

# Mid-term quiz 1

① The SVD of  $A = U \Sigma V^T$

$A$  = general matrix ( $m \times n$ ,  $m > n$ )

$U$  =  $m \times m$  orthogonal matrix

$\Sigma$  =  $m \times n$  diagonal matrix  
(diagonal entries are real and in ~~decreasing~~  
nonincreasing order)

$V$  =  $n \times n$  orthogonal matrix

Least squares problem can be solved by normal equations

$$\begin{matrix} m \times n & n \times 1 \\ A & x = b \end{matrix}$$

solved  
by  $\rightarrow$

$$A^T A x = A^T b$$

NORMAL EQN

(1) is an SVD because  $U$  = orthogonal

that is  $\left(\frac{1}{\sqrt{3}}\right)^2 + \left(\frac{1}{\sqrt{3}}\right)^2 + \left(\frac{1}{\sqrt{3}}\right)^2 = 1$

$$\left(\frac{1}{\sqrt{2}}\right)^2 + 0^2 + \left(\frac{1}{\sqrt{2}}\right)^2 = 1$$

$$\left(\frac{1}{\sqrt{6}}\right)^2 + \left(\frac{\sqrt{2}}{\sqrt{3}}\right)^2 + \left(\frac{1}{\sqrt{6}}\right)^2 = 1$$

$$\frac{1}{\sqrt{3}} \cdot -\frac{1}{\sqrt{2}} + \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{2}} = 0$$

$$\frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{6}} - \frac{1}{\sqrt{3}} \cdot \frac{\sqrt{2}}{\sqrt{3}} + \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{6}} = 0$$

$$-\frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{6}} + \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{6}} = 0$$

Probably is  
needed:

NOT NEEDED  
FOR  
FULL  
MARKS

$V = \text{orthogonal}$  . (clear identity = orthogonal)

$\Sigma = \text{diagonal}$  and  $\sqrt{3} > \sqrt{2}$  .

$$A^T A = (U \Sigma V^T)^T (V \Sigma V^T) = V \Sigma^T \underbrace{U^T U}_{=I} \Sigma V^T$$

$\omega U = \text{orthogonal}$

$$= V \Sigma^T \Sigma V^T$$

In our case  $V = I$  so

$$A^T A = \Sigma^T \Sigma = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \quad \cancel{A^T \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ -1 \end{pmatrix}}$$

$$A^T \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ -1 \end{pmatrix}$$

$$\therefore \text{NORMAL EQN: } \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = \begin{pmatrix} 4 \\ -1 \end{pmatrix}$$

$$\Rightarrow c = 4/3, d = -1/2$$

LEAST SQUARES ERROR :

$$(-1, 2): \quad 4/3 + \frac{1}{2} = \frac{5}{6}$$

$$(0, 1): \quad 4/3 - \frac{1}{2} \cdot 0 = 4/3$$

$$(1, 1): \quad 4/3 - \frac{1}{2} \cdot 1 = 5/6$$

$$\text{error at } (-1, 2) = \frac{1}{6}$$

$$\text{error at } (0, 1) = \frac{1}{3}$$

$$\text{error at } (1, 1) = \frac{1}{6}$$

$$\therefore \|Ax - b\|_2^2 = \frac{(1/6)^2}{\cancel{1/6}} + \left(\frac{1}{3}\right)^2 + \left(\frac{1}{6}\right)^2 = \frac{1}{6}$$

$$\text{Using calculator: } \|Ax - b\|_2 = 0.4082 \dots$$

(2)

$$u(x+h) = u(x) + hu'(x) + 2hu''(x) + \dots$$

$$u(x-h) = u(x) - hu'(x) - 2hu''(x) + \dots$$

$$\Rightarrow \frac{u(x+h) - u(x-h)}{2h} = \frac{1}{2h} [2hu'(x) + 4hu''(x) + \dots]$$

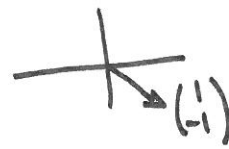
$$= u'(x) + 2hu''(x) + \dots$$

$$\therefore u'(x) \approx \frac{u(x+h) - u(x-h)}{2h} + O(h)$$

$$A_3 = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 1 \end{bmatrix}$$

Step 1: Put a zero in (2,1) entry of  $A_3$ . Rotate  $\begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$

$$\therefore A_3 \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

Step 2: Put a zero in (3,2) entry.  [Rotate 45° anticlockwise]

$$\therefore \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2}/2 & -\sqrt{2}/2 \\ 0 & \sqrt{2}/2 & \sqrt{2}/2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ \sqrt{2} \\ 0 \end{bmatrix}$$

$$\text{and } \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2}/2 & -\sqrt{2}/2 \\ 0 & \sqrt{2}/2 & \sqrt{2}/2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & \sqrt{2} & -\sqrt{2}/2 \\ 0 & 0 & \sqrt{2}/2 \end{bmatrix}$$

R

Set  $f(x) = 1$

Since  $u'(x) = 1$ ,  $u(0) = 0 \Rightarrow u(x) = x$

I guess 
$$V = \begin{pmatrix} u(h) \\ \vdots \\ u(nh) \end{pmatrix} = \begin{pmatrix} h \\ \vdots \\ nh \end{pmatrix}$$

Check it is a solution:

eq 1 :  $u(2h) = 2h = 2hf(h) = \cancel{2h} \checkmark$

eq 2 :  $-u(h) + u(3h) = 2h = 2hf(2h) \checkmark$

$\vdots$

eq (n-1) :  $-u((n-2)h) + u(nh) = 2h = 2hf((n-1)h) \checkmark$

eq n :  $-u((n-1)h) + u(nh) = h = hf(nh) \checkmark$

Since  $A_n$  is invertible  $\Rightarrow v$  is only solution.

Bonus part: 1<sup>st</sup> equation shows that  $u(2h) = 2hf(h)$   
3<sup>rd</sup> equation show that  $-u(2h) + u(4h) = 2hf(3h)$

If  $n = \text{even}$ : ① Solve for  $u(2h), u(4h), \dots, u(\cancel{2h} \dots \overset{n}{h})$  by forwards substitution.

② Use last equation to solve for  $u((n-1)h)$ .

③ Now solve for  $u((n-1)h), u((n-3)h), \dots, u(h)$  using back~~ward~~ substitution.



Repeating this argument we have

$$D = \text{identity} = L = Q.$$

$$\therefore A = U = R = \text{upper triangular}.$$

$$(d) \quad A = LU \Rightarrow A^T = U^T L^T$$

but  $U^T \neq$  unit lower triangular.

$$\text{let } D = \text{diag}(U^T)$$

$$\Rightarrow U^T D^{-1} = \text{unit lower triangular}$$

$$\text{So } A^T = \underbrace{(U^T D^{-1})}_{\text{unit lower triangular}} \underbrace{(D L^T)}_{\text{upper triangular}}.$$

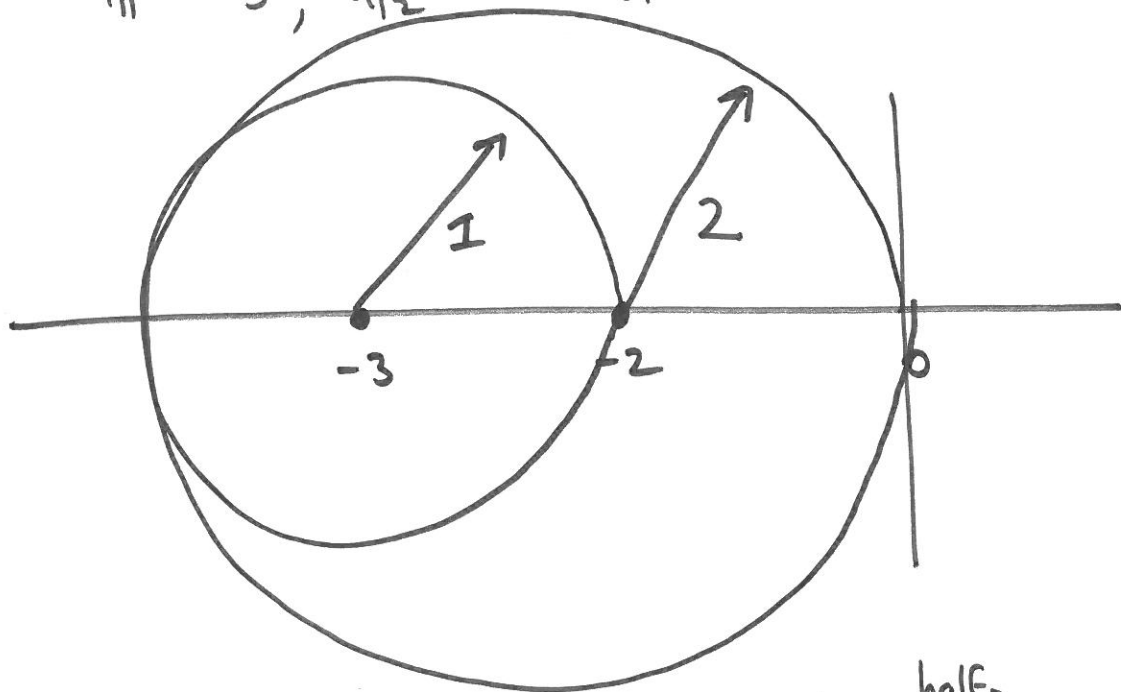
BONUS PART: IF  $A =$  upper-triangular

then  $A = LU$ ,  $L = \text{identity}.$

and  $A = QR$ ,  $Q = \text{diag}(\pm 1\text{'s})$

$$\text{So } L = Q \begin{pmatrix} \pm 1 & & \\ & \dots & \\ & & \pm 1 \end{pmatrix}$$

④  $a_{11} = -3, a_{12} = 1, a_{21} = 2, a_{22} = -2$



The circles are not in +ve real ~~part~~ <sup>half-</sup> plane  $\Rightarrow$  eigenvalues ~~not strictly~~ has nonpositive real part.

~~Not~~ Not quite:  $x(t) = A e^{\lambda_1 t} + B e^{\lambda_2 t}$   
 $y(t) = C e^{\lambda_1 t} + D e^{\lambda_2 t}$

since ~~the~~  $\text{Re}(\lambda_1) \leq 0, \text{Re}(\lambda_2) \leq 0$  (the eigenvalues could have has a zero real part)

$\Rightarrow x(t) \rightarrow 0, y(t) \rightarrow 0$  (perhaps)

$$\begin{aligned} \det(A - xI) &= \det \begin{pmatrix} -3-x & 1 \\ 2 & -2-x \end{pmatrix} = (x+3)(x+2) - 2 \\ &= x^2 + 5x + 6 - 2 \\ &= x^2 + 5x + 4 \\ &= (x+1)(x+4) \end{aligned}$$

$\Rightarrow$  eigenvalues of  $A = -1$  and  $-4$ .

Now

$$\underline{\lambda_1 = -1}: \quad \begin{pmatrix} -3 & 1 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} -v_1 \\ -v_2 \end{pmatrix}$$

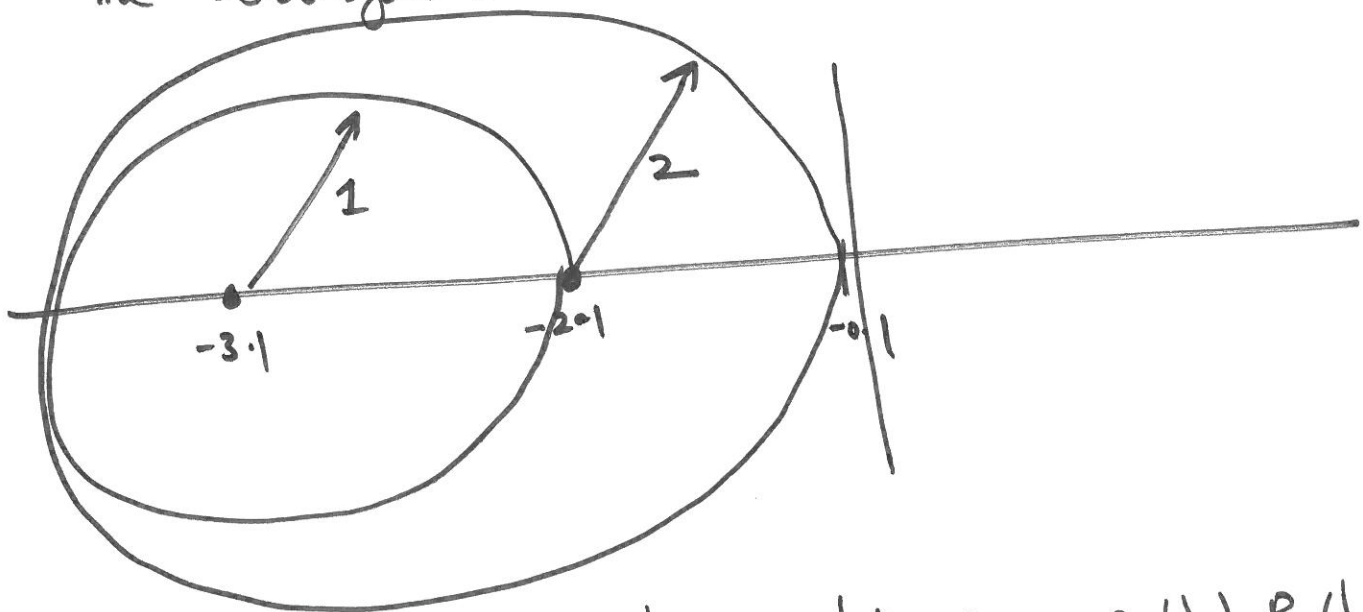
$$\Rightarrow \begin{cases} -2v_1 + v_2 = 0 \\ 2v_1 - v_2 = 0 \end{cases} \Rightarrow \begin{cases} v_1 = 1/2 \\ v_2 = 1 \end{cases}$$

$$\underline{\lambda_2 = -2}: \quad \begin{pmatrix} -3 & 1 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} -4v_1 \\ -4v_2 \end{pmatrix}$$

$$\Rightarrow \begin{cases} v_1 + v_2 = 0 \\ 2v_1 + v_2 = 0 \end{cases} \Rightarrow \begin{cases} v_1 = 1 \\ v_2 = -1 \end{cases}$$

BONUS PART:

The Gerschgorin discs are now:



So

$$\left. \begin{aligned} x(t) &= Ae^{\lambda_1 t} + Be^{\lambda_2 t} \\ y(t) &= Ce^{\lambda_1 t} + De^{\lambda_2 t} \end{aligned} \right\} \text{ and } \operatorname{Re}(\lambda_1), \operatorname{Re}(\lambda_2) < 0$$
$$\Rightarrow x(t), y(t) \rightarrow 0 \text{ as } t \rightarrow \infty.$$