

Homology and Brouwer's fixed point theorem

Evin Liang, Corey Zhao, Derek Zhao

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Simplices

Definition

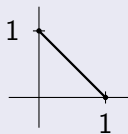
$$\Delta^n = \left\{ (x_0, \dots, x_n) \in \mathbb{R}^{n+1} \mid \sum_i x_i = 1, x_i \geq 0 \right\}$$

Example

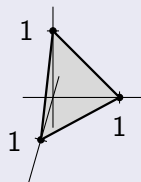
$n = 0$



$n = 1$



$n = 2$



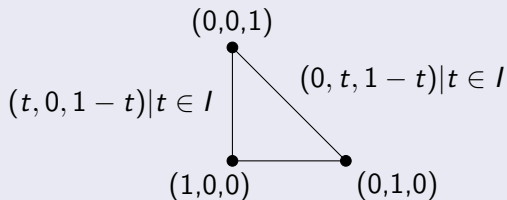
Simplicial complexes

Definition

A face of Δ^n is a subset $\{(x_0, x_1, \dots, x_n) \in \Delta^n \mid x_{i_1}, \dots, x_{i_j} = 0\}$.

Example

Triangle faces

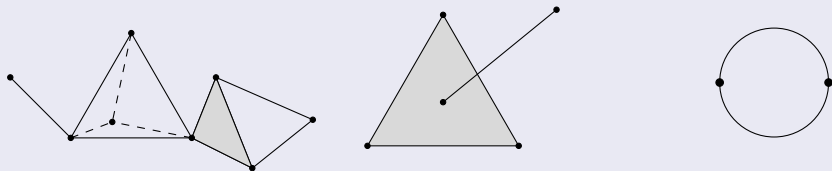


Simplicial complexes

Definition

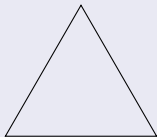
A *simplicial complex* X is obtained by gluing together simplices along same dimensional faces such that every simplex in X is uniquely determined by its vertices.

Example

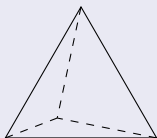


Example

$$S^1 = \partial\Delta^2$$



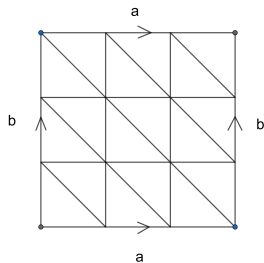
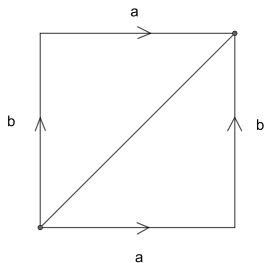
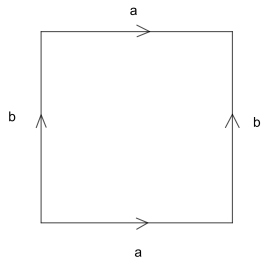
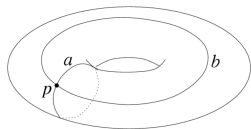
$$S^2 = \partial\Delta^3$$



$$S^n = \partial\Delta^{n+1}$$

Simplicial complexes

Simplicial complex of a torus T^2 :



Motivation

Question

Can a simplicial complex of the torus be continuously and invertibly deformed to give a simplicial complex of the sphere?

Answer

No!

Idea

Associate algebraic objects to simplicial complexes to distinguish them.

Chain complexes

Denote the simplex in X with vertices v_0, \dots, v_n by $[v_0, \dots, v_n]$.

Definition

The p th chain group of a simplicial complex X is

$$C_p(X) = \left\{ \sum_i a_i \cdot [v_{i_0}, \dots, v_{i_p}] \mid a_i \in \mathbb{Q}, [v_{i_0}, \dots, v_{i_p}] \text{ is a simplex of } X \right\}.$$

Definition

The boundary operator $\partial_p: C_p(X) \rightarrow C_{p-1}(X)$ is

$$\partial_p([v_0, \dots, v_p]) = \sum_{i=0}^p (-1)^i \cdot [v_0, \dots, \hat{v}_i, \dots, v_p].$$

Proposition

$$\partial_{p-1} \circ \partial_p = 0$$

Proof.

$$\begin{aligned}\partial(\partial([v_0, v_1, v_2])) &= \partial([v_1, v_2] - [v_0, v_2] + [v_0, v_1]) \\ &= v_2 - v_1 - v_2 + v_0 + v_1 - v_0 \\ &= 0\end{aligned}$$



Definition

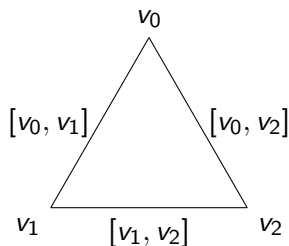
The i th homology group $H_i(K)$ is defined as

$$H_i(K) = \ker \partial_i / \text{Im } \partial_{i+1}.$$

Remark

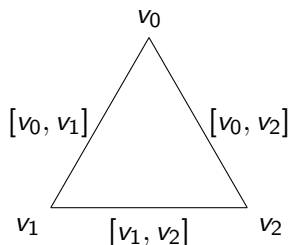
- 1 Quotient vector space:
 - V = vector space, $W \subset V$ a subspace.
 - $v, v' \in V$ are equivalent iff $v - v' \in W$.
 - V/W is the set of equivalence classes.
- 2 Since $\partial \circ \partial = 0$, $\text{Im } \partial_{i+1} \subset \ker \partial_i$.

Homology of a circle



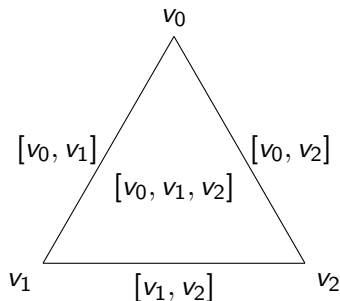
- $\ker \partial_1 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$ and $\text{Im } \partial_2 = 0$.
- $H_i(S^1) = \begin{cases} \mathbb{Q}, & i = 0, 1 \\ 0, & \text{else} \end{cases}$

Homology of a sphere



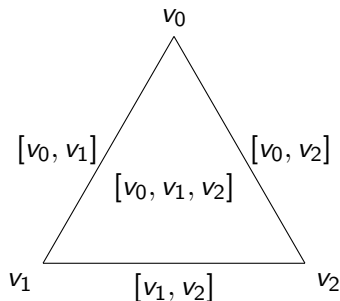
- $\ker \partial_1 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$ and $\text{Im } \partial_2 = 0$.
- $H_i(S^n) = \begin{cases} \mathbb{Q}, & i = 0, n \\ 0, & \text{else} \end{cases}$

Homology of a disc



- $\ker \partial_1 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$ and $\text{Im } \partial_2 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$.
- $H_i(\Delta^2) = \begin{cases} \mathbb{Q}, & i = 0 \\ 0, & \text{else} \end{cases}$

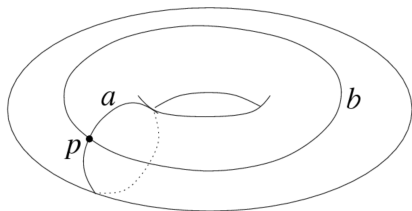
Homology of a disc



- $\ker \partial_1 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$ and $\text{Im } \partial_2 = \langle [v_1, v_2] - [v_0, v_2] + [v_0, v_1] \rangle$.
- $H_i(\Delta^n) = \begin{cases} \mathbb{Q}, & i = 0 \\ 0, & \text{else} \end{cases}$

Homology of a Torus

$$H_i(T^2) = \begin{cases} \mathbb{Q} & i = 0 \\ \mathbb{Q}^2 & i = 1 \\ \mathbb{Q} & i = 2 \end{cases}$$



Theorem

If X is a space, then $H_\bullet(X)$ does not depend on the simplicial complex.

Theorem

$f: X \rightarrow Y$ a continuous map of simplicial complexes.

- 1 *We can produce a matrix $f_*: H_i(X) \rightarrow H_i(Y)$.*
- 2 *Given $g: Y \rightarrow Z$, $g_* \circ f_* = (g \circ f)_*$.*

Definition

Two spaces X and Y are homeomorphic if there exist continuous maps $f: X \rightarrow Y$ and $g: Y \rightarrow X$ such that $f \circ g = \text{id}_Y$ and $g \circ f = \text{id}_X$.

Theorem

The sphere is not homeomorphic to the torus.

Proof.

- Suppose $S^2 \cong T^2$.
- There are continuous maps $f: S^2 \rightarrow T^2$ and $g: T^2 \rightarrow S^2$.
- These induce maps $f_*: H_1(S^2) \rightarrow H_1(T^2)$ and $g_*: H_1(T^2) \rightarrow H_1(S^2)$.
- $g_* \circ f_* = \text{id}_{S^2}$ and $f_* \circ g_* = \text{id}_{T^2}$, so f_* and g_* are invertible.
- Contradiction!



Theorem

Let $f: \Delta^n \rightarrow \Delta^n$ be a continuous mapping. Then there exists a point $x \in \Delta^n$ such that $f(x) = x$.

Notation

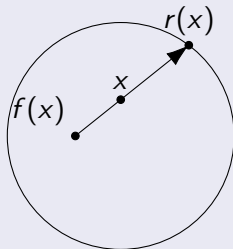
$Y \subset X$ a subspace, let $i: Y \rightarrow X$ denote the continuous inclusion.

Example

$S^{n-1} = \partial\Delta^n \subset \Delta^n$. We get an inclusion $i: S^{n-1} \rightarrow \Delta^n$.

Proof.

- Suppose that f has no fixed points.
- We get a map $r: \Delta^n \rightarrow \partial\Delta^n = S^{n-1}$:



- $r \circ i = \text{id}_{S^{n-1}}$.

Proof.

$$\begin{array}{ccccc}
 & & r_* \circ i_* = \text{id}_{*S^{n-1}} & & \\
 & & \curvearrowright & & \\
 H_{n-1}(S^{n-1}) & \xrightarrow{i_*} & H_{n-1}(\Delta^n) & \xrightarrow{r_*} & H_{n-1}(S^{n-1}) \\
 \parallel & & \parallel & & \parallel \\
 \mathbb{Q} & \longrightarrow & 0 & \longrightarrow & \mathbb{Q}
 \end{array}$$

Contradiction!



Questions?

Acknowledgements

We thank our mentor Alex Pieloch for his guidance and assistance on this project.

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