

## 18.700 - Fall 2006 - Practice Exam B

### Problem 1.

- (a) Such a basis exists only if  $\theta = 0$  or  $\theta = \pi$ .

Suppose there is a basis  $\mathcal{B} = \{v_1, v_2\}$  of  $\mathbb{R}^2$  such that  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is upper triangular.

Then  $R_{\theta}(v_1) = \lambda_1 v_1$ , where  $\lambda_1$  is  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})_{11}$ . As  $R_{\theta}$  is a rotation, the only possible values for  $\lambda_1$  are 1 and  $-1$ .

If  $\lambda_1 = 1$ , then  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta}) = I_2$  the identity matrix, and so  $R_{\theta}$  is the identity (and so  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is the identity for every  $\mathcal{B}$ ).

If  $\lambda_1 = -1$ , then  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta}) = -I_2$  and so  $\theta = \pi$  (and  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is  $-I_2$  for every  $\mathcal{B}$ ).

If  $\theta \neq 0, \pi$ , then  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is never upper triangular (and so never diagonal).

- (b) Yes, an example of such a basis is  $\mathcal{C} = \{v_1 = e_1 + ie_2, v_2 = e_1 - ie_2\}$  (the other bases look like  $\{\alpha_1 v_1, \alpha_2 v_2\}$  with  $0 \neq \alpha_1, \alpha_2 \in \mathbb{C}$ ).

In fact,  $R_{\theta}(e_1) = \cos \theta e_1 + \sin \theta e_2$  and  $R_{\theta}(e_2) = -\sin \theta e_1 + \cos \theta e_2$ .

So,  $R_{\theta}(e_1 + ie_2) = (\cos \theta - i \sin \theta)(e_1 + ie_2)$  and  $R_{\theta}(e_1 - ie_2) = (\cos \theta + i \sin \theta)(e_1 - ie_2)$ .

- (c) Such a basis exists only if  $\theta = 0$  or  $\theta = \pi$ .

If  $\theta = 0$ , then  $R_{\theta}$  is the identity and so  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta}) = I_3$  for every basis  $\mathcal{B}$ .

If  $\theta = \pi$ , then we can choose  $v_1$  to be a nonzero vector along the axis of rotation and  $v_2, v_3$  to be

a basis of the plane perpendicular to the axis. Then we obtain  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\pi}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$ ,

which is diagonal.

Assume now that  $\theta \neq 0, \pi$  and suppose there exists a basis  $\mathcal{B} = \{v_1, v_2, v_3\}$  of  $\mathbb{R}^3$  such that  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is upper triangular. Then  $R_{\theta}(v_1)$  is a multiple of  $v_1$ , and hence it must be a vector along the axis of rotation.

Because  $R_{\theta}$  is a rotation, it preserves the plane  $\Pi$  perpendicular to  $v_1$ , i.e.  $R_{\theta}(w) \in \Pi$  for every  $w \in \Pi$ . Moreover, this is the only plane<sup>1</sup> preserved by  $R_{\theta}$ , because  $\theta \neq 0, \pi$ .

As we are assuming that  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is upper triangular, then the plane spanned by  $v_1$  and  $v_2$  is also preserved. This implies that  $\Pi = \text{span}\{v_1, v_2\}$ , which is clearly a contradiction.

Hence, if  $\theta \neq 0, \pi$ , there is no basis  $\mathcal{B}$  such that  $M_{\mathcal{B}}^{\mathcal{B}}(R_{\theta})$  is upper triangular.

### Problem 2.

Define  $\mathcal{B} = \left\{ v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \right\}$  and

$\mathcal{C} = \left\{ w_1 = \begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix}, w_2 = \begin{pmatrix} 1 \\ 5 \\ 3 \end{pmatrix}, w_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ .

You can easily check that both  $\mathcal{B}$  and  $\mathcal{C}$  are bases of  $\mathbb{Q}^3$ .

A straightforward computation gives  $L(v_1) = L(e_1) = w_1$ ,  $L(v_2) = L(e_2) = w_2$  and  $L(v_3) = 0$ .

<sup>1</sup>I know that this requires some justification. Try to figure out why it is so.

Hence, with the choices of  $\mathcal{B}$  and  $\mathcal{C}$  made above,  $M_{\mathcal{C}}^{\mathcal{B}}(L) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ .

(The choices of  $\mathcal{B}$  and  $\mathcal{C}$  made above work, but they are not unique: you can find other bases that work as well.)

### Problem 3.

*Proof that  $\text{Ann}_V(\ker(L)) \supseteq \text{Im}(L^*)$ .*

If  $\varphi \in \text{Im}(L^*)$ , then there exists  $\psi \in W^*$  such that  $\varphi = L^*(\psi) = \psi \circ L$ . Hence, for every  $v \in \ker(L)$ , we have  $\varphi(v) = \psi \circ L(v) = 0 \implies \varphi \in \text{Ann}_V(\ker(L))$ .

*Proof that  $\text{Ann}_V(\ker(L)) \subseteq \text{Im}(L^*)$ .*

If  $\varphi \in \text{Ann}_V(\ker(L))$ , then  $\varphi(v) = 0 \forall v \in \ker(L)$ .

We want to find  $\psi \in W^*$  such that  $\varphi = L^*(\psi) = \psi \circ L$ .

Let  $U \subseteq W$  be a complement of  $\text{Im}(L)$ , i.e.  $W = U \oplus \text{Im}(L)$ . To define  $\psi(w)$  for every  $w \in W$ , rewrite  $w = u + L(v)$ , with  $u \in U$  and  $v \in V$  (warning: here the choice of  $v \in V$  is not unique, which means that later we have to check that  $\psi$  is well-defined), and define  $\psi(w) = \psi(u + L(v)) = \varphi(v)$ . Suppose now that  $w = u + L(v')$ , with  $v' \in V$ . As  $L(v') = w - u = L(v)$ , we have  $L(v' - v) = 0$  and so  $v' - v = k \in \ker(L)$ . Hence,  $\psi(w) = \varphi(v) = \varphi(v' - k) = \varphi(v') - \varphi(k) = \varphi(v')$  and so  $\psi$  is well-defined (i.e. independent of the choice of  $v$ ).

Clearly,  $L^*(\psi)(v) = \psi \circ L(v) = \varphi(v)$  for every  $v \in V$ .

*Proof that  $\text{Ann}_W(\text{Im}(L)) = \ker(L^*)$ .*

$\psi \in \ker(L^*) \iff L^*(\psi) = \psi \circ L = 0 \iff \psi \circ L(v) = 0 \forall v \in V \iff \psi(w) = 0 \forall w \in \text{Im}(L) \iff \psi \in \text{Ann}_W(\text{Im}(L))$ .

### Problem 4.

*Proof that  $\mathcal{B}$  is a set of linear independent vectors on  $\mathbb{R}$ .*

Let  $a_1 \text{ev}_{x_1} + \dots + a_n \text{ev}_{x_n} = 0$  (this is an equality in  $V^*$ ) for  $a_1, \dots, a_n \in \mathbb{R}$  and  $x_1, \dots, x_n \in \mathbb{R}$  (notice that  $x_1, \dots, x_n$  are distinct).

If we evaluate the equality above at the vector  $(t - x_2)(t - x_3) \dots (t - x_n)$ , we obtain  $a_1 = 0$ . Evaluating at the vector  $(t - x_1)(t - x_3) \dots (t - x_n)$ , we obtain  $a_2 = 0$ . Similarly, we obtain that  $a_1 = a_2 = \dots = a_n = 0$ .

*Counterexample:  $\mathcal{B}$  is **not** a set of generators.*

Consider the functional  $\varphi : V = \mathbb{R}[t] \longrightarrow \mathbb{R}$  defined as  $\varphi(t) = 1$  and  $\varphi(t^d) = 0$  for  $d \neq 1$ .

We want to show that  $\varphi \notin \text{span}(\mathcal{B})$ .

For every  $\lambda \in \mathbb{R}$ , define the homomorphism  $L_\lambda : V \longrightarrow V$  as  $L_\lambda(p(t)) = p(\lambda t)$ .

The dual homomorphism  $L_\lambda^* : V^* \longrightarrow V^*$  has the property that  $L^*(\text{ev}_x) = \text{ev}_x \circ L_\lambda = \text{ev}_{\lambda x}$  for every  $x \in \mathbb{R}$ . Moreover,  $L^*(\varphi) = \varphi \circ L = \lambda \varphi$ .

By contradiction, suppose that  $\varphi = a_1 \text{ev}_{x_1} + \dots + a_n \text{ev}_{x_n}$  for some  $a_1, \dots, a_n \in \mathbb{R}$  and  $x_1, \dots, x_n \in \mathbb{R}$ . We can assume that  $a_1, \dots, a_n \neq 0$  and that the  $x_i$ 's are all distinct.

Then  $\lambda \varphi = L^*(\varphi) = L^*(a_1 \text{ev}_{x_1} + \dots + a_n \text{ev}_{x_n}) = a_1 \text{ev}_{\lambda x_1} + \dots + a_n \text{ev}_{\lambda x_n} \implies \lambda a_1 \text{ev}_{x_1} + \dots + \lambda a_n \text{ev}_{x_n} = a_1 \text{ev}_{\lambda x_1} + \dots + a_n \text{ev}_{\lambda x_n}$ .

If we choose  $0 \neq \lambda \in \mathbb{R}$  such that the set  $\{x_1, \dots, x_n\}$  is different from the set  $\{\lambda x_1, \dots, \lambda x_n\}$ , then the equality gives a contradiction, because  $\mathcal{B}$  is a set of linearly independent vectors (as shown above).

*The case of  $V = (\mathbb{Z}/p)[t]$ .*

The same proof as for  $\mathbb{R}$  shows that  $\mathcal{B}$  is a (finite) set of linearly independent vectors. Clearly,  $\mathcal{B}$  cannot be a set of generators for  $V^*$ , because it is a finite set, while  $V^*$  has infinite dimension.

*(Notice that the conclusion is the same as for  $\mathbb{R}$ , but the proof that  $\mathcal{B}$  is not a set of generators is different. In the case of  $\mathbb{Z}/p$ , we are exploiting the fact that  $\mathcal{B}$  is a finite set, which depends on the fact that  $\mathbb{Z}/p$  is a finite field. In the other case, we are exploiting the fact that  $\mathbb{R}$  is an infinite field, exactly in the part of the proof when we say: given a finite set  $\{x_1, \dots, x_n\} \subset \mathbb{R}$ , we can find  $0 \neq \lambda \in \mathbb{R}$  such that  $\{x_1, \dots, x_n\} \neq \{\lambda x_1, \dots, \lambda x_n\}$ .*

*The difference in the proofs depends essentially on the finiteness/infiniteness of the field.)*