

## HYPERBOLIC PLANES AND WITT'S CANCELLATION THEOREM

Yelena Yasinnik <yelena@mit.edu>

Notes for Lecture of March 4, 2004

In this lecture, we will be introduce hyperbolic planes and prove a couple of results about them and their applications. Throughout these notes, it will be assumed that we are working over a field  $F$  with  $\text{char} \neq 2$ .

Recall from the lecture on bilinear forms, that a *bilinear form*  $B$  on  $V$  is a function  $B : V \times V \mapsto F$  which becomes linear in one variable if the other variable is fixed. Any bilinear form has a corresponding representational matrix  $\hat{B}$  relative to a basis  $\{v_i\}$  of  $V$ . The matrix consists of entries  $b_{ij} = B(v_i, v_j)$  for all  $i, j$ . Also,  $B$  is called

- *symmetric* if  $B(v, w) = B(w, v)$  for all  $v, w \in V$ ;
- *alternate* if  $B(v, v) = 0$  for all  $v \in V$ ;
- *reflexive* if  $B(v, w) = 0 \implies B(w, v) = 0$ . (Proposition 2.7 in the text also shows that  $B$  is reflexive iff it is either symmetric or alternate).

### HYPERBOLIC PLANES: CASE OF AN ALTERNATE BILINEAR FORM ON $V$

**Definition.** Given a vector space  $V$  with an alternate bilinear form  $B$  on  $V$ , we call a pair of vectors  $u, v \in V$  a *hyperbolic pair* if  $B(u, v) = 1$ . Consequently, the subspace  $H \in V$  spanned by  $(u, v)$  will be called a *hyperbolic plane*.

We can construct a hyperbolic plane in  $V$  by choosing a hyperbolic pair  $(u, v)$  in the following way: for some linearly independent  $\hat{u}, \hat{v} \in V$  such that  $B(\hat{u}, \hat{v}) = b \neq 0$ ,

set  $u = b^{-1}\hat{u}$ , and  $v = \hat{v}$ . Notice that  $B(u, u) = 0$  and  $B(v, v) = 0$  as well as  $B(u, v) = B(b^{-1}\hat{u}, \hat{v}) = b^{-1}B(\hat{u}, \hat{v}) = b^{-1}b = 1$ . Thus,  $(u, v)$  is a hyperbolic pair in  $V$  and the space  $H = \langle u, v \rangle$  is a hyperbolic plane. Moreover, as the following theorem shows,  $V$  can be represented using a set of mutually orthogonal hyperbolic planes.

**Theorem.** *If  $B$  is an alternating form on  $V$ , then*

$$V = W_1 \oplus W_2 \oplus \cdots \oplus W_r \oplus \text{rad}V,$$

*a direct sum of mutually orthogonal subspaces with each  $W_i$  a hyperbolic plane.*

**Proof.** The proof will proceed by induction on dimension  $n$  of the space  $V$ .

If  $B=0$ , then  $\text{rad}V = V$  and we are done.

Suppose the result is true for spaces of dimension less than or equal to  $n$ . Consider a space  $V$  with dimension  $n+1$  and the same bilinear form  $B$ . Choose a hyperbolic pair  $(u, v)$  in  $V$  as described above. Let the hyperbolic plane spanned by  $u, v$  be  $W_1$ . The restriction matrix of  $B$  to subspace  $W_1$ , relative to the basis  $(u, v)$ , is  $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ . Since the determinant of this matrix is 1, then  $\text{discr}B|_{W_1} \neq 0$ , and thus  $W_1$  is a nondegenerate subspace of  $V$  relative to  $B$ . Proposition 2.9 of the text states that for a reflexive form  $B$  on space  $V$  and nondegenerate subspace  $W$ ,  $V$  is a direct sum of  $W$  and its complement. This proposition applies to  $B$  since alternate bilinear forms are also reflexive, and we get that  $V = W_1 \oplus W_1^\perp$ . Since  $\dim(W_1^\perp) = \dim(V) - \dim(W_1) = n - 1$ , the subspace  $W_1^\perp$  can be represented as a direct sum of mutually orthogonal hyperbolic planes and  $\text{rad}(W_1^\perp)$ .

Notice that, conveniently,  $\text{rad}V = V^\perp = (W_1 \oplus W_1^\perp)^\perp = W_1^\perp \cap W_1^{\perp\perp} = \text{rad}(W_1^\perp)$ . Therefore, we now have a representation of  $n+1$ -dimensional space  $V$  as a direct sum

of mutually orthogonal hyperbolic planes and  $\text{rad}V$ . By induction, the statement of the theorem is true.

### HYPERBOLIC PLANES: CASE OF A SYMMETRIC BILINEAR FORM ON $V$

Of course we can extend the definition of a hyperbolic plane to vector spaces with bilinear forms that are not alternate. In particular, let us consider a vector space  $V$  with a bilinear form  $B$  that is symmetric. Since having an alternate bilinear form guaranteed that for  $u, v \in V$ , we have  $B(u, u) = B(v, v) = 0$ , now we will have to impose this condition on basis vectors of a hyperbolic plane in a different way.

**Definition.** Given a vector space  $V$  with a symmetric bilinear form  $B$ , define *quadratic form*  $Q$  corresponding to  $B$  as a function  $Q : V \mapsto F$  with  $Q(v) = B(v, v)$ .

It is easy to see that for all  $a \in F$  and  $v \in V$ , we get  $Q(av) = a^2Q(v)$  - hence the name of the form. Also, one should keep in mind that even though we define  $Q$  in as a quadratic form associated with  $B$ , the bilinear form  $B$  is completely determined by  $Q$ :  $B(u, v) = \frac{1}{2}[Q(u + v) - Q(u) - Q(v)]$ . (This expression is derived by evaluating  $Q(u + v)$  using the above definition and then solving the resulting equation for  $B(u, v)$ .) Now, we are ready to give the definition of a hyperbolic plane in a space with a symmetric form.

**Definition.** Given  $B$  a nondegenerate symmetric bilinear form on  $V$ , for  $u, v \in V$ , we call  $(u, v)$  a *hyperbolic pair* if  $B(u, v) = 1$ , and  $Q(u) = 0, Q(v) = 0$ . The subspace of  $V$  spanned by a hyperbolic pair is a *hyperbolic plane*.

A space with such bilinear form, i.e. with a nondegenerate symmetric bilinear form, is called a *quadratic space*. This is the terminology we will use throughout the rest of the notes. (Note: we need the bilinear form to be nondegenerate in order to

make sure that  $B(u, v) = 1$ . Allowing the bilinear form to have zero determinant of the corresponding matrix  $\hat{B}$ , would also allow  $\hat{B}$  to have all diagonal entries as 0. In such case,  $B(v_i, v_i) = Q(v_i) = 0$  for all  $i$ , and hence  $B(u, v) = 0$  for all  $u, v \in V$ . We can also see that nondegeneracy of the form restricted to the hyperbolic plane  $\langle u, v \rangle = H$  is implied from  $\hat{B}_H = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ , whose determinant is 1.)

### WITT'S CANCELLATION THEOREM

**Definition.** If  $V$  is a vector space with quadratic form  $Q$ , then vector  $v \in V$ ,  $v \neq 0$  is called

- *isotropic* if  $Q(v) = 0$ ;
- *anisotropic* if  $Q(v) \neq 0$ . (Note:  $v = 0$  is also taken to be anisotropic.)

Space  $V$  is called *isotropic* if it contains at least one isotropic vector. If all vectors in  $V$  are isotropic, we will say that  $V$  is *totally isotropic*.

**Definition.** Given  $V$ , a quadratic space with bilinear form  $B$ , an *isometry* of  $V$  is defined to be any linear transformation  $\sigma : V \mapsto V$  such that for all  $u, v \in V$ ,  $B(\sigma u, \sigma v) = B(u, v)$ .

**Theorem.** (*Witt's Cancellation Theorem*). Suppose that  $U_1$  and  $U_2$  are nondegenerate subspaces of a quadratic space  $V$  and that  $\sigma : U_1 \mapsto U_2$  is an isometry. Then  $U_1^\perp$  and  $U_2^\perp$  are also isometric.

**Proof.** The proof will proceed by induction on the dimension of  $U_1$ .

For base case, suppose that  $U_1 = \langle u_1 \rangle, U_2 = \langle u_2 \rangle$ , that is  $\dim U_1 = 1$ . Since  $U_1$  and  $U_2$  are nondegenerate subspaces,  $Q(u_1)$  and  $Q(u_2)$  are nonzero. Without loss of generality, assume that  $\sigma u_1 = \sigma u_2$ . Then,  $Q(u_1) = Q(u_2)$ . It is not difficult to verify that the equality  $Q(u_1 \pm u_2) = 2Q(u_1) \pm 2B(u_1, u_2)$  implies that only one of

$Q(u_1 + u_2)$  and  $Q(u_1 - u_2)$  can be 0. Thus, at least one of them, say  $Q(u_1 - u_2)$  is nonzero. (The case that is worked out in the book is  $Q(u_1 + u_2) \neq 0$ , and it is very similar.)

Since  $Q(u_1) = Q(u_2)$ , and  $B(u_1 + u_2, u_1 - u_2) = Q(u_1) - Q(u_2) = 0$ , then  $(u_1 - u_2) \perp (u_1 + u_2)$ . Hence,  $\sigma_{u_1 - u_2}(u_1 + u_2) = (u_1 + u_2)$  (\*). Notice that we can represent  $u_1$  the following way:  $u_1 = \frac{1}{2}(u_1 + u_2) + \frac{1}{2}(u_1 - u_2)$ . Using equation (\*) and this representation of  $u_1$ , we get that  $\sigma_{u_1 - u_2}(u_1) = \sigma_{u_1 - u_2}([\frac{1}{2}(u_1 + u_2)] + [\frac{1}{2}(u_1 - u_2)]) = [\frac{1}{2}(u_1 + u_2)] - [\frac{1}{2}(u_1 - u_2)] = u_2$ . And in general,  $\sigma_{u_1 - u_2}(\langle u_1 \rangle) = \langle u_2 \rangle$ . Since  $\sigma$  is an isometry, then by definition,  $B(\sigma(\langle u_1 \rangle), \sigma(\langle u_1 \rangle^\perp)) = B(\langle u_2 \rangle, \langle u_2 \rangle^\perp) = 0$ , i.e.  $\sigma(\langle u_1 \rangle^\perp) = (\sigma(\langle u_1 \rangle))^\perp = \langle u_2 \rangle^\perp$ , and thus  $U_1^\perp$  and  $U_2^\perp$  are isometric for our base case of  $\dim U_1 = 1$ .

Assume that the theorem is true for  $U_1$  of dimension less than or equal to  $n$ . Consider a nondegenerate subspace  $U_1$  of  $V$ ,  $\dim U_1 = n + 1$ . Pick  $u \in U_1$ , an anisotropic vector. Let the subspace of  $\langle u^\perp \rangle$  in  $U_1$  be  $W_1$ . Since  $\langle u \rangle$  is nondegenerate, then  $U_1 = \langle u \rangle \oplus W_1$ . Let  $\sigma u_1 = u_2$ , and  $\sigma W_1 = W_2$ , then since  $\sigma$  is an isometry,  $u_2$  is anisotropic and hence  $\langle u_2 \rangle$  is nondegenerate and  $U_2 = \langle u_2 \rangle \oplus W_2$ . Thus we can represent  $V$  in two ways:  $V = (\langle u_1 \rangle \oplus W_1) \oplus U_1^\perp = \langle u_2 \rangle \oplus (W_2 \oplus U_2^\perp)$  and  $V = (\langle u_2 \rangle \oplus W_2) \oplus U_2^\perp = \langle u_2 \rangle \oplus (W_2 \oplus U_2^\perp)$ . Using the one dimensional case, we know that there exists some isometry, call it  $\eta$ , such that  $\eta : W_1 \oplus U_1^\perp \mapsto W_2 \oplus U_2^\perp$ , that is  $\eta W_1 \oplus \eta U_1^\perp = W_2 \oplus U_2^\perp$ . Since  $W_2 = \sigma W_1$ , then  $\eta \sigma^{-1} : W_2 \mapsto \eta W_1$  is an isometry. Notice that  $\dim W_2 < \dim U_1$  and so the induction assumption implies that since  $W_2$  and  $\eta W_1$  are nondegenerate subspaces of  $W_2 \oplus U_2^\perp$ , and since there exists an isometry, namely  $\eta \sigma^{-1}$ , that maps from one subspace to the other, then their orthogonal complements,  $U_2^\perp$  and  $\eta U_1^\perp$  respectively, must be isometric. It is easy to see that an isometry mapping  $U_2^\perp$  to  $\eta U_1^\perp$  can be multiplied by  $\eta^{-1}$  to get an

isometry from  $U_1^\perp$  to  $U_2^\perp$ . This completes the induction step and the proof of Witt's Cancellation Theorem.

**Definition.** The dimension  $m$  of a maximal totally isotropic subspace of a quadratic space  $V$  is called the *Witt index of  $V$* . (Note: Witt index is well defined since the Corollary of Witt's Extension Theorem presented on page 41 of the text states that any two maximal totally isotropic subspaces of  $V$  have the same dimension, and moreover every totally isotropic subspace is contained in one of maximal dimension.)

**Definition.** A subspace  $H$  of a quadratic space  $V$  is called a *hyperbolic subspace* if  $H$  is a direct sum of mutually orthogonal hyperbolic planes.

**Theorem.** (*Theorem 5.4 of the text.*) *If  $V$  is a quadratic space with Witt index  $m$ , then  $V$  has a hyperbolic subspace  $H$  of dimension  $2m$  and an anisotropic subspace  $X$  with  $V = H \oplus X$ . If  $V = H' \oplus Y$  is any orthogonal splitting with  $H'$  hyperbolic and  $Y$  anisotropic, then  $\dim H' = 2m$ , and  $Y$  and  $X$  are isometric.*

We will not present the proof of this theorem, however it is easy to see that demonstrating  $Y$  and  $X$  are isometric will involve use of Witt's Cancellation Theorem. Notice also that based on this theorem we can define Witt index  $m$  as the maximum number of mutually orthogonal hyperbolic planes in  $V$ , since if we construct a basis using vectors  $u_i$  taken from hyperbolic pairs  $(u_i, v_i)$  spanning each of the  $m$  hyperbolic planes, then we will get a basis of size  $m$  for a maximal totally isotropic subspace.

**Corollary.** *If  $V$  has dimension  $n$  and Witt index  $m$  then  $m \leq n/2$ .*

FIGURE 1. A crocheted model of a hyperbolic plane



## APPENDIX

Even though we have developed some feel for the geometry of hyperbolic planes, visualizing one might not be easy. The link included at the end of this section is a link to a fun article about constructing physical models of a hyperbolic plane. The article is actually an interview with Daina Taimina, a mathematician at Cornell University, who crochets models of a hyperbolic plane, one of which is shown in Figure 1.

⟨ <http://www.cabinetmagazine.org/issues/16/crocheting.php> ⟩