

## 18.700 - Fall 2006 - Solutions of Practice Exam C

### Problem 1.

Call  $M^{ij}$  the matrix whose unique nonzero entry is a 1, placed at the  $i$ -th row  $j$ -th column. Clearly,  $M^{ij}$  has rank 1 and clearly the set  $\{M^{ij} \in \mathcal{M}_{n \times n}(\mathbb{F}) \mid i, j = 1, \dots, n\}$  generate  $\mathcal{M}_{n \times n}(\mathbb{F})$  (really, they are even a basis).

For  $k > 1$ , we will show that we can generate  $R_1$  using matrices in  $R_k$ . As  $R_1$  is a set of generators, it will follow that  $R_k$  is a set of generators as well.

For notational simplicity, let's use the following convention: consider the index for the row and for the column as a number in  $\mathbb{Z}/n$ , in such a way that the  $\bar{0}$ -th column is the  $n$ -th column, the  $\overline{n+1}$ -st column is the first column and so on.

Suppose I want to generate  $M^{ij}$  with matrices in  $R_k$ .

Define the matrix  $A$  as  $A_{rc} = 1$  for  $(r, c) = (i-1, j), (i, j), (i, j+1), (i+1, j+2), (i+2, j+3), \dots, (i+k-1, j+k)$  and  $A_{rc} = 0$  otherwise. Define also  $B$  as  $B_{rc} = 1$  for  $(r, c) = (i-1, j), (i, j+1), (i+1, j+2), \dots, (i+k-1, j+k)$  and  $B_{rc} = 0$  otherwise.

Both  $A$  and  $B$  have rank  $k$  and  $A - B = M^{ij}$ .

### Problem 2.

Call  $v_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} -2 \\ 5 \\ 0 \end{pmatrix}$ ,  $v_3 = \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix}$ ,  $w_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ ,  $w_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

$$L(v_1) = \begin{pmatrix} 1 \\ -2 \end{pmatrix} = -3w_1 + 4w_2, \quad L(v_2) = \begin{pmatrix} -14 \\ -26 \end{pmatrix} = -12w_1 - 2w_2 \quad \text{and}$$

$$L(v_3) = \begin{pmatrix} -4 \\ -6 \end{pmatrix} = -2w_1 - 2w_2.$$

$$\text{Hence, } M_{\mathcal{C}}^{\mathcal{B}}(L) = \begin{pmatrix} -3 & -12 & -2 \\ 4 & -2 & -2 \end{pmatrix}$$

### Problem 3.

$\mathcal{L}$  is a vector subspace, because: if  $S_1, S_2 \in \mathcal{L}$ , then  $S_1T = S_2T = 0$  and so  $(S_1 + S_2)T = S_1T + S_2T = 0$ . Similarly,  $(\lambda S_1)T = \lambda(S_1T) = 0$  for  $\lambda \in \mathbb{F}$  and  $S_1 \in \mathcal{L}$ .

The proof for  $\mathcal{R}$  is analogous.

$$\text{Hence, } \text{span}(\mathcal{L}) = \mathcal{L}, \text{span}(\mathcal{R}) = \mathcal{R}, \text{span}(\mathcal{L} \cap \mathcal{R}) = \mathcal{L} \cap \mathcal{R} \text{ and } \text{span}(\mathcal{L} \cup \mathcal{R}) = \mathcal{L} + \mathcal{R}.$$

Let  $k = \dim \text{Im}(T)$ , so that  $\dim \ker(T) = n - k$ .

Let  $\{v_1, \dots, v_k\}$  be a basis of  $\text{Im}(T)$  and  $\{w_1, \dots, w_{n-k}\}$  a basis of  $\ker(T)$ . Complete them to bases  $\mathcal{B} = \{v_1, \dots, v_n\}$  and  $\mathcal{C} = \{w_1, \dots, w_n\}$  of  $V$ .

We can thus define an isomorphism  $\Phi : \text{Hom}(V, V) \rightarrow \mathcal{M}_{n \times n}(\mathbb{F})$  given by  $\Phi(S) = M_{\mathcal{C}}^{\mathcal{B}}(S)$ .

Through this isomorphism, it is clear that  $\Phi(\mathcal{L})$  correspond to the subspace of matrices whose first  $k$  columns are zero. Thus,  $\dim \mathcal{L} = n(n - k)$ .

Similarly,  $\Phi(\mathcal{R})$  corresponds to the subspace of matrices whose last  $k$  rows are zero. Hence,  $\dim \mathcal{R} = n(n - k)$ .

$\Phi(\mathcal{R} \cap \mathcal{L})$  corresponds to matrices whose first  $k$  columns and last  $k$  rows are zero, so  $\dim(\mathcal{L} \cap \mathcal{R}) =$

$(n - k)(n - k)$ .

Finally,  $\Phi(\mathcal{L} + \mathcal{R})$  corresponds to matrices whose entries  $(i, j)$  vanish if  $i > n - k$  and  $j \leq k$ . Hence, this is the whole vector space if and only if  $k = 0$ , that is if and only if  $T = 0$ .

**Problem 4.**

$\ker(j^*)$  is the subspace of functionals  $\varphi : \mathbb{C}^3 \rightarrow \mathbb{C}$  such that  $\varphi(w) = 0$  for every  $w \in W$ .

We can write  $\varphi = (a \ b \ c)$ , so that  $\varphi \in \ker(j^*)$  if and only if 
$$\begin{cases} a + c = 0 \\ a + b - 2c = 0 \end{cases} .$$

This implies  $\ker(j^*) = \text{span}\{(1 \ 1 \ -1)\}$ .

(Call  $v_3$  the third vector of  $\mathcal{B}$ , that is  $v_3 = e_1$ .)

By definition,  $v_1^* = (v_1^*(e_1) \ v_1^*(e_2) \ v_1^*(e_3))$ ,  $v_2^* = (v_2^*(e_1) \ v_2^*(e_2) \ v_2^*(e_3))$ ,  $v_3^* = (v_3^*(e_1) \ v_3^*(e_2) \ v_3^*(e_3))$ .  
As  $e_1 = v_3$ ,  $e_2 = -2v_1 + v_2 + v_3$  and  $e_3 = v_1 - v_3$ , we obtain  $v_1^* = (0 \ -2 \ 1)$ ,  $v_2^* = (0 \ 1 \ 0)$  and  $v_3^* = (1 \ 1 \ -1)$ .