18.175: Lecture 31 More Markov chains

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Outline

Recollections

General setup and basic properties

Recurrence and transience

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Recurrence and transience

▶ Consider a sequence of random variables X_0, X_1, X_2, \ldots each taking values in the same state space, which for now we take to be a finite set that we label by $\{0, 1, \ldots, M\}$.

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- Sequence is called a **Markov chain** if we have a fixed collection of numbers P_{ij} (one for each pair $i,j \in \{0,1,\ldots,M\}$) such that whenever the system is in state i, there is probability P_{ij} that system will next be in state j.

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- ▶ Kind of an "almost memoryless" property. Probability distribution for next state depends only on the current state (and not on the rest of the state history).

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For this to make sense, we require $P_{ij} \ge 0$ for all i, j and $\sum_{i=0}^{M} P_{ij} = 1$ for each i. That is, the rows sum to one.

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- One can solve the system of linear equations $\pi_j = \sum_{k=0}^M \pi_k P_{kj}$ to compute the values π_j . Equivalent to considering A fixed and solving $\pi A = \pi$. Or solving $(A-I)\pi = 0$. This determines π up to a multiplicative constant, and fact that $\sum \pi_j = 1$ determines the constant.

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- Snakes and ladders.

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- Say that X_n is a **Markov chain** w.r.t. \mathcal{F}_n with transition probability p if $P(X_{n+1} \in B | \mathcal{F}_n) = p(X_n, B)$.

Markov chains: general definition

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- ▶ How do we construct an infinite Markov chain? Choose p and initial distribution μ on (S, S). For each $n < \infty$ write

$$P(X_j \in B_j, 0 \le j \le n) = \int_{B_0} \mu(dx_0) \int_{B_1} p(x_0, dx_1) \cdots$$

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Extend to $n = \infty$ by Kolmogorov's extension theorem.

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- ▶ **Notation:** Extension produces probability measure P_{μ} on sequence space $(S^{0,1,\dots}, S^{0,1,\dots})$.
- ▶ **Theorem:** $(X_0, X_1, ...)$ chosen from P_μ is Markov chain.
- ▶ **Theorem:** If X_n is any Markov chain with initial distribution μ and transition p, then finite dim. probabilities are as above.

Markov properties

▶ Markov property: Take $(\Omega_0, \mathcal{F}) = (S^{\{0,1,\ldots\}}, \mathcal{S}^{\{0,1,\ldots\}})$, and let P_μ be Markov chain measure and θ_n the shift operator on Ω_0 (shifts sequence n units to left, discarding elements shifted off the edge). If $Y: \Omega_0 \to \mathbb{R}$ is bounded and measurable then

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▶ Strong Markov property: Can replace n with a.s. finite stopping time N and function Y can vary with time. Suppose that for each n, $Y_n : \Omega_n \to \mathbb{R}$ is measurable and $|Y_n| \leq M$ for all n. Then

$$E_{\mu}(Y_{N}\circ\theta_{N}|\mathcal{F}_{N})=E_{X_{N}}Y_{N},$$

where RHS means $E_x Y_n$ evaluated at $x = X_n, n = N$.

Properties

▶ Property of infinite opportunities: Suppose X_n is Markov chain and

$$P(\cup_{m=n+1}^{\infty}\{X_m\in B_m\}|X_n)\geq \delta>0$$

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- ▶ **Reflection principle:** Symmetric random walks on \mathbb{R} . Have $P(\sup_{m\geq n} S_m > a) \leq 2P(S_n > a)$.
- ▶ **Proof idea:** Reflection picture.

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- ▶ How about e^A or $e^{\lambda A}$?
- Related to distribution after a Poisson random number of steps?

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- ▶ If it's 1, return to *y* infinitely often, else don't. Call *y* a recurrent state if we return to *y* infinitely often.