

Self dual obstruction theory (Behrend)

• Model:  $f: A \rightarrow \mathbb{C}$ ,  $M = (df)^{-1}(0)$

Assume  $\dim M > 0$ ,  $M$  smooth

$$0 \rightarrow TM \rightarrow TA|_M \xrightarrow{\mathcal{D}(df)} T^*A|_M \rightarrow \text{coker} \rightarrow 0$$

This is the Hessian  $(\partial^2_{ij} f)$ , symmetric

$\Rightarrow$  The dual map  $T^*A|_M \leftarrow TA|_M$  is also  $\mathcal{D}(df)$

and hence  $\text{coker} = T^*M$ .

So: Def & Obs are dual to each other

(definition of self-dual obs-theory)

Perturb  $f$  by a function  $g$  on  $M$ :  $d(f+g)^{-1}(0) = \text{zeros of } dg \text{ on } M$

$\rightarrow$  the virtual cycle should be  $C_{\text{top}}(T^*M) = (-1)^{\dim M} e(M)$

• In general: ( $M$  self-dual obstruction theory, not necess. smooth)

Behrend shows:  $[M]^{\text{virt}} \in H_0(M)$  is  $e(M, \chi^B) := \sum_{n \in \mathbb{Z}} n \cdot e(\{\chi^B = n\})$

for some combinatorial function  $\chi^B: M \rightarrow \mathbb{Z}$  which depends only on the local analytic structure of  $M$

(on smooth part,  $\chi^B = (-1)^{\dim M}$ )

In what follows, for simplicity we ignore  $\chi^B$  & signs, just work with the Euler class (but one should really use  $\chi^B$ , since  $e(M)$  isn't deform<sup>n</sup> invariant unlike  $[M]^{\text{virt}} \dots$ )

\* MNOP theory: do deformation theory not for the subscheme  $Z \subset X$   
not for the subsheaf  $\mathcal{I}_Z \subset \mathcal{O}_X$   
 but for the sheaf  $\mathcal{I}_Z$  as a sheaf w/ fixed trivial determinant.

- $T_Z \mathcal{I}_n(X, \beta) = \text{Ext}^1(\mathcal{I}_Z, \mathcal{I}_Z)_0$
  - $\text{Obs}_Z = \text{Ext}^2(\mathcal{I}_Z, \mathcal{I}_Z)_0$
- ↙ Serre dual  
in CY 3-fold case.

\* Stable pairs. do deform<sup>n</sup> theory not as a pair, but for the  
 2-term complex with trivial det.  $I^\bullet = \{\mathcal{O}_X \xrightarrow{s} F\} \in \mathcal{D}^b(X)$

- $T_{I^\bullet} P_n(X, \beta) = \text{Ext}^1(I^\bullet, I^\bullet)_0$
  - $\text{Obs}_{I^\bullet} = \text{Ext}^2(I^\bullet, I^\bullet)_0$
- ↙ Serre dual

NB: the 2 theories agree when  $\text{coker}(s) = 0$ :

then  $I^\bullet = \{\mathcal{O}_X \xrightarrow{s} F\} \cong$  ideal sheaf  $\mathcal{I}_Z = \ker(s)$

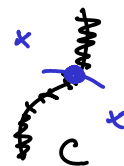
and deform<sup>n</sup> theories match. The two theories differ in their  
 treatment of free points / cokernels. Then want to compare  
 $e(\mathcal{M})$ 's (or rather,  $e(\mathcal{M}, \chi^\beta)$ 's).

• Work with a fixed Cohen-Macaulay curve  $C \subset X$ ,  $\chi(\mathcal{O}_C) = 1 - g$ .

$$\rightarrow \mathcal{I}_n(X, C) \subset \mathcal{I}_{1-g+n}(X, \beta)$$

locus of subschemes whose largest CM subscheme is  $C$ .

$Z = C \cup$  embedded pts  
free pts



$$\rightarrow P_n(X, C) \subset P_{1-g+n}(X, \beta)$$

parts supported in  $C$

Then: the formula  $\frac{Z_{\text{MOP}, \beta}}{Z_{\text{MOP}, 0}} = Z_{P, \beta}$

Corresponds to: 
$$\mathbb{I}_{n, C} = P_{n, C} + P_{n-1, C} e(X) + P_{n-2, C} e(\text{Hilb}^2 X) + \dots + e(\text{Hilb}^n X)$$

$\swarrow$   $n$  pts on  $C$        $\swarrow$   $n-1$  pts on  $C$ ,  $1$  in  $X$   
 $\swarrow$   $n$  pts in  $X$

where  $I_{n, C} = e(I_n(X, C), X^B)$   
 $P_{n, C} = e(P_n(X, C), X^B)$  etc...

Wall-crossing: If  $Z = C \cup \{p_i\}$  then  $\mathbb{I}_Z \rightarrow \mathbb{I}_C \rightarrow \mathcal{O}_{p_i}$   
 $(*) \mathcal{O}_{p_i}[-1] \rightarrow \mathbb{I}_Z \rightarrow \mathbb{I}_C$

Move across a wall in space of stability cond<sup>s</sup> so that the slope (phase) of  $\mathcal{O}_{p_i}[-1]$  crosses that of  $\mathbb{I}_C$ :

• When bigger,  $(*)$  destabilizes  $\mathbb{I}_Z$ , so  $\mathbb{I}_Z$  not stable, so it disappears from our counts.

However, extensions of the form  $\mathbb{I}_C \rightarrow ?? \rightarrow \mathcal{O}_{p_i}[-1]$  are now stable.

These extensions are of the form

$$I^\bullet = \{ \mathcal{O}_X \rightarrow F \}$$

$$\mathbb{I}_C \begin{array}{l} \uparrow \text{ker} \\ \searrow \text{coker} \end{array} \begin{array}{l} \mathcal{O}_{p_i}[-1] \end{array}$$

$$\mathcal{O}_C \rightarrow F \rightarrow \mathcal{O}_{p_i} \quad \text{governed by} \quad \text{Ext}^1(\mathcal{O}_{p_i}, \mathcal{O}_C) \cong \text{Ext}^1(\mathcal{O}_{p_i}[-1], \mathbb{I}_C) = \text{Hom}(\mathcal{O}_{p_i}, \mathbb{I}_C)$$

• Want to compare (weighted) Euler classes across the wall:

Toy Model: sheaves  $E$  which can become unstable as we cross a wall in Kähler moduli space,  $0 \rightarrow A \rightarrow E \rightarrow B \rightarrow 0$



$$\text{Hence } I_{1,C} = e(X \setminus C) + 2 \overset{e(P^1)}{e(C)} \quad \text{vs.} \quad P_{1,C} = e(C)$$

$$\Rightarrow I_{1,C} = P_{1,C} + e(X) \quad \checkmark$$

• For general  $C$  (not smooth),

$p \in X$  contributes

$$e(\mathbb{P}\text{Hom}(\mathcal{J}_C, \mathcal{O}_p)) = \text{hom}(\mathcal{I}_C, \mathcal{O}_p) \quad \text{to } \mathcal{I}_{C,1}$$

$$e(\mathbb{P}\text{Ext}^1(\mathcal{O}_p, \mathcal{O}_C)) = \text{ext}^1(\mathcal{I}_C, \mathcal{O}_p) \quad \text{to } P_{C,1}$$

By RR,  $\text{hom}(\mathcal{I}_C, \mathcal{O}_p) - \text{ext}^1(\mathcal{I}_C, \mathcal{O}_p) = 1$

hence difference in invariants is  $+1 \quad \forall p \in X$

$$\int_X \Rightarrow \text{get difference in invariants is } e(X).$$