# 1 Exercise 1 solution

### 1.1 Part (a)

We define the map  $F : \mathbb{R}^4 \to \mathbb{R}^2$  by:

$$F(x_1, x_2, x_3, x_4) := (x_1^2 + x_2^2 - x_3^2 - x_4^2, x_1^2 + x_2^2 + x_3^2 + x_4^2 - 4)$$

Then, we have that the wanted set M is equal to  $F^{-1}\{0\}$ . If we show that 0 is a regular value of F, it will follow that M is a submanifold of  $\mathbb{R}^4$  of dimension 4-2=2.

We know that at  $(x_1, x_2, x_3, x_4)$  the differential of F equals

$$\begin{bmatrix} 2x_1 & 2x_2 & -2x_3 & -2x_4 \\ 2x_1 & 2x_2 & 2x_3 & 2x_4 \end{bmatrix}$$

If  $(x_1, x_2, x_3, x_4) \in F^{-1}\{0\}$  then we can check that  $x_1$  and  $x_2$  can't simultaneously be 0. Similarly, both  $x_3$  and  $x_4$  can't be 0. Hence, the above matrix has full rank. Thus M is indeed a 2 dimensional submanifold of  $\mathbb{R}^4$ .

#### 1.2 Part (b)

We know that the tangent space to M at p = (1, 1, -1, -1) is 2 dimensional, and given by the kernel of  $T_pF$ . As computed above,

$$T_p F = \left[ \begin{array}{rrrr} 2 & 2 & 2 & 2 \\ 2 & 2 & -2 & -2 \end{array} \right]$$

The kernel of this, we can see is the span of the two vectors  $\{(p, (1, -1, 0, 0)), (p, (0, 0, 1, -1))\}$ .

### 1.3 Part (c)

Denote the span of the vectors  $\{e_2, e_3\}$  by V, and  $\{e_1, e_4\}$  by W. Note that  $\mathbb{R}^4 = V \oplus W$ .

$$DF(p)|_W = \begin{bmatrix} 2 & 2\\ 2 & -2 \end{bmatrix}$$

The determinant of this is 8, so  $DF(p)|_W$  is invertible. F is also smooth, so we can use the implicit function theorem to tell us that there exists some smooth function  $g: V \longrightarrow W$  so in a neighborhood of  $(x_2, x_3) = (1, -1)$ ,

$$F(g_1(x_2, x_3), x_2, x_3, g_2(x_2, x_3)) = 0$$

Then the chain rule tells us that

$$DF(p)|_{W}Dg(1,-1) + DF(p)|_{V} = 0$$

So

$$Dg(1-1) = -\begin{bmatrix} 2 & 2\\ 2 & -2 \end{bmatrix}^{-1} \begin{bmatrix} 2 & 2\\ 2 & -2 \end{bmatrix} = \begin{bmatrix} -1 & 0\\ 0 & -1 \end{bmatrix}$$

# 2 Exercise 2 solution

The question of whether TX is a manifold is local on TX, since we ask that there exists some open set about each point (x, v). Thus for each x, we may replace Xby an open neighborhood U of x in X, for which there exists a diffeomorphism  $\phi: U \longrightarrow V$ , where  $V \subset \mathbb{R}^n$  is open. We now answer the equivalent question for U. We know that  $T(\phi): TU \longrightarrow TV \cong V \times \mathbb{R}^n$  is then a smooth map. We know also that  $T(\phi^{-1})$  maps TV to TU and is smooth. We must check that these maps are inverses to each other. This follows from the chain rule. Thus, TU is diffeomorphic to  $TV \cong V \times \mathbb{R}^n$ . This is an open subset of  $\mathbb{R}^{2n}$ . Hence, it follows that TX is a 2n-dimensional manifold.

## 3 Exercise 3 solution

#### 3.1 Part (a)

Let  $S_n$  denote the set of all  $n \times n$  symmetric matrices. As suggested in the lecture notes, Lecture 2, Example 3, we consider the map

$$\begin{array}{rccc} f: M_n & \to & S_n \\ & A & \mapsto & A^T A - I \end{array}$$

which is a smooth map, as it is given in coordinates by polynomial expressions. Then,  $O(n) = f^{-1}(0)$ . To see this note that

$$Ax \cdot Ay = x^T A^T Ay$$

so A preserves the dot product if and only if  $A^T A = I$ .

To apply Theorem 1 from the same lecture, we need to check that every element  $A \in O(n)$  is a regular value for the map f. Since  $M_n \cong \mathbb{R}^{n^2}$ , we may identify the

tangent space at every point A naturally with  $M_n$  itself. Thus, to compute Df(A), we may consider paths of the form p(t) = A + tX, where X is an arbitrary element of  $M_n$ .

In particular, we have that

$$f(A + tX) = (A + tX)^{T}(A + tX) - Id = A^{T}A + t(X^{T}A + A^{t}X) + t^{2}X^{T}X - Id$$
  
=  $t(X^{T}A + A^{T}X) + t^{2}X^{T}X.$ 

We apply  $\frac{d}{dt}|_{t=0}$ , to get  $Df(A)(X) = X^T A + A^T X$ . We immediately get that the above matrix lies in  $S_n$ . Now, given any  $A \in O^n$ , and  $Y \in T_0 S_n \cong S_n$ , we let X = AY/2. Then  $Df(A)(X) = Y/2^T A^T A + A^T AY/2 = Y$ . Therefore, Df(A) is surjective for all  $A \in O^n$ .

Using the fact that the space of all  $n \times n$  symmetric matrices is a vector space of dimension  $\frac{n(n+1)}{2}$ , it follows that O(n) is a smooth  $\frac{n(n-1)}{2}$  submanifold of  $\mathbb{R}^{n^2}$  of dimension  $\frac{n(n+1)}{2}$ . Every element of O(n) has orthonormal rows, so O(n) is a bounded subset of the space of all  $n \times n$  matrices. (In particular, each entry is bounded by 1.) Also, since the map  $A \mapsto AA^t - Id$  is continuous, the preimage of zero under this map, which is precisely O(n) is closed. Consequently, O(n) is indeed compact.

#### **3.2** Part (b)

Identifying  $T_I M_n$  with  $M_n$  as above, we have

$$T_I O(n) = \ker Df(I)$$

As computed above,  $Df(I)(X) = X^T I + I^T X = X^T + X$ . We therefore have that

$$T_I O(n) = Skew(n) = \{A \in M_n | A^T + A = 0\}$$

## 4 Exercise 4 solution

We reduce this to the Theorem 1 of Lecture 2, as follows.

First, the condition that  $X = f^{-1}(Y)$  is a manifold is local on both X and Y, which we see as follows. X is a submanifold if every point  $x \in X$  has some open neighborhood V diffeomorphic to an open subset in  $\mathbb{R}^s$ . Thus, for a fixed x, we can replace X by an open neighborhood U of x, and V by  $U \cap V$  (and conversely,  $U \cap V$ is open in X). Similarly, we can replace Y by a neighborhood of y = f(x).

By choosing a sufficiently small neighborhood of y, we may in fact take Y to be the coordinate plane  $\mathbb{R}^k \subset \mathbb{R}^m$ . Consider the projection  $\pi : \mathbb{R}^m \to \mathbb{R}^m / \mathbb{R}^k \cong \mathbb{R}^{m-k}$ . Then, clearly,  $Y = \pi^{-1}(0)$ , and thus,  $f^{-1}(Y) = f^{-1}(\pi^{-1}(0)) = (\pi \circ f)^{-1}(0)$ . The condition that f was transversal to Y at x clearly implies that x is a regular point of  $(\pi \circ f)$ , and we thus by Theorem 1 of the notes, we are done.