

18.700 - Fall 2006 - Solutions of Practice Exam A

Problem 1.

$L(e_i) \in \mathbb{C}^3$ is the i -th column of L . Call it v_i .

Notice that $2v_3 = v_2 - v_1$ and $v_4 = v_2 - v_3 = v_2 - \frac{v_2 - v_1}{2} = \frac{v_1 + v_2}{2}$. Hence, $\text{Im}(L)$ is spanned by v_1, v_2 . Moreover, $v_1, v_2 \neq 0$ and they are not proportional. This shows that $\mathcal{B} = \{v_1, v_2\} \subset \mathbb{C}^3$ is a set of linearly independent vectors and so a basis of $\text{Im}(L)$.

As $\dim \ker(L) + \dim \text{Im}(L) = \dim \mathbb{C}^4 = 4$, then we expect a bidimensional $\ker(L)$.

As $2v_3 = v_2 - v_1$ and $v_4 = v_2 - v_3$, we have $L \begin{pmatrix} 1 \\ -1 \\ 2 \\ 0 \end{pmatrix} = 0$ and $L \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} = 0$.

$\mathcal{C} = \left\{ \begin{pmatrix} 1 \\ -1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \end{pmatrix} \right\} \subset \mathbb{C}^4$ is a basis of $\ker(L)$, because it is a maximal set of linearly independent vectors (as they are nonzero and nonproportional).

The system has solution if and only if $B = \begin{pmatrix} 2 \\ 0 \\ c \end{pmatrix}$ belongs to $\text{Im}(L) = \text{span}\{v_1, v_2\}$. Looking at the second entry of the vectors, we conclude that $B \in \text{Im}(L)$ if and only if B is a multiple of v_2 , i.e. if and only if $c = 6$.

In this case, $L(e_2) = \begin{pmatrix} 2 \\ 0 \\ 6 \end{pmatrix}$, so e_2 is a particular solution of the system and the set of solutions is

$$e_2 + \ker(L) = \{e_2 + v \in \mathbb{C}^4 \mid v \in \ker(L)\} = \left\{ \begin{pmatrix} a \\ 1 - a + b \\ 2a - b \\ -b \end{pmatrix} \in \mathbb{C}^4 \mid \forall a, b \in \mathbb{C} \right\}.$$

Problem 2.

Let L be injective and define U to be a subspace of W which is complementary to $\text{Im}(L)$, i.e. $U \subseteq W$ and $W = \text{Im}(L) \oplus U$. Define $F : U \rightarrow W$ to be the inclusion homomorphism.

Let's show that, with the choices made above, \tilde{L} is an isomorphism.

To show that \tilde{L} is injective, let $(v, u) \in V \times U$ be a vector such that $\tilde{L}(v, u) = 0$. We want to prove that $(v, u) = (0, 0)$. We have $\tilde{L}(v, u) = L(v) + F(u) = 0 \implies L(v) = -u$. But $L(v) \in \text{Im}(L)$ and $-u \in U$. As $\text{Im}(L) \cap U = \{0\}$, we get $L(v) = 0$ and $u = 0$. As L is injective, $L(v) = 0 \implies v = 0$. To show that \tilde{L} is surjective, let $w \in W$. As $W = U \oplus \text{Im}(L)$, we can rewrite $w = u + L(v)$ for some $v \in V$. Hence, $\tilde{L}(u, v) = F(u) + L(v) = u + L(v) = w$.

Similarly, suppose that L is surjective and define $Z = \ker(L)$. Let $Y \subset V$ be a complement subspace of Z , i.e. $V = Y \oplus Z$. Define $G : V = Y \oplus Z \rightarrow Z$ as $G(y + z) = z$, where $y \in Y$ and $z \in Z$.

Let's show that, with the choice made above, L' is an isomorphism.

To show that L' is injective, let $v \in \ker(L')$ and rewrite $v = y + z$ with $y \in Y$ and $z \in Z = \ker(L)$. As $v \in \ker(L')$, we have $(0, 0) = L'(v) = L'(y + z) = (L(y + z), G(y + z)) = (L(y), z)$, which implies

that $L(y) = 0$ and $z = 0$. But $L(y) = 0 \implies y = 0$, because $Y \cap \ker(L) = \{0\}$. Hence, $v = 0$. To show that L' is surjective, pick $(w, z) \in W \times Z$. As L is surjective, $w = L(v)$ for some $v \in V$. If we write $v = y + z$, with $y \in Y$ and $x \in Z$, we find that $w = L(v) = L(y + x) = L(y) + L(x) = L(y)$. As $Z = \ker(L)$, we have $G(z) = z$ and $z \in Z \subset V$. Hence, $L'(y + z) = (L(y + z), G(y + z)) = (L(v), G(z)) = (w, z)$.

Problem 3.

$AB = BA$ if and only if $(AB)_{ij} = (BA)_{ij}$ for all $i, j = 1, \dots, n$.

$$(AB)_{ij} = \sum_{k=1}^n A_{ik}B_{kj} \text{ and } (BA)_{ij} = \sum_{h=1}^n B_{ih}A_{hj}.$$

As A is diagonal, we have $A_{ij} = 0$ if $i \neq j$.

So $(AB)_{ij} = A_{ii}B_{ij} = \lambda_i B_{ij}$, whereas $(BA)_{ij} = B_{ij}A_{jj} = \lambda_j B_{ij}$.

As $\lambda_i B_{ij} = \lambda_j B_{ij}$ for all $i, j = 1, \dots, n$ but $\lambda_i \neq \lambda_j$ for $i \neq j$, we obtain that $B_{ij} = 0$ for $i \neq j$, which is the same as saying that B is diagonal.

Notice that, conversely, if B is diagonal, then $AB = BA$.

If the λ 's are not all distinct, the previous conclusion is false. As an example, let $A = I_n$ be the identity matrix $n \times n$. Then $AB = BA$ for all matrices B , so also for nondiagonal B 's.

Problem 4.

As V has finite dimension, then $\text{ev} : V \longrightarrow V^{**}$ is a canonical isomorphism and we can use it to identify V with V^{**} .

We look for $\mathcal{B} = \{v_1, v_2, v_3\}$, so that $\text{ev}_0 = v_1^*$, $\text{ev}_1 = v_2^*$ and $\text{ev}_i = v_3^*$. Hence, v_1 is a polynomial in $\mathbb{C}[t]_{\leq 2}$ such that $\text{ev}_0(v_1) = 1$, $\text{ev}_1(v_1) = 0$ and $\text{ev}_i(v_1) = 0$.

Thus, $v_1 = -i(t-1)(t-i) = 1 + (i-1)t - it^2$,

v_2 is a polynomial in $\mathbb{C}[t]_{\leq 2}$ such that $\text{ev}_0(v_2) = 0$, $\text{ev}_1(v_2) = 1$ and $\text{ev}_i(v_2) = 0$.

Thus, $v_2 = \frac{1+i}{2}t(t-i) = \frac{1+i}{2}t^2 + \frac{1-i}{2}t$.

v_3 is a polynomial in $\mathbb{C}[t]_{\leq 2}$ such that $\text{ev}_0(v_3) = 0$, $\text{ev}_1(v_3) = 0$ and $\text{ev}_i(v_3) = 1$.

Thus, $v_3 = -\frac{1+i}{2}t(t-1) = -\frac{1+i}{2}t^2 + \frac{1+i}{2}t$,

Hence, $\mathcal{B} = \left\{ 1 + (i-1)t - it^2, \frac{1+i}{2}t^2 + \frac{1-i}{2}t, -\frac{1+i}{2}t^2 + \frac{1+i}{2}t \right\}$.

To simplify the computation of $M_{\mathcal{B}^*}^{\mathcal{B}}(L^*)$, we write it as $M_{\mathcal{B}^*}^{\mathcal{B}}(L^*) = M_{\mathcal{B}^*}^{\mathcal{C}} \cdot M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*)$, where $\mathcal{C} = \{w_0 = 1, w_1 = t, w_2 = t^2\}$ and $\mathcal{C}^* = \{w_0^*, w_1^*, w_2^*\}$ is the dual basis.

We already know that $w_i^*(a_0 + a_1t + a_2t^2) = a_i$.

Moreover, $M_{\mathcal{B}^*}^{\mathcal{C}}$ is the transpose of $M_{\mathcal{C}}^{\mathcal{B}}$.

$$\text{Looking at } v_1, v_2, v_3, \text{ we immediately see that } M_{\mathcal{C}}^{\mathcal{B}} = \frac{1}{2} \begin{pmatrix} 2 & 0 & 0 \\ 2i-2 & 1-i & 1+i \\ -2i & 1+i & -1-i \end{pmatrix},$$

$$\text{so that } M_{\mathcal{B}^*}^{\mathcal{C}} = \frac{1}{2} \begin{pmatrix} 2 & 2i-2 & -2i \\ 0 & 1-i & 1+i \\ 0 & 1+i & -1-i \end{pmatrix}.$$

Notice that $L^*(\text{ev}_0)(a_0 + a_1t + a_2t^2) = \text{ev}_0 \circ L(a_0 + a_1t + a_2t^2) = \text{ev}_0(a_1t + 2a_2t^2) = 0$.

Instead, $L^*(\text{ev}_1)(a_0 + a_1t + a_2t^2) = \text{ev}_1 \circ L(a_0 + a_1t + a_2t^2) = \text{ev}_1(a_1t + 2a_2t^2) = a_1$, so that $L^*(\text{ev}_1) = w_1^*$.

Similarly, $L^*(\text{ev}_i)(a_0 + a_1t + a_2t^2) = \text{ev}_i \circ L(a_0 + a_1t + a_2t^2) = \text{ev}_i(a_1t + 2a_2t^2) = -2a_2 + a_1i$, so

that $L^*(ev_i) = iw_1^* - 2w_2^*$.

For $M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*)$, its first column is given by $M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*)(e_1) = M_{\mathcal{C}^*} \circ L^* \circ M^{\mathcal{B}^*}(e_1) = M_{\mathcal{C}^*} \circ L(ev_0) = 0$.

The second column is given by $M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*)(e_2) = M_{\mathcal{C}^*} \circ L(ev_1) = M_{\mathcal{C}^*}(w_1^*) = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$.

The third column is given by $M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*)(e_3) = M_{\mathcal{C}^*} \circ L(ev_i) = M_{\mathcal{C}^*}(iw_1^* - 2w_2^*) = \begin{pmatrix} 0 \\ i \\ -2 \end{pmatrix}$.

$$\text{Hence, } M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & i \\ 0 & 0 & -2 \end{pmatrix}.$$

$$\begin{aligned} \text{Finally, } M_{\mathcal{B}^*}^{\mathcal{B}^*} &= M_{\mathcal{B}^*}^{\mathcal{C}^*} \cdot M_{\mathcal{C}^*}^{\mathcal{B}^*}(L^*) = \frac{1}{2} \begin{pmatrix} 2 & 2i-2 & -2i \\ 0 & 1-i & 1+i \\ 0 & 1+i & 1-i \end{pmatrix} \cdot \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & i \\ 0 & 0 & -2 \end{pmatrix} = \\ &= \frac{1}{2} \begin{pmatrix} 0 & 2i-2 & -2+2i \\ 0 & 1-i & -1-i \\ 0 & 1+i & 1+3i \end{pmatrix}. \end{aligned}$$