

Answers to Problem Set # 04, 18.306

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1 Fundamental solution for the Laplace operator

1.1 Statement: Fundamental solution for the Laplace operator

Let Δ be the Laplace operator in \mathcal{R}^d

$$\Delta = \sum_{n=1}^d \partial_{x_n}^2, \tag{1.1}$$

where $d \geq 3$. Further, let G be defined by

$$G = \frac{1}{(d-2)\alpha_d r^{d-2}}, \quad \text{where } r = \sqrt{\sum_{n=1}^d x_n^2} \tag{1.2}$$

and α_d is the "area" of the unit sphere $S^d(1)$ in d -dimensions. Show that

$$\Delta G = -\delta(\vec{x}), \tag{1.3}$$

where δ is Dirac's delta in \mathcal{R}^d . That is: show that for any test function¹ ψ in \mathcal{R}^d

$$\psi(0) + \int_{\mathcal{R}^d} G \Delta \psi dV = 0, \quad (1.4)$$

where $dV = dx_1 \dots dx_d$ is the "volume" element in \mathcal{R}^d . Proceed as follows

1. For any function f in R^d , define the radial function $\bar{f} = \bar{f}(r)$ by averaging over the angular variables:

$$\bar{f} = \frac{1}{\alpha_d} \int_{S^d(1)} f(r, \vec{\sigma}) dS = \frac{1}{\alpha_d r^{d-1}} \int_{S^d(r)} f d\tilde{S}, \quad (1.5)$$

where: (i) $\vec{\sigma}$ are the angular variables in R^d ; (ii) dS is the surface element in $S^d(1)$ — dS involves only the angular variables; and (iii) $d\tilde{S} = r^{d-1} dS$ is the area element in $S^d(r)$ (sphere of radius r).

2. Use Gauss theorem to express $\bar{\psi}_r$ in terms of the integral of $\Delta \psi$ over a ball of radius r . That is, in terms of: $\int_{B^d(r)} \Delta \psi dV$, where $B^d(r) = \{\vec{x} \in R^d \mid \|\vec{x}\| \leq r\}$.

3. Use 2 to show that $\Delta \bar{\psi} = \overline{\Delta \psi}$. (1.6)

Note: $\Delta g = r^{1-d} (r^{d-1} g_r)_r$ for radial functions.

4. Use the fact that $dV = r^{d-1} dr dS$ to re-write the integral in (1.4). You are now a small step away from being able to show (1.4) applies.

Important: You **do not need** explicit expressions for the angular variables.

This problem involves very few grungy calculation.

1.2 Answer: Fundamental solution for the Laplace operator

Since $\psi_r = \hat{n} \text{grad}(\psi)$, where \hat{n} is the radial unit vector, we have

$$\bar{\psi}_r = \frac{1}{\alpha_d} \int_{S^d(1)} \psi_r(r, \vec{\sigma}) dS = \frac{1}{\alpha_d r^{d-1}} \int_{S^d(r)} \hat{n} \text{grad}(\psi) d\tilde{S} = \frac{1}{\alpha_d r^{d-1}} \int_{B^d(r)} \Delta \psi dV \quad (1.7)$$

where $S^d(r)$ is the sphere of radius r , $d\tilde{S} = r^{d-1} dS$ is the area element in $S^d(r)$, and $B^d(r)$ is the ball of radius r . We now use (1.7) to write

$$\begin{aligned} \Delta \bar{\psi} &= \frac{1}{r^{d-1}} (r^{d-1} \bar{\psi}_r)_r = \frac{1}{\alpha_d r^{d-1}} \left(\int_{B^d(r)} \Delta \psi dV \right)_r \\ &= \frac{1}{\alpha_d r^{d-1}} \left(\int_0^r \rho^{d-1} d\rho \int_{S^d(1)} \Delta \psi(\rho, \vec{\sigma}) dS \right)_r = \overline{\Delta \psi}. \end{aligned} \quad (1.8)$$

Finally, we can write

$$\begin{aligned} \int_{\mathcal{R}^d} G \Delta \psi dV &= \frac{1}{(d-2)\alpha_d} \int_0^\infty r dr \int_{S^d(1)} \Delta \psi(r, \vec{\sigma}) dS = \frac{1}{d-2} \int_0^\infty r dr \overline{\Delta \psi} \\ &= \frac{1}{d-2} \int_0^\infty r^{2-d} (r^{d-1} \bar{\psi}_r)_r dr = \int_0^\infty \bar{\psi}_r dr = -\bar{\psi}(0) = -\psi(0). \end{aligned} \quad (1.9)$$

¹ A smooth function decaying as fast as you need as $r \rightarrow \infty$.

2 Green's functions #11

2.1 Statement: Green's functions #11

The Green's function for the heat equation half line Dirichlet² signaling problem is defined by

$$G_t = G_{xx}, \quad \text{for } -\infty < t < \infty \quad \text{and} \quad x > 0, \quad (2.1)$$

with the boundary condition

$$G(0, t) = \delta(t), \quad (2.2)$$

where $\delta(\cdot)$ denotes Dirac's delta function. In addition: G is bounded away from the origin $(0, 0)$ and satisfies **causality** $G = 0$ for $t < 0$.

Thus **we only need to find G for $t \geq 0$ only.**

For any constant $\nu \neq 0$, $\nu^2 \delta(\nu^2 t) = \delta(t)$. Thus: If G is a solution, $\nu^2 G(\nu x, \nu^2 t)$ is a solution.

Hence, from uniqueness, for any $\nu \neq 0$,

$$G(x, t) = \nu^2 G(\nu x, \nu^2 t). \quad (2.3)$$

Set $\nu = x/t$ to get, for some function $g = g(\xi)$,

$$G(x, t) = \frac{1}{t} g\left(\frac{x^2}{t}\right). \quad (2.4)$$

Notice that

A. $g(0) = 0$. This follows because, for any $t > 0$ fixed, G must vanish as $x \downarrow 0$.

B. $\int_0^\infty g(\xi) \frac{d\xi}{\xi} = 1$. We have $\int_{-\infty}^\infty G(x, t) dt = \int_0^\infty g(\xi) \frac{d\xi}{\xi} = \text{constant}$, for any $x > 0$.

By taking $x \downarrow 0$, and using (2.2), the result follows.

- **Task 1:** Substitute (2.4) into (2.1), and get an o.d.e. for g .
- **Task 2:** Solve the o.d.e. for g , and thus find the Green's function.

Hints: (i) The o.d.e. for g is second order. It can be integrated once, to yield a first order equation. (ii) The general solution to the o.d.e. in **1** has two constants. These follow from **A – B** above.

Remark 2.1 For any fixed $x > 0$, the formula in (2.4) should, as $t \downarrow 0$, smoothly match with the solution $G \equiv 0$ for $t < 0$. This will be guaranteed by the fact that $g(\xi)$ vanishes exponentially as $\xi \rightarrow \infty$. Hence, G as given by (2.4), as well as all its derivatives, vanish as $t \downarrow 0$ for any $x > 0$. ♣

2.2 Answer: Green's functions #11

Substituting (2.4) into (2.1) yields

$$4\xi \frac{d^2g}{d\xi^2} + (2 + \xi) \frac{dg}{d\xi} + g = 0. \quad (2.5)$$

Hence, for some constant a ,

$$4\xi \frac{dg}{d\xi} + (\xi - 2)g = 4a. \quad (2.6)$$

Thus, for some constant b ,

$$g = a \left(\sqrt{\xi} \int_0^\xi \frac{e^{s/4} - 1}{s^{3/2}} ds - 2 \right) e^{-\xi/4} + b \sqrt{\xi} e^{-\xi/4}. \quad (2.7)$$

Since $g(0) = 0$, $a = 0$. So:

$$g = b \sqrt{\xi} \exp\left(-\frac{\xi}{4}\right) \quad (2.8)$$

Then **B** yields

$$1 = b \int_0^\infty e^{-\xi/4} \frac{d\xi}{\sqrt{\xi}} = 2b\sqrt{\pi}, \quad (2.9)$$

which leads to the **final answer**

$$G = \frac{x}{2\sqrt{\pi} t^{3/2}} \exp\left(-\frac{x^2}{4t}\right). \quad (2.10)$$

² Temperature prescribed on the boundary.

To visualize how this approaches a Delta function

as $x \downarrow 0$, write G in terms of $\tau = \frac{4t}{x^2}$. Then

$$G = \frac{4}{\sqrt{\pi} x^2} \frac{1}{\tau^{3/2}} \exp\left(-\frac{1}{\tau}\right). \quad (2.11)$$

As a function of τ increasing, G starts at 0 — with all its derivatives vanishing. It then rises rapidly to reach its maximum at $\tau = 2/3$, and then decays back to zero as $\tau \rightarrow \infty$. This function shape is then amplified and compressed by x^2 — via the pre-factor and the dependence of τ on x^2 .

3 Laplace equation in a circle #01

3.1 Statement: Laplace equation in a circle #01

Green's function: Laplace equation in a circle, with Dirichlet BC. Consider the question of determining the steady state temperature in a thin circular plate such that: (a) The temperature is prescribed at the edges of the plate, and (b) The facets of the plate (top and bottom) are insulated. This problem can be written — using polar coordinates and non-dimensional variables (selected so that the plate has radius 1) — in the form

$$\frac{1}{r^2} (r(rT_r)_r + T_{\theta\theta}) = \Delta T = 0, \quad \text{for } 0 \leq \theta \leq 2\pi \quad \text{and } 0 \leq r \leq 1, \quad (3.1)$$

with the boundary condition[†]

$$T(1, \theta) = h(\theta), \quad \text{for some given function } h. \quad (3.2)$$

[†] T and h are 2π -periodic in θ .

The solution to this problem, as follows from separation of variables, is³

$$T = \sum_{n=-\infty}^{\infty} h_n r^{|n|} e^{in\theta}, \quad \text{where } h_n = \frac{1}{2\pi} \int_0^{2\pi} h(\theta) e^{-in\theta} d\theta. \quad (3.3)$$

For $r < 1$ this formula provides a solution to the equation even if h is not very smooth (or in fact, not even a function) and thus has a very poorly convergent Fourier series $\sum h_n e^{in\theta}$. For example, assume that the sequence $\{h_n\}$ is bounded. Then, in any disk of radius $R < 1$: (i) the series for T in (3.3) converges absolutely; and (ii) the series obtained by term by term differentiation, for any derivative of T , also converges absolutely. It follows that T is smooth for $r < 1$. In a similar fashion, one can justify exchanging the order of integration and summation — as you are asked to do below.

1. Assume that $h = \delta(\theta)$, and **write an explicit formula for the solution T .**

2. In (3.3), substitute the formula for h_n into the series for T , exchange the summation and integration order, and

derive an equation of the form

$$T = \int_0^{2\pi} G(r, \theta - \phi) h(\phi) d\phi. \quad (3.4)$$

3. **Show that:**

(a) $G > 0$ for $r < 1$.

(b) $G(r, \theta) \rightarrow 0$ as $r \rightarrow 1$, if $\theta \neq 0$.

(c) $\int_0^{2\pi} G(r, \theta) d\theta = 1$ for $r < 1$.

Hint. Add the positive and negative indexes n separately. Then use that $\sum_{n=0}^{\infty} z^n = \frac{1}{1-z}$ for $|z| < 1$.

³ Check, by direct substitution, that this is indeed the solution. That (3.2) is satisfied should be “obvious”.

3.2 Answer: Laplace equation in a circle #01

Let us first **assume that $h = \delta(\theta)$** . Then $h_n = \frac{1}{2\pi}$ for all n , so that

$$2\pi T = \sum_{n=0}^{\infty} r^n e^{in\theta} + \sum_{n=0}^{\infty} r^n e^{-in\theta} - 1 = \frac{1}{1-r e^{i\theta}} + \frac{1}{1-r e^{-i\theta}} - 1.$$

Thus

$$T = \frac{1}{2\pi} \frac{1-r^2}{1-2r\cos\theta+r^2} = G(r, \theta), \quad (3.5)$$

where G is defined by the equation.

More generally, $h_n = \frac{1}{2\pi} \int_0^{2\pi} h(\phi) e^{-in\phi} d\phi$ leads to

$$2\pi T = \int_0^{2\pi} \left(\sum_{n=0}^{\infty} r^n e^{in(\theta-\phi)} + \sum_{n=0}^{\infty} r^n e^{-in(\theta-\phi)} - 1 \right) h(\phi) d\phi.$$

Thus the general formula

$$T = \int_0^{2\pi} G(r, \theta - \phi) h(\phi) d\phi, \quad (3.6)$$

where G is as in (3.5).

Finally

(a) $1 - 2r\cos\theta + r^2 = (1-r)^2 + 2r(1-\cos\theta) > (1-r)^2$. Thus $G > 0$ for $r < 1$.

(b) $1 - 2r\cos\theta + r^2 = (r - \cos\theta)^2 + 1 - \cos^2\theta > 1 - \cos^2\theta$. Thus $\lim_{r \rightarrow 1} G(r, \theta) = 0$ if $\theta \neq 0$.

(c) For $r < 1$, $G = \frac{1}{2\pi} \left(\sum_{n=0}^{\infty} r^n e^{in\theta} + \sum_{n=0}^{\infty} r^n e^{-in\theta} - 1 \right)$, which converges absolutely, and can be integrated term

by term. Thus $\int_0^{2\pi} G(r, \theta) d\theta = 1$ for $r < 1$.

In fact, the same argument in item c shows that, for $r < 1$,

$$\int_0^{2\pi} G(r, \theta) h(\theta) d\theta = \sum_{n=-\infty}^{\infty} r^{|n|} h_n.$$

If h is smooth enough $h(0) = \sum_{n=-\infty}^{\infty} h_n$, where convergence is absolute. Thus $G \rightarrow \delta(\theta)$ as $r \rightarrow 1$.

4 Laplace equation in a circle #02

4.1 Statement: Laplace equation in a circle #02

Green's function: Laplace equation in a circle, with Neumann BC. Consider the question of determining the steady state temperature in a thin circular plate such that: (a) The temperature flux is prescribed at the edges of the plate, and (b) The facets of the plate (top and bottom) are insulated. This problem can be written — using polar coordinates and non-dimensional variables (selected so that the plate has radius 1) — in the form

$$\frac{1}{r^2} (r(r T_r)_r + T_{\theta\theta}) = \Delta T = 0, \quad \text{for } 0 \leq \theta \leq 2\pi \quad \text{and } 0 \leq r \leq 1, \quad (4.1)$$

with the boundary condition[†] $T_r(1, \theta) = h(\theta)$, for some given function h . (4.2)

[†] T and h are 2π -periodic in θ .

In addition, the function $h = h(\theta)$ must satisfy
$$\int_0^{2\pi} h(\theta) d\theta = 0. \quad (4.3)$$

Equation (4.3) follows because, unless the net heat flux through the boundary vanishes, no steady state temperature is possible. Equivalently: (4.1–4.2) does not have a solution unless (4.3) applies.

The solution to this problem, as follows from separation of variables, is⁴

$$T = \sum_{-\infty < n < \infty, n \neq 0} \frac{1}{|n|} h_n r^{|n|} e^{in\theta}, \quad \text{where } h_n = \frac{1}{2\pi} \int_0^{2\pi} h(\theta) e^{-in\theta} d\theta, \quad (4.4)$$

where, **to make the solution unique**,⁵ we have added the condition: $T = 0$ at the origin.

For $r < 1$ this formula provides a solution to the equation even if h is not very smooth (or in fact, not even a function) and thus has a very poorly convergent Fourier series $\sum h_n e^{in\theta}$. For example, assume that the sequence $\{h_n\}$ is bounded. Then, in any disk of radius $R < 1$: (i) the series for T in (4.4) converges absolutely; and (ii) the series obtained by term by term differentiation, for any derivative of T , also converges absolutely. It follows that T is smooth for $r < 1$. In a similar fashion, one can justify exchanging the order of integration and summation — as you are asked to do below.

1. Assume that $h = \delta(\theta) - \frac{1}{2\pi}$, and **write an explicit formula for the solution T** .

2. In (4.4), substitute the formula for h_n into the series for T , exchange the summation and integration order, and

derive an equation of the form

$$T = \int_0^{2\pi} G(r, \theta - \phi) h(\phi) d\phi. \quad (4.5)$$

3. Let $H = G_r + \frac{1}{2\pi}$. **Show that:**

$$(a) H(r, \theta) \rightarrow 0 \text{ as } r \rightarrow 1, \text{ if } \theta \neq 0. \quad (b) \int_0^{2\pi} H(r, \theta) d\theta = 1 \text{ for } r < 1.$$

Hint. Add the positive and negative indexes n separately. Then use $\sum_{n=1}^{\infty} \frac{1}{n} z^n = -\ln(1-z)$ for $|z| < 1$ — note that, for $|z| < 1$ the argument for the log stays within a circle of radius 1 centered at 1, so that no problem arises because of the branch point of the log at the origin.

4.2 Answer: Laplace equation in a circle #02

Let us first **assume that $h = \delta(\theta) - \frac{1}{2\pi}$** . Then $h_n = \frac{1}{2\pi}$ for all $n \neq 0$, so that

$$2\pi T = \sum_{n=1}^{\infty} \frac{1}{n} r^n e^{in\theta} + \sum_{n=1}^{\infty} \frac{1}{n} r^n e^{-in\theta} = -\ln((1-r e^{i\theta})(1-r e^{-i\theta})).$$

Thus

$$T = -\frac{1}{2\pi} \ln(1 - 2r \cos \theta + r^2) = G(r, \theta), \quad (4.6)$$

where G is defined by the equation — note that $1 - 2r \cos \theta + r^2 \geq (1-r)^2$, so that there is no problem with the meaning of \ln in the formula.

More generally, $h_n = \frac{1}{2\pi} \int_0^{2\pi} h(\phi) e^{-in\phi} d\phi$ leads to

$$2\pi T = \int_0^{2\pi} \left(\sum_{n=1}^{\infty} \frac{1}{n} r^n e^{in(\theta-\phi)} + \sum_{n=1}^{\infty} \frac{1}{n} r^n e^{-in(\theta-\phi)} \right) h(\phi) d\phi.$$

⁴ Check, by direct substitution, that this is indeed the solution. That (4.2) is satisfied should be “obvious”.

⁵ A constant can be added to any solution of (4.1–4.2).

Thus the general formula

$$T = \int_0^{2\pi} G(r, \theta - \phi) h(\phi) d\phi, \quad (4.7)$$

where G is as in (4.6).

Finally, it is easy to check that

$$H = G_r + \frac{1}{2\pi} = \frac{1}{2\pi} \frac{(1-r)(1+2\cos\theta-r)}{1-2r\cos\theta+r^2}.$$

From this it follows that

(a) $1 - 2r\cos\theta + r^2 = (r - \cos\theta)^2 + 1 - \cos^2\theta > 1 - \cos^2\theta$. Thus $\lim_{r \rightarrow 1} H(r, \theta) = 0$ if $\theta \neq 0$.

(b) For $r < 1$, $H = \frac{1}{2\pi} \left(\sum_{n=1}^{\infty} r^{n-1} e^{in\theta} + \sum_{n=1}^{\infty} r^{n-1} e^{-in\theta} + 1 \right)$, which converges absolutely, and can be integrated term by term. Thus $\int_0^{2\pi} H(r, \theta) d\theta = 1$ for $r < 1$.

The same argument in (b) shows that, for $r < 1$,

$$\int_0^{2\pi} H(r, \theta) h(\theta) d\theta = h_0 + \sum_1^{\infty} r^{n-1} (h_n + h_{-n}).$$

If h is smooth enough $h(\mathbf{0}) = \sum_{-\infty}^{\infty} h_n$, where convergence is absolute. Thus $\mathbf{H} \rightarrow \delta(\theta)$ as $\mathbf{r} \rightarrow \mathbf{1}$.

5 Normal modes #02

5.1 Statement: Normal modes #02

Normal mode expansions are not guaranteed to work when the associated eigenvalue problem is not self adjoint (more generally, not normal).⁶ Here is an example: consider the problem

$$u_t + u_x = 0 \quad \text{for } 0 < x < 1 \quad \text{and } t > 0, \quad \text{with } u(x, 0) = U(x) \quad (5.1)$$

and boundary condition $u(0, t) = 0$. **Find all the normal mode solutions** to this problem,⁷ and **show that the solution to (5.1) cannot be written as a linear combination of these modes. What is the solution to (5.1)?**

5.2 Answer: Normal modes #02

Substitute $u = e^{\lambda t} \phi(x)$ into (5.1). This yields the eigenvalue problem

$$\lambda \phi + \phi' = 0, \quad \text{for } 0 < x < 1, \quad \text{with } \phi(0) = 0, \quad (5.2)$$

where a prime denotes a derivative. Hence $\phi \equiv 0$ for any λ . Thus **there are no normal modes!**

The solution to (5.1) is:

$$u = f(t - x), \quad (5.3)$$

where $f(\zeta) = U(-\zeta)$ for $-1 < \zeta < 0$, and $f(\zeta) = 0$ for $\zeta > 0$. Note that the solution vanishes for $t > 1$, while a normal mode would (at best) decay exponentially [another way to see that there can be no normal modes].

THE END.

⁶ An operator A is normal if it commutes with its adjoint: $AA^\dagger = A^\dagger A$.

⁷ That is: non-trivial solutions of the form $u = e^{\lambda t} \phi(x)$, where λ is a constant.