

3.1.3. Integrating from 0 to 1,  $\int_0^1 f(x)dx = \int_0^1 -\frac{dw}{dx}dx = -(w(1)-w(0)) = 0$ , which is the sought condition on  $f$ .

3.1.4. Integrating  $-u'' = e^x$  twice, we obtain  $u = -e^x + Ax + B$ . Now  $u(0) = u(1) = 0$  imply  $A = e - 1, B = 1$  i.e.  $u = -e^x + (e - 1)x + 1$ .

3.1.7. For  $p = 0$ , the equation becomes  $-u'' = 0$ , whose general solution is  $u = Ax + B$ . For  $p \neq 0$ , setting  $u = e^{\lambda x}$  and solving for  $\lambda$  we get  $\lambda = 0$  or  $\lambda = p$ . Thus the general solution in this case is  $u = Ae^{px} + B$ .

3.1.10. The discrete equation for  $-u'' = 2, u(0) = u(1) = 0$  has the form  $K \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = F$ , where  $F_i = \int_0^1 2\phi_i dx = \frac{1}{2}$  (twice the area of the graph under  $\phi_i$ )

and  $K_{ij} = \int_0^1 \phi_i' \phi_j' dx$ . Since  $\phi_2, \phi_3$  are just shifts of  $\phi_1$ , we only need to compute  $K_{11} = \int_0^{1/2} 16dx = 8, K_{12} = \int_{1/4}^{1/2} (-4)(4)dx = -4$ , hence the equation becomes  $\begin{bmatrix} 8 & -4 & 0 \\ -4 & 8 & -4 \\ 0 & -4 & 8 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \end{bmatrix} \Rightarrow \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \frac{1}{16} \begin{bmatrix} 3 \\ 4 \\ 3 \end{bmatrix}$ . These values perfectly match the values of the actual solution  $u = x - x^2$  at  $x = \frac{1}{4}, \frac{2}{4}, \frac{3}{4}$ .

3.1.12. We will use the same  $\phi_i$  as in the previous problem. Again, because of symmetry, we only need to compute  $M_{11} = \int_0^{1/4} (4x)^2 dx + \int_{1/4}^{1/2} (1 - 4x)^2 dx = \frac{1}{6}, M_{12} = \int_{1/4}^{1/2} (4x)(1 - 4x)dx = \frac{1}{24}$ . The desired matrix is

$$M = \begin{bmatrix} \frac{1}{6} & \frac{1}{24} & 0 \\ \frac{1}{24} & \frac{1}{6} & \frac{1}{24} \\ 0 & \frac{1}{24} & \frac{1}{6} \end{bmatrix}.$$

3.1.14. Integrating  $\frac{d}{dx}(w(x)v(x)) = w(x)\frac{dv}{dx} + v(x)\frac{dw}{dx}$  from 0 to 1, and setting  $w(x) = c(x)\frac{du}{dx}$ , we obtain  $[c(x)v(x)\frac{du}{dx}]_0^1 = \int_0^1 d(c(x)\frac{du}{dx})v(x)dx + \int_0^1 c(x)\frac{du}{dx}\frac{dv}{dx}dx$ , i.e. equation (21).

3.1.15. Once finds  $\phi_5 = -\frac{4}{h^2}(x - h)(x - 2h), \phi_5' = -\frac{4}{h^2}(2x - 3h)$ . Using Simpson's formula,  $K_{55} = \frac{h}{6}(\phi_5'(h))^2 + 0 + \frac{h}{6}(\phi_5'(2h))^2 = \frac{16}{3h}$ .