column to  $A^T$ ) has increased  $A^T A$  by the rank one matrix  $\mathbf{v}\mathbf{v}^T$ .

The book is ending with matrix multiplication! We could allow changes of rank  $r$ :

When  $A$  changes to  $M = A - UW^{-1}V$ , its inverse changes to

$$M^{-1} = A^{-1} + A^{-1}U(W - VA^{-1}U)^{-1}VA^{-1}.$$

This change has rank  $r$  when  $W_{r \times r}$  and  $V_{r \times n}$  and  $U_{n \times r}$  all have rank  $r$ .